

H^1 –PERTURBATIONS OF SMOOTH SOLUTIONS FOR A WEAKLY DISSIPATIVE HYPERELASTIC-ROD WAVE EQUATION

M. BENDAHDANE, G. M. COCLITE, AND K. H. KARLSEN

ABSTRACT. We consider a weakly dissipative hyperelastic-rod wave equation (or weakly dissipative Camassa–Holm equation) describing nonlinear dispersive dissipative waves in compressible hyperelastic rods. By fixed a smooth solution, we establish the existence of a strongly continuous semigroup of global weak solutions for any initial perturbation from $H^1(\mathbb{R})$. In particular, the supersonic solitary shock waves [8] are included in the analysis.

1. INTRODUCTION AND STATEMENT OF MAIN RESULTS

Consider the equation

$$(1.1) \quad \partial_t u - \partial_{xxx}^3 u + 3u\partial_x u + \delta\partial_{xx}^2 u = \gamma(2\partial_x u\partial_{xx}^2 u + u\partial_{xxx}^3 u), \quad t > 0, \quad x \in \mathbb{R}.$$

In the case $\gamma = 1$, $\delta = 0$ it is known as the *Camassa–Holm equation* and describes unidirectional shallow water waves above a flat bottom: u represents the fluid velocity [1, 12]. The Camassa–Holm equation possesses a bi-Hamiltonian structure (and thus an infinite number of conservation laws) [11, 1] and is completely integrable [1]. From a mathematical point of view the Camassa–Holm equation is well studied, see [3] for a complete list of references. In particular, we recall that existence and uniqueness results for global weak solutions have been proved by Constantin and Escher [4], Constantin and Molinet [5], and Xin and Zhang [17, 18], see also Danchin [9, 10].

When $\delta = 0$, it is termed *hyperelastic-rod wave equation* and describes the finite length, small amplitude radial deformation waves in cylindrical compressible hyperelastic rods. The constant $\gamma > 0$ depends on the material constants and the prestress of the rod [6, 7, 8].

The additional weakly dissipative term $\delta\partial_{xx}^2 u$ is introduced in [15]. We coin (1.1) the *weakly dissipative hyperelastic-rod wave equation*.

In [3] the authors consider the case $\delta = 0$ and prove the global existence and wellposedness of solutions belonging to $L^\infty(\mathbb{R}_+; H^1(\mathbb{R}))$. On the other hand in [8] it is showed that for $\delta = 0$ and any constants $0 < \gamma < 3$, $c > 0$ there exists a $\zeta \in \mathbb{R}$

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such that the following peakon like function is a traveling wave solution of (1.1)

$$(1.2) \quad U(t, x) = \frac{c}{2} \left(1 - \frac{1}{\gamma}\right) + \frac{c}{2} \left(\frac{3}{\gamma} - 1\right) e^{-|x-ct-\zeta|/\sqrt{\gamma}},$$

called *supersonic solitary shock wave*. It is clear that the analysis in [3] does not cover this kind of solutions (that do not belong to $L^\infty(\mathbb{R}_+; H^1(\mathbb{R}))$!).

In this paper we extend the result of [3] to cover also (1.2). Roughly speaking the idea is to look at (1.2) as a $L^\infty(\mathbb{R}_+; H^1(\mathbb{R}))$ -perturbation of a constant state. Indeed we can decompose U in the following way

$$U = U_1 + U_2, \quad U_1 := \frac{c}{2} \left(1 - \frac{1}{\gamma}\right), \quad U_2(t, x) := \frac{c}{2} \left(\frac{3}{\gamma} - 1\right) e^{-|x-ct-\zeta|/\sqrt{\gamma}},$$

where U_1 is a classical solution to (1.1) and U_2 is a perturbation that lies in the space $L^\infty(\mathbb{R}_+; H^1(\mathbb{R}))$.

To be more precise: let $\varphi = \varphi(t, x)$ be a solution of (1.1) such that

$$(1.3) \quad \varphi \in C^3([0, \infty) \times \mathbb{R}), \quad \varphi, \partial_t \varphi, \partial_x \varphi, \partial_{tx}^2 \varphi, \partial_{xx}^2 \varphi, \partial_x^3 \varphi \in L^\infty(\mathbb{R}_+ \times \mathbb{R}),$$

(this is the case if φ is periodic or constant) and

$$(1.4) \quad v_0 \in H^1(\mathbb{R}), \quad \gamma > 0, \quad \delta \in \mathbb{R}.$$

We want to study the wellposedness of the Cauchy problem

$$(1.5) \quad \begin{cases} \partial_t u - \partial_{txx}^3 u + 3u \partial_x u + \delta \partial_{xx}^2 u = \gamma (2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u), & t > 0, \quad x \in \mathbb{R}, \\ u(0, x) = \varphi(0, x) + v_0(x), & x \in \mathbb{R}. \end{cases}$$

Observe that, at least formally, (1.5) is equivalent to the elliptic-hyperbolic system

$$(1.6) \quad \begin{cases} \partial_t u + \gamma u \partial_x u + \partial_x P = 0, & t > 0, \quad x \in \mathbb{R}, \\ -\partial_{xx}^2 P + P = \frac{3-\gamma}{2} u^2 + \frac{\gamma}{2} (\partial_x u)^2 + \delta \partial_x u, & t > 0, \quad x \in \mathbb{R}, \\ u(0, x) = \varphi(0, x) + v_0(x), & x \in \mathbb{R}. \end{cases}$$

Motivated by this, we shall use the following definition of weak solution. Moreover, in the same spirit of [3, Definition 1.1] we define the admissible perturbations.

