

Kap. 6 Supp. ex.

2) $A = I_n - \frac{2}{\|x\|^2} x x^T$

Vis at A er
ortogonal og Symmetrisk

Symmetrisk:

$$A^T = I_n^T - \frac{2}{\|x\|^2} (x x^T)^T$$

$$= I_n - \frac{2}{\|x\|^2} (x^T x^T) = I_n - \frac{2}{\|x\|^2} x x^T = A$$

$A^T = A$

Ortogonal:

Må vise at $A^T A = I_n$

$$A^T A = A^2 = \left(I_n - \frac{2}{\|x\|^2} x x^T \right)^2 =$$

$$\left(I_n^2 - \frac{4}{\|x\|^2} x x^T + \frac{4}{\|x\|^4} (x x^T)^2 \right) = I_n - \frac{4}{\|x\|^2} x x^T + \frac{4}{\|x\|^4} \underbrace{(x x^T)(x x^T)}$$

$$= I_n - \frac{4}{\|x\|^2} x x^T + \frac{4}{\|x\|^4} \|x\|^2 \cdot x x^T$$

$$x^T x = \|x\|^2$$

I_n

$A^T A = I_n$

3 | Ser på ligningssystemet $Ax = 0$

$$A = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix}$$

$$Ax \text{ er da: } \begin{bmatrix} \langle r_1^T, x \rangle \\ \langle r_2^T, x \rangle \\ \vdots \\ \langle r_n^T, x \rangle \end{bmatrix}$$

der $\langle \cdot, \cdot \rangle$ er det Euklidiske indreproduktet.

$$\begin{bmatrix} \langle r_1^T, x \rangle \\ \langle r_2^T, x \rangle \\ \vdots \\ \langle r_n^T, x \rangle \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\iff \begin{cases} r_1^T \text{ er ortogonal p\u00e5 } x \\ r_2^T \text{ er ortogonal p\u00e5 } x \\ \vdots \\ r_n^T \text{ er ortogonal p\u00e5 } x. \end{cases}$$

S\u00e5 $[Ax = 0] \iff x$ er ortogonal p\u00e5 radvektorerne i A .

Kap. 8 Supp. ex.

$$\begin{array}{ccc} 15 | & L: M_{2 \times 2} & \longrightarrow M_{2 \times 2} \\ & A & \longmapsto A^T \end{array}$$

Find $[L]_B$, der B er standardbasisen p\u00e5 $M_{2 \times 2}$

$$[L]_B = \left[[L(b_1)]_B \mid [L(b_2)]_B \mid [L(b_3)]_B \mid [L(b_4)]_B \right]$$

der

$$b_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, b_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, b_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, b_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$[L]_B = \left[[b_1]_B \mid [b_3]_B \mid [b_2]_B \mid [b_4]_B \right] = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$17 \quad T: V \rightarrow V$$

$$[T(x)]_B = \begin{bmatrix} x_1 - x_2 + x_3 \\ x_2 \\ x_1 - x_3 \end{bmatrix} \text{ hvis } [x]_B = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Find $[T]_B$

Vi vet at $[T]_B = \left[[T(b_1)]_B \mid [T(b_2)]_B \mid [T(b_3)]_B \right]$

der $B = \{ b_1, b_2, b_3 \}$.

Vi vet også at $[b_1]_B = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $[b_2]_B = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ og

$$[b_3]_B = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Så $[T(b_1)]_B = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$, $[T(b_2)]_B = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ og

$$[T(b_3)]_B = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$\Rightarrow [T]_B = \underline{\underline{\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix}}}$

Kap. 9.1

3) a) Løs systemet

$$y_1' = 4y_1 + y_3$$

$$y_2' = -2y_1 + y_2$$

$$y_3' = -2y_1 + y_3$$

Skrives på matrixform:

$$y' = Ay, \text{ hvor}$$

$$A = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$$

Diagonalisering:

$$\begin{aligned} \det(A - \lambda I) &= (4 - \lambda)(1 - \lambda)^2 + 1 \cdot 2 \cdot (1 - \lambda) \\ &= (1 - \lambda)(2 + (4 - \lambda)(1 - \lambda)) = (1 - \lambda)(\lambda^2 - 5\lambda + 6) \end{aligned}$$

$$\lambda_1 = 1, \lambda_2 = \frac{5 + \sqrt{25 - 24}}{2} = 3, \lambda_3 = \frac{5 - \sqrt{25 - 24}}{2} = 2.$$

tilhørende egenvektor

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Egenvektor for λ_2 :

$$\begin{bmatrix} 1 & 0 & 1 \\ -2 & -2 & 0 \\ -2 & 0 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = 0$$

$$\left. \begin{aligned} v_1 &= -v_3 \\ v_1 &= -v_2 \end{aligned} \right\}$$

$$\Rightarrow \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix}$$

Eigenvektoren für $\lambda_3 = 0$:

$$\begin{bmatrix} 2 & 0 & 1 \\ -2 & -1 & 0 \\ -2 & 0 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = 0 \quad \left. \begin{array}{l} v_1 = -2v_3 \\ v_2 = -2v_3 \end{array} \right\} \Rightarrow \begin{bmatrix} 1 \\ -2 \\ -2 \end{bmatrix}$$

$$P = \begin{bmatrix} 0 & 1 & 1 \\ 1 & -2 & -1 \\ 0 & -2 & -1 \end{bmatrix} \quad P^{-1}AP = D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

Annahme $Pu = y$ \Rightarrow für

$$Pu' = APu \quad \text{oder} \quad u' = P^{-1}APu$$

$$\begin{bmatrix} u_1' \\ u_2' \\ u_3' \end{bmatrix} = \begin{bmatrix} u_1 \\ 2u_2 \\ 3u_3 \end{bmatrix}$$

$$u_1 = c_1 e^x$$

$$u_2 = c_2 e^{2x}$$

$$u_3 = c_3 e^{3x}$$

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = P \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} u_2 + u_3 \\ u_1 - 2u_2 - u_3 \\ -2u_2 - u_3 \end{bmatrix} = \begin{bmatrix} c_2 e^{2x} + c_3 e^{3x} \\ c_1 e^x - 2c_2 e^{2x} - c_3 e^{3x} \\ -2c_2 e^{2x} - c_3 e^{3x} \end{bmatrix}$$

$$b) \quad \left. \begin{array}{l} y_1(0) = c_2 + c_3 = -1 \\ y_2(0) = c_1 - 2c_2 - c_3 = 1 \\ y_3(0) = -2c_2 - c_3 = 0 \end{array} \right\} \begin{array}{l} -c_3 = -2 \\ c_1 = 1 \\ -c_2 = +1, c_2 = 1 \end{array}$$

Solution:

$$\begin{bmatrix} e^{2x} - 2e^{3x} \\ e^x - 2e^{2x} + 2e^{3x} \\ -2e^{2x} + 2e^{3x} \end{bmatrix}$$

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$$y'' - y' - 6y = 0$$

$$y_1 = y, \quad y_2 = y'$$

$$y_1' = y_2$$

$$y_2' = y'' = y' + 6y = y_2 + 6y_1$$