Definition 1.1. We call $u : [0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$ a weak solution of the Cauchy problem (1.5) if

- (i) $u \in C([0, \infty) \times \mathbb{R})$;
- (ii) $u - \varphi \in L^\infty((0, T); H^1(\mathbb{R}))$, $T > 0$;
- (iii) u satisfies (1.6) in the sense of distributions;
- (iv) $u(0, x) = \varphi(0, x) + v_0(x)$, for every $x \in \mathbb{R}$.

If, in addition, for each $T > 0$ there exists a positive constant K_T depending only on $\|v_0\|_{H^1(\mathbb{R})}$, φ , γ , T , such that

$$(1.7) \quad \partial_x (u(t, x) - \varphi(t, x)) \leq \frac{4}{\gamma t} + K_T, \quad (t, x) \in (0, T) \times \mathbb{R},$$

then we say that $u - \varphi$ is an admissible perturbation of (1.1).

Our results are collected in the following theorem:

Theorem 1.1. *There exists a strongly continuous semigroup of solutions associated to the Cauchy problem (1.5). More precisely, there exists a map*

$$S : [0, \infty) \times (0, \infty) \times \mathbb{R} \times H^1(\mathbb{R}) \longrightarrow C([0, \infty) \times \mathbb{R}), \quad (t, \gamma, \delta, v_0) \longmapsto S_t(\gamma, \delta, v_0)(\cdot),$$

with the following properties:

- (i) *for each $v_0 \in H^1(\mathbb{R})$, $\gamma > 0$, $\delta \in \mathbb{R}$ the map $u(t, x) = S_t(\gamma, \delta, v_0)(x)$ is a weak solution of (1.5) and $u - \varphi$ is an admissible perturbation of (1.1);*
- (ii) *it is stable with respect to the initial condition and the coefficient in the following sense, if*

$$(1.8) \quad v_{0,n} \longrightarrow v_0 \text{ in } H^1(\mathbb{R}), \quad \gamma_n \longrightarrow \gamma, \quad \delta_n \longrightarrow \delta \text{ in } \mathbb{R},$$

then

$$(1.9) \quad S(\gamma_n, \delta_n, v_{0,n}) - \varphi \longrightarrow S(\gamma, \delta, v_0) - \varphi \text{ in } L^\infty([0, T]; H^1(\mathbb{R})),$$

for every $\{v_{0,n}\}_{n \in \mathbb{N}} \subset H^1(\mathbb{R})$, $\{\gamma_n\}_{n \in \mathbb{N}} \subset (0, \infty)$, $\{\delta_n\}_{n \in \mathbb{N}} \subset \mathbb{R}$, $v_0 \in H^1(\mathbb{R})$, $\gamma > 0$, $\delta \in \mathbb{R}$, $T > 0$.

Moreover, the following statements hold:

- (iii) *the estimate (1.7) is valid with*

$$(1.10) \quad K_T := \frac{2}{\sqrt{\gamma}} \left(\left(\frac{\gamma}{\sqrt{2}} \|\partial_{xx}^2 \varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})} + |\gamma - 3| \sqrt{2} \|\varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})} \right) e^{\rho T} \|v_0\|_{H^1(\mathbb{R})} \right. \\ \left. + \frac{\max\{|3 - \gamma|, 2\gamma\} + |3 - \gamma|}{4} e^{2\rho T} \|v_0\|_{H^1(\mathbb{R})}^2 \right. \\ \left. + \frac{5\gamma}{2} \|\partial_x \varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})}^2 + 2 \frac{\delta^2}{\gamma} \right)^{1/2},$$

$$(1.11) \quad \rho := \frac{3 + \gamma}{2} \|\partial_x \varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})} + \frac{\gamma}{2} \|\partial_{xxx}^3 \varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})} + |\delta|,$$

for $T > 0$;

- (iv) *there results*

$$(1.12) \quad \partial_x S(\gamma, \delta, v_0) \in L_{\text{loc}}^p(\mathbb{R}_+ \times \mathbb{R}),$$

with $1 \leq p < 3$.

Our argument is based on the analysis of the evolution of the perturbation

$$v := u - \varphi.$$

From (1.5) we get the following equation for v

$$(1.13) \quad \begin{cases} \partial_t v - \partial_{txx}^3 v + 3v\partial_x v + 3\varphi\partial_x v + 3v\partial_x \varphi + \delta\partial_{xx}^2 v \\ \quad = \gamma(2\partial_x v\partial_{xx}^2 v + v\partial_{xxx}^3 v + 2\partial_x v\partial_{xx}^2 \varphi + 2\partial_x \varphi\partial_{xx}^2 v + v\partial_{xxx}^3 \varphi + \varphi\partial_{xxx}^3 v), \\ v(0, \cdot) = v_0, \end{cases}$$

that is formally equivalent to the elliptic-hyperbolic system

$$(1.14) \quad \begin{cases} \partial_t v + \gamma v\partial_x v + \gamma v\partial_x \varphi + \gamma\varphi\partial_x v + \partial_x P = 0, \\ -\partial_{xx}^2 P + P = \frac{3 - \gamma}{2} v^2 + \frac{\gamma}{2} (\partial_x v)^2 + (3 - \gamma)\varphi v + \gamma\partial_x \varphi\partial_x v + \delta\partial_x v, \\ v(0, \cdot) = v_0. \end{cases}$$

Since the argument is very similar to the one in [3] we simply sketch it.

2. VISCOUS APPROXIMATIONS: EXISTENCE AND A PRIORI ESTIMATES

We prove existence of a weak solution to the Cauchy problem (1.13) (and equivalently to (1.5)) by proving compactness of a sequence of smooth solutions $\{v_\varepsilon\}_{\varepsilon>0}$ solving the following viscous problems (see [2]):

$$(2.1) \quad \begin{cases} \partial_t v_\varepsilon + \gamma v_\varepsilon \partial_x v_\varepsilon + \gamma v_\varepsilon \partial_x \varphi + \gamma \varphi \partial_x v_\varepsilon + \partial_x P_\varepsilon = \varepsilon \partial_{xx}^2 v_\varepsilon, \\ -\partial_{xx}^2 P_\varepsilon + P_\varepsilon = \frac{3-\gamma}{2} v_\varepsilon^2 + \frac{\gamma}{2} (\partial_x v_\varepsilon)^2 + (3-\gamma) \varphi v_\varepsilon + \gamma \partial_x \varphi \partial_x v_\varepsilon + \delta \partial_x v_\varepsilon, \\ v_\varepsilon(0, \cdot) = v_{\varepsilon,0}, \end{cases}$$

that is equivalent to the following fourth order one

$$(2.2) \quad \begin{cases} \partial_t v_\varepsilon - \partial_{txx}^3 v_\varepsilon + 3v_\varepsilon \partial_x v_\varepsilon + 3\varphi \partial_x v_\varepsilon + 3v_\varepsilon \partial_x \varphi + \delta \partial_{xx}^2 v_\varepsilon \\ = \gamma (2\partial_x v_\varepsilon \partial_{xx}^2 v_\varepsilon + v_\varepsilon \partial_{xxx}^3 v_\varepsilon + 2\partial_x v_\varepsilon \partial_{xx}^2 \varphi + 2\partial_x \varphi \partial_{xx}^2 v_\varepsilon) \\ + \gamma (\varphi \partial_{xxx}^3 v_\varepsilon + v_\varepsilon \partial_{xxx}^3 \varphi) + \varepsilon \partial_{xx}^2 v_\varepsilon - \varepsilon \partial_{xxxx}^4 v_\varepsilon, \\ v_\varepsilon(0, \cdot) = v_{\varepsilon,0}. \end{cases}$$

Formally, sending $\varepsilon \rightarrow 0$ in (2.2), (2.1) yields (1.13), (1.14), respectively.

We shall assume that

$$(2.3) \quad v_{\varepsilon,0} \in H^2(\mathbb{R}), \quad \|v_{\varepsilon,0}\|_{H^1(\mathbb{R})} \leq \|v_0\|_{H^1(\mathbb{R})}, \varepsilon > 0, \quad \text{and} \quad v_{\varepsilon,0} \longrightarrow v_0 \text{ in } H^1(\mathbb{R}).$$

The starting point of our analysis is the following wellposedness result for (2.1) (see [2, Theorem 2.3]).

Lemma 2.1. *Assume (1.3), (1.4) and (2.3), let $\varepsilon > 0$. There exists a unique smooth solution $v_\varepsilon \in C([0, \infty); H^2(\mathbb{R}))$ to the Cauchy problem (2.1).*

The next step in our analysis is to derive the following a priori estimates:

Lemma 2.2. *Assume (1.3), (1.4) and (2.3), and let $\varepsilon > 0$. Then the following estimates hold:*

j) (Energy Conservation) for each $t \geq 0$

$$(2.4) \quad \|v_\varepsilon(t, \cdot)\|_{H^1(\mathbb{R})}^2 + 2\varepsilon \int_0^t \|\partial_x v_\varepsilon(\tau, \cdot)\|_{H^1(\mathbb{R})}^2 d\tau \leq e^{2\rho t} \|v_0\|_{H^1(\mathbb{R})}^2;$$

jj) (Oleinik type Estimate) for any $0 < t < T$ and $x \in \mathbb{R}$,

$$(2.5) \quad \partial_x v_\varepsilon(t, x) \leq \frac{4}{\gamma t} + K_T,$$

where K_T is defined in (1.10);

jjj) (Higher Integrability Estimate) for every $0 \leq \alpha < 1$, $T > 0$, and $a, b \in \mathbb{R}$, $a < b$, there exists a positive constant C_T depending only on $\|v_0\|_{H^1(\mathbb{R})}$, φ , α , T , a and b , but independent on ε , such that

$$(2.6) \quad \int_0^T \int_a^b |\partial_x v_\varepsilon(t, x)|^{2+\alpha} dt dx \leq C_T.$$

Remark 2.1. *Due to [13, Theorem 8.5], (2.3) and (2.4), we have for each $t \geq 0$*

$$(2.7) \quad \|v_\varepsilon(t, \cdot)\|_{L^\infty(\mathbb{R})} \leq \frac{1}{\sqrt{2}} \|v_\varepsilon(t, \cdot)\|_{H^1(\mathbb{R})} \leq \frac{e^{\rho t}}{\sqrt{2}} \|v_0\|_{H^1(\mathbb{R})}.$$

Proof of Lemma 2.2. We begin with j). Multiplying (2.2) by v_ε , integrating on \mathbb{R} , and integrating by parts we get

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}} (v_\varepsilon^2 + (\partial_x v_\varepsilon)^2) dx + \varepsilon \int_{\mathbb{R}} ((\partial_x v_\varepsilon)^2 + (\partial_{xx}^2 v_\varepsilon)^2) dx \leq \rho \int_{\mathbb{R}} (v_\varepsilon^2 + (\partial_x v_\varepsilon)^2) dx,$$

where ρ is defined in (1.11). Hence (2.4) is consequence of (2.3) and the Gronwall Lemma.

We continue by proving jj). Introduce the notation

$$q_\varepsilon := \partial_x v_\varepsilon.$$

From (2.1) we get the following equation for q_ε

$$(2.8) \quad \begin{aligned} \partial_t q_\varepsilon + \frac{\gamma}{2} q_\varepsilon^2 + \gamma v_\varepsilon \partial_x q_\varepsilon + \gamma v_\varepsilon \partial_{xx}^2 \varphi + \gamma \partial_x \varphi q_\varepsilon - \delta q_\varepsilon \\ + \gamma \varphi \partial_x q_\varepsilon + \frac{\gamma-3}{2} v_\varepsilon^2 + (\gamma-3) \varphi v_\varepsilon + P_\varepsilon - \varepsilon \partial_{xx}^2 q_\varepsilon = 0. \end{aligned}$$

Using the fact that $e^{-|x|}/2$ is the Green's function of the operator $1 - \partial_{xx}^2$

$$(2.9) \quad \begin{aligned} P_\varepsilon(t, x) = \frac{1}{2} \int_{\mathbb{R}} e^{-|x-y|} \left(\frac{3-\gamma}{2} v_\varepsilon^2(t, y) + \frac{\gamma}{2} (\partial_x v_\varepsilon(t, y))^2 \right. \\ \left. + (3-\gamma) \varphi(t, y) v_\varepsilon(t, y) + \gamma \partial_x \varphi(t, y) \partial_x v_\varepsilon(t, y) \right) dy. \end{aligned}$$

It follows from (2.4) and (2.7) (see [3, Proof of Lemma 3.1]) that

$$(2.10) \quad \left\| \gamma v_\varepsilon \partial_{xx}^2 \varphi + \frac{\gamma-3}{2} v_\varepsilon^2 + (3-\gamma) \varphi v_\varepsilon + P_\varepsilon \right\|_{L^\infty((0,T) \times \mathbb{R})} \leq L_T,$$

for some constant $L_T > 0$. Then, from (2.8),

$$\partial_t q_\varepsilon + \frac{\gamma}{2} q_\varepsilon^2 + \gamma v_\varepsilon \partial_x q_\varepsilon + \gamma \partial_x \varphi q_\varepsilon - \delta q_\varepsilon + \gamma \varphi \partial_x q_\varepsilon - \varepsilon \partial_{xx}^2 q_\varepsilon \leq L_T.$$

Since

$$\frac{\gamma}{2} \xi^2 + (\gamma \partial_x \varphi - \delta) \xi \geq \frac{\gamma}{4} \xi^2 - \frac{(\gamma \partial_x \varphi - \delta)^2}{\gamma}, \quad \xi \in \mathbb{R},$$

we conclude

$$(2.11) \quad \begin{aligned} \partial_t q_\varepsilon + \frac{\gamma}{4} q_\varepsilon^2 + \gamma v_\varepsilon \partial_x q_\varepsilon + \gamma \varphi \partial_x q_\varepsilon - \varepsilon \partial_{xx}^2 q_\varepsilon \\ \leq L_T + 2\gamma \|\partial_x \varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})}^2 + 2 \frac{\delta^2}{\gamma} =: \tilde{L}_T. \end{aligned}$$

Employing the comparison principle for parabolic equations, we get

$$(2.12) \quad q_\varepsilon(t, x) \leq h(t), \quad 0 \leq t \leq T, \quad x \in \mathbb{R}$$

where h solves

$$(2.13) \quad \frac{dh}{dt} + \frac{\gamma}{4} h^2 = \tilde{L}_T, \quad h(0) = \|\partial_x v_{\varepsilon,0}\|_{L^\infty(\mathbb{R})}.$$

Since the map

$$H(t) := \frac{4}{\gamma t} + \sqrt{\frac{4\tilde{L}_T}{\gamma}}, \quad t > 0,$$

is a super-solution of (2.13) in the interval $[0, T]$. Due to the comparison principle for ordinary differential equations, we get $h(t) \leq H(t)$ for all $0 < t \leq T$. Therefore, (2.5) is proved.

Finally, we consider jjj). The argument is very similar to the one of [3, Lemma 4.1]. Pick a cut-off function $\chi \in C^\infty(\mathbb{R})$ such that

$$0 \leq \chi \leq 1, \quad \chi(x) = \begin{cases} 1, & \text{if } x \in [a, b], \\ 0, & \text{if } x \in (-\infty, a-1] \cup [b+1, \infty), \end{cases}$$

consider the map $\theta(\xi) := \xi(|\xi|+1)^\alpha$, $\xi \in \mathbb{R}$, then multiply (2.8) by $\chi\theta'(q_\varepsilon)$, integrate over $(0, T) \times \mathbb{R}$ and use (2.4). \square

3. COMPACTNESS

Lemma 3.1. *The family $\{P_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $L^\infty([0, T]; W^{1,\infty}(\mathbb{R}))$ and $L^\infty([0, T]; H^1(\mathbb{R}))$ for each $T > 0$.*

Proof. The argument is the same of [3, Lemma 5.1]: use the integral representation of P_ε (2.9) and then employ (2.7). \square

Lemma 3.2. *There exists a sequence $\{\varepsilon_j\}_{j \in \mathbb{N}}$ tending to zero and a function $v \in L^\infty([0, T]; H^1(\mathbb{R})) \cap H^1([0, T] \times \mathbb{R})$, for each $T \geq 0$, such that*

$$(3.1) \quad v_{\varepsilon_j} \rightharpoonup v \quad \text{weakly in } H_{\text{loc}}^1([0, T] \times \mathbb{R}), \text{ for each } T \geq 0,$$

$$(3.2) \quad v_{\varepsilon_j} \rightarrow v \quad \text{strongly in } L_{\text{loc}}^\infty([0, \infty) \times \mathbb{R}).$$

Proof. Fix $T > 0$. Observe that, from (2.1),

$$\partial_t v_\varepsilon = \varepsilon \partial_{xx}^2 v_\varepsilon - \gamma v_\varepsilon \partial_x v_\varepsilon - \gamma v_\varepsilon \partial_x \varphi - \gamma \varphi \partial_x v_\varepsilon - \partial_x P_\varepsilon,$$

hence, by (2.7), (2.4), Lemma 3.1, and the Hölder inequality, $\{v_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $H^1([0, T] \times \mathbb{R}) \cap L^\infty([0, T]; H^1(\mathbb{R}))$, and (3.1) follows. Finally, since $H^1(\mathbb{R}) \subset\subset L_{\text{loc}}^\infty(\mathbb{R}) \subset L_{\text{loc}}^2(\mathbb{R})$, (3.2) is consequence of [16, Theorem 5]. \square

Lemma 3.3. *The family $\{P_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W_{\text{loc}}^{1,1}([0, T] \times \mathbb{R})$ for any $T > 0$. In particular, there exists a sequence $\{\varepsilon_j\}_{j \in \mathbb{N}}$ tending to zero and a function $P \in L^\infty([0, T]; W^{1,\infty}(\mathbb{R}))$ such that for each $1 \leq p < \infty$*

$$(3.3) \quad P_{\varepsilon_j} \rightarrow P \quad \text{strongly in } L_{\text{loc}}^p([0, \infty) \times \mathbb{R}).$$

Proof. The argument is analogous to the one of [3, Lemma 5.3]. Using the integral representation (2.9) of P_ε and then employing (2.7) we get the uniform boundedness of $\{\partial_t P_\varepsilon\}_{\varepsilon>0}$ in $L_{\text{loc}}^1([0, \infty) \times \mathbb{R})$. Then, due to Lemma 3.1, $\{P_\varepsilon\}_{\varepsilon>0}$ is bounded in $W_{\text{loc}}^{1,1}([0, T] \times \mathbb{R})$. Finally, using again Lemma 3.1, we have the existence of a pointwise converging subsequence that is uniformly bounded in $L^\infty([0, T] \times \mathbb{R})$. Clearly, this implies (3.3). \square

Lemma 3.4. *There exist a sequence $\{\varepsilon_j\}_{j \in \mathbb{N}}$ tending to zero and two functions $q \in L_{\text{loc}}^p([0, \infty) \times \mathbb{R})$, $\overline{q^2} \in L_{\text{loc}}^r([0, \infty) \times \mathbb{R})$ such that*

$$(3.4) \quad q_{\varepsilon_j} \rightharpoonup q \quad \text{in } L_{\text{loc}}^p([0, \infty) \times \mathbb{R}), \quad q_{\varepsilon_j} \xrightarrow{*} q \quad \text{in } L_{\text{loc}}^\infty([0, \infty); L^2(\mathbb{R})),$$

$$(3.5) \quad q_{\varepsilon_j}^2 \rightharpoonup \overline{q^2} \quad \text{in } L_{\text{loc}}^r([0, \infty) \times \mathbb{R}),$$

for each $1 < p < 3$ and $1 < r < 3/2$. Moreover,

$$(3.6) \quad q^2(t, x) \leq \overline{q^2}(t, x) \quad \text{for almost every } (t, x) \in [0, \infty) \times \mathbb{R}$$

and

$$(3.7) \quad \partial_x v = q \quad \text{in the sense of distributions on } [0, \infty) \times \mathbb{R}.$$

Proof. Formulas (3.4) and (3.5) are direct consequences of Lemma 2.1 and (2.6). Inequality (3.6) is true thanks to the weak convergence in (3.5). Finally, (3.7) is a consequence of the definition of q_ε , Lemma 3.2, and (3.4). \square

In the following, for notational convenience, we replace the sequences $\{v_{\varepsilon_j}\}_{j \in \mathbb{N}}$, $\{q_{\varepsilon_j}\}_{j \in \mathbb{N}}$, $\{P_{\varepsilon_j}\}_{j \in \mathbb{N}}$ by $\{v_\varepsilon\}_{\varepsilon > 0}$, $\{q_\varepsilon\}_{\varepsilon > 0}$, $\{P_\varepsilon\}_{\varepsilon > 0}$, respectively.

In view of (3.4), we conclude that for any $\eta \in C^1(\mathbb{R})$ with η' bounded, Lipschitz continuous on \mathbb{R} and any $1 \leq p < 3$ we have

$$(3.8) \quad \eta(q_\varepsilon) \rightharpoonup \overline{\eta(q)} \quad \text{in } L^p_{\text{loc}}([0, \infty) \times \mathbb{R}), \quad \eta(q_\varepsilon) \xrightarrow{*} \overline{\eta(q)} \quad \text{in } L^\infty_{\text{loc}}([0, \infty); L^2(\mathbb{R})).$$

Multiplying the equation in (2.8) by $\eta'(q_\varepsilon)$, we get

$$(3.9) \quad \begin{aligned} & \partial_t \eta(q_\varepsilon) + \gamma \partial_x ((v_\varepsilon + \varphi) \eta(q_\varepsilon)) - \varepsilon \partial_{xx}^2 \eta(q_\varepsilon) - \varepsilon \eta''(q_\varepsilon) (\partial_x \eta(q_\varepsilon))^2 - \gamma q_\varepsilon \eta(q_\varepsilon) \\ & + \gamma v_\varepsilon \partial_{xx}^2 \varphi \eta'(q_\varepsilon) + \gamma \partial_x \varphi (q_\varepsilon \eta'(q_\varepsilon) - \eta(q_\varepsilon)) - \delta q_\varepsilon \eta'(q_\varepsilon) \\ & + \frac{\gamma - 3}{2} v_\varepsilon^2 \eta'(q_\varepsilon) + \frac{\gamma}{2} q_\varepsilon^2 \eta'(q_\varepsilon) + (\gamma - 3) \varphi v_\varepsilon \eta'(q_\varepsilon) + P_\varepsilon \eta'(q_\varepsilon) = 0. \end{aligned}$$

Lemma 3.5. *For any convex $\eta \in C^1(\mathbb{R})$ with η' bounded, Lipschitz continuous on \mathbb{R} , we have*

$$(3.10) \quad \begin{aligned} & \partial_t \overline{\eta(q)} + \gamma \partial_x ((v + \varphi) \overline{\eta(q)}) - \gamma \overline{q \eta'(q)} \\ & + \gamma v \partial_{xx}^2 \varphi \overline{\eta'(q)} + \gamma \partial_x \varphi (\overline{q \eta'(q)} - \overline{\eta(q)}) - \delta \overline{q \eta'(q)} \\ & + \frac{\gamma - 3}{2} v^2 \overline{\eta'(q)} + \frac{\gamma}{2} \overline{q^2 \eta'(q)} + (\gamma - 3) \varphi v \overline{\eta'(q)} + P \overline{\eta'(q)} \leq 0, \end{aligned}$$

in the sense of distributions on $[0, \infty) \times \mathbb{R}$. Here $\overline{q \eta'(q)}$, $\overline{q^2 \eta'(q)}$ and $\overline{\eta'(q) q}$ denote the weak limits of $q_\varepsilon \eta'(q_\varepsilon)$, $q_\varepsilon^2 \eta'(q_\varepsilon)$ and $\eta'(q_\varepsilon) q_\varepsilon$ in $L^r_{\text{loc}}([0, \infty) \times \mathbb{R})$, $1 < r < 3/2$, respectively.

Proof. In (3.9), by convexity of η , (3.2), (3.4), and (3.5), sending $\varepsilon \rightarrow 0$ yields (3.10). \square

Remark 3.1. *From (3.4) and (3.5), it is clear that*

$$q = q_+ + q_- = \overline{q_+} + \overline{q_-}, \quad q^2 = (q_+)^2 + (q_-)^2, \quad \overline{q^2} = \overline{(q_+)^2} + \overline{(q_-)^2},$$

almost everywhere in $[0, \infty) \times \mathbb{R}$, where $\xi_+ := \xi \chi_{[0, +\infty)}(\xi)$, $\xi_- := \xi \chi_{(-\infty, 0]}(\xi)$, $\xi \in \mathbb{R}$. Moreover, by (2.5) and (3.4),

$$(3.11) \quad q_\varepsilon(t, x), q(t, x) \leq \frac{4}{\gamma t} + K_T, \quad 0 < t < T, \quad x \in \mathbb{R}.$$

Lemma 3.6. *There holds*

$$(3.12) \quad \partial_t q + \gamma \partial_x ((v + \varphi) q) - \frac{\gamma}{2} \overline{q^2} + \gamma v \partial_{xx}^2 \varphi + \frac{\gamma - 3}{2} v^2 + (\gamma - 3) \varphi v + P - \delta q = 0,$$

in the sense of distributions on $[0, \infty) \times \mathbb{R}$.

Proof. Using (3.2), (3.3), (3.4), and (3.5), the result (3.12) follows by $\varepsilon \rightarrow 0$ in (2.8). \square

The next lemma contains a renormalized formulation of (3.12).

Lemma 3.7 ([3, Lemma 5.8]). *For any $\eta \in C^1(\mathbb{R})$ with $\eta' \in L^\infty(\mathbb{R})$,*

$$(3.13) \quad \begin{aligned} \partial_t \eta(q) + \gamma \partial_x((v + \varphi)\eta(q)) - \gamma q \eta(q) - \gamma \left(\frac{\overline{q^2}}{2} - q^2 \right) \eta'(q) \\ + \gamma v \partial_{xx}^2 \varphi \eta'(q) + \gamma \partial_x \varphi (q \eta'(q) - \eta(q)) - \delta q \eta(q) \\ + \frac{\gamma - 3}{2} v^2 \eta'(q) + (\gamma - 3) \varphi v \eta'(q) + P \eta'(q) = 0, \end{aligned}$$

in the sense of distributions on $[0, \infty) \times \mathbb{R}$.

Following [3, Section 6] and [17], we improve the weak convergence of q_ε in (3.4) to strong convergence (and then we have an existence result for (1.5)). The idea is to derive a “transport equation” for the evolution of the defect measure $(\overline{q^2} - q^2)(t, \cdot) \geq 0$, so that if it is zero initially then it will continue to be zero at all later times $t > 0$. The proof is complicated by the fact that we do not have a uniform bound on q_ε from below but merely (3.11) and that in (2.6) we have only $\alpha < 1$.

Lemma 3.8. *Assume (1.3) and (2.3). Then for each $t \geq 0$*

$$(3.14) \quad \begin{aligned} \int_{\mathbb{R}} \left(\overline{(q_+)^2}(t, x) - (q_+)^2(t, x) \right) dx \\ \leq 2e^{\lambda t} \int_0^t \int_{\mathbb{R}} e^{-\lambda s} S(s, x) [\overline{q_+}(s, x) - q_+(s, x)] ds dx, \end{aligned}$$

where

$$\begin{aligned} \lambda &:= \gamma \|\partial_x \varphi\|_{L^\infty(\mathbb{R}_+ \times \mathbb{R})} + 2|\delta|, \\ S(s, x) &:= -v(s, x) \partial_{xx}^2 \varphi(s, x) + \frac{3 - \gamma}{2} v^2(s, x) + (3 - \gamma) \varphi(s, x) v(s, x) - P(s, x). \end{aligned}$$

Proof. Let $T > 0$, $R > K_T$ (see (2.5)). Subtract (3.13) from (3.10) using the renormalization

$$\eta_R^+(\xi) := \begin{cases} R\xi - R^2/2, & \text{if } \xi > R, \\ \xi^2/2, & \text{if } 0 \leq \xi \leq R, \\ 0, & \text{if } \xi < 0. \end{cases}$$

Arguing as in [3, Lemma 6.4] we get

$$\frac{d}{dt} \int_{\mathbb{R}} \left(\overline{(q_+)^2} - (q_+)^2 \right) dx \leq \lambda \int_{\mathbb{R}} \left(\overline{(q_+)^2} - (q_+)^2 \right) dx + 2 \int_{\mathbb{R}} S(t, x) [\overline{q_+} - q_+] dx,$$

for $4/(\gamma(R - K_T)) < t < T$. First we have to apply the Gronwall Lemma to the previous inequality on the interval $(4/(\gamma(R - K_T)), T)$. Then sending $R \rightarrow \infty$ and using (see [3, Lemma 6.2])

$$(3.15) \quad \lim_{t \rightarrow 0^+} \int_{\mathbb{R}} \left(\overline{\eta_R^+(q)}(t, x) - \eta_R^+(q(t, x)) \right) dx = 0, \quad R > 0.$$

□

Lemma 3.9. *For any $t \geq 0$ and any $R > 0$,*

$$(3.16) \quad \begin{aligned} \int_{\mathbb{R}} \left[\overline{\eta_R^-(q)}(t, x) - \eta_R^-(q)(t, x) \right] dx \\ \leq \frac{Re^{\lambda t}}{2} \int_0^t \int_{\mathbb{R}} e^{-\lambda s} (\gamma R - 2\gamma \partial_x \varphi + 2\delta) \overline{(R + q)\chi_{(-\infty, -R)}(q)} ds dx \end{aligned}$$

$$\begin{aligned}
& - \frac{Re^{\lambda t}}{2} \int_0^t \int_{\mathbb{R}} e^{-\lambda s} (\gamma R - 2\gamma \partial_x \varphi + 2\delta) (R + q) \chi_{(-\infty, -R)}(q) ds dx \\
& + \frac{\gamma Re^{\lambda t}}{2} \int_0^t \int_{\mathbb{R}} e^{-\lambda s} \left(\overline{(q_+)^2} - (q_+)^2 \right) ds dx \\
& + \gamma Re^{\lambda t} \int_0^t \int_{\mathbb{R}} e^{-\lambda s} \left(\overline{\eta_R^-(q)} - \eta_R^-(q) \right) ds dx \\
& + e^{\lambda t} \int_0^t \int_{\mathbb{R}} e^{-\lambda s} S(s, x) \left[\overline{(\eta_R^-)'(q)} - (\eta_R^-)'(q) \right] ds dx.
\end{aligned}$$

Proof. The argument is very similar to the one of [3, Lemma 6.3]. We begin by subtracting (3.13) from (3.10), using the renormalization

$$\eta_R^-(\xi) := \begin{cases} 0, & \text{if } \xi > 0, \\ \xi^2/2, & \text{if } -R \leq \xi \leq 0, \\ -R\xi - R^2/2, & \text{if } \xi < -R. \end{cases}$$

Then we integrate on \mathbb{R} and use the Gronwall Lemma and (see [3, Lemma 6.2])

$$(3.17) \quad \lim_{t \rightarrow 0+} \int_{\mathbb{R}} \left(\overline{\eta_R^-(q)}(t, x) - \eta_R^-(q(t, x)) \right) dx = 0, \quad R > 0.$$

□

Lemma 3.10. *There holds $\overline{q^2} = q^2$ almost everywhere in $[0, \infty) \times \mathbb{R}$.*

Proof. We follow the argument of [3, Lemma 6.6]. We add (3.14) and (3.16). Using the concavity of $\xi \mapsto (R + \xi) \chi_{(-\infty, -R)}(\xi)$, the Gronwall Lemma, (3.15), (3.17) and

$$\lim_{t \rightarrow 0+} \int_{\mathbb{R}} q^2(t, x) dx = \lim_{t \rightarrow 0+} \int_{\mathbb{R}} \overline{q^2}(t, x) dx = \int_{\mathbb{R}} (\partial_x v_0)^2 dx,$$

we conclude that

$$\int_{\mathbb{R}} \left(\frac{1}{2} \left[\overline{(q_+)^2} - (q_+)^2 \right] + \left[\overline{\eta_R^-(q)} - \eta_R^-(q) \right] \right) (t, x) dx = 0, \quad \text{for each } 0 < t < T.$$

By the Fatou Lemma, Remark 3.1, and (3.6), sending $R \rightarrow \infty$ yields

$$0 \leq \int_{\mathbb{R}} \left(\overline{q^2} - q^2 \right) (t, x) dx \leq 0, \quad 0 < t < T,$$

and, since the argument holds for each $T > 0$, we are done. □

4. PROOF OF THEOREM 1.1

In this last section we prove Theorem 1.1. The first step consists in the proof of the existence of solutions for (1.5).

Lemma 4.1. *Assume (1.3) and (2.3). Then there exists an admissible weak solution of (1.5), satisfying (iii) and (iv) of Theorem 1.1.*

Proof. The conditions (i), (ii), (iv) of Definition 1.1 are satisfied, due to (2.3), (2.4) and Lemma 3.2. We have to verify (ii). Due to Lemma 3.10, we have

$$(4.1) \quad q_\varepsilon \rightarrow q \quad \text{strongly in } L_{\text{loc}}^2([0, \infty) \times \mathbb{R}).$$

Clearly (3.2), (3.3), and (4.1) imply that v is a distributional solution of (1.14). Therefore $u := v + \varphi$ is a weak solution of (1.5) and v is an admissible perturbation

of (1.1). Finally, (iii) and (iv) of Theorem 1.1 are consequences of (2.5) and (2.6), respectively. \square

The second step is the existence of the semigroup.

Lemma 4.2. *There exists a strongly continuous semigroup of solutions associated with the Cauchy problem (1.5)*

$$S : [0, \infty) \times (0, \infty) \times \mathbb{R} \times H^1(\mathbb{R}) \longrightarrow C([0, \infty) \times \mathbb{R}),$$

namely, for each $v_0 \in H^1(\mathbb{R})$, $\gamma > 0$, $\delta \in \mathbb{R}$ the map $u(t, x) = S_t(\gamma, \delta, v_0)(x)$ is an admissible weak solution and $u - \varphi$ and admissible perturbation of (1.5). Moreover, (iii) and (iv) of Theorem 1.1 are satisfied.

Clearly, this lemma is a direct consequence of the following one and of the ones in the previous sections.

Lemma 4.3. *Let $\{\varepsilon_n\}_{n \in \mathbb{N}}$, $\{\mu_n\}_{n \in \mathbb{N}} \subset (0, \infty)$ and $v, w \in L^\infty([0, T]; H^1(\mathbb{R})) \cap H^1([0, T] \times \mathbb{R})$, for each $T \geq 0$, be such that $\varepsilon_n, \mu_n \rightarrow 0$ and*

$$v_{\varepsilon_n} \rightarrow v, \quad v_{\mu_n} \rightarrow v, \quad \text{strongly in } L^\infty([0, T]; H^1(\mathbb{R})), \quad T > 0,$$

then

$$v = w.$$

Proof. Let $t > 0$. From [2, Theorem 3.1], we have that

$$\|v_\varepsilon(t, \cdot) - v_\mu(t, \cdot)\|_{H^1(\mathbb{R})} \leq A(t, \varepsilon + \mu)\|v_{0, \varepsilon} - v_{0, \mu}\|_{H^1(\mathbb{R})} + B(t, \varepsilon + \mu)|\varepsilon - \mu|,$$

with

$$A(t, \varepsilon + \mu) = \mathcal{O}(e^{t/(\varepsilon + \mu)}), \quad B(t, \varepsilon + \mu) = \mathcal{O}(e^{t/(\varepsilon + \mu)}),$$

for each $\varepsilon, \mu > 0$. Hence

$$\|v_{\varepsilon_n}(t, \cdot) - v_{\mu_n}(t, \cdot)\|_{H^1(\mathbb{R})} \leq c_1 e^{t/(\varepsilon + \mu)}(|\varepsilon_n - \mu_n| + \|v_{0, \varepsilon_n} - v_{0, \mu_n}\|_{H^1(\mathbb{R})}), \quad n \in \mathbb{N},$$

for some constant $c_1 > 0$. Choosing suitable subsequences as in [3, Lemma 7.2] we get $v = w$. \square

The third and last step is the stability of the semigroup.

Lemma 4.4. *The semigroup S defined on $[0, \infty) \times (0, \infty) \times \mathbb{R} \times H^1(\mathbb{R})$ satisfies the stability property (ii) of Theorem 1.1.*

Proof. Fix $\varepsilon > 0$ and denote by S^ε the semigroup associated to the viscous problem (2.1) and $\tilde{S} := S - \varphi$. Choose $\{v_{0, n}\}_{n \in \mathbb{N}} \subset H^1(\mathbb{R})$, $\{\gamma_n\}_{n \in \mathbb{N}} \subset (0, \infty)$, $\{\delta_n\}_{n \in \mathbb{N}} \subset \mathbb{R}$, $v_0 \in H^1(\mathbb{R})$, $\gamma > 0$, $\delta \in \mathbb{R}$ satisfying (1.8). The initial data satisfy $v_{0, \varepsilon, n}, v_{0, \varepsilon} \in H^2(\mathbb{R})$ and (2.3). Finally, write

$$v_{\varepsilon, n} := S^\varepsilon(\gamma_n, \delta_n, v_{0, n}), \quad v_n := S(\gamma_n, \delta_n, v_{0, n}), \quad v := S(\gamma, \delta, v_0).$$

Let $t > 0$. Due to Lemmas 3.2 and 4.1,

$$\|v_n(t, \cdot) - v(t, \cdot)\|_{H^1(\mathbb{R})} = \lim_{\varepsilon \rightarrow 0} \|v_{\varepsilon, n}(t, \cdot) - v_\varepsilon(t, \cdot)\|_{H^1(\mathbb{R})}.$$

Using [2, Theorem 3.1], we have that

$$\|v_{\varepsilon, n}(t, \cdot) - v_\varepsilon(t, \cdot)\|_{H^1(\mathbb{R})} \leq A(t, \varepsilon)\|v_{0, n} - v_0\|_{H^1(\mathbb{R})} + B(t, \varepsilon)(|\gamma_n - \gamma| + |\delta_n - \delta|),$$

with

$$A(t, \varepsilon) = \mathcal{O}(e^{T/\varepsilon}), \quad B(t, \varepsilon) = \mathcal{O}(e^{T/\varepsilon}), \quad t \in [0, T].$$

Now, using the same argument as in [3, Lemma 8.1] we prove the claim. \square

Proof of Theorem 1.1. It is direct consequence of Lemmas 4.2 and 4.4. \square

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(Mostafa Bendahmane, Giuseppe Maria Coclite, and Kenneth Hvistendahl Karlsen)

CENTRE OF MATHEMATICS FOR APPLICATIONS (CMA)

UNIVERSITY OF OSLO

P.O. BOX 1053, BLINDERN

N-0316 OSLO, NORWAY

E-mail address: mostafab@math.uio.no, giusepc@math.uio.no, kennethk@math.uio.no

URL: <http://folk.uio.no/mostafab/>, <http://www.math.uio.no/~kennethk/>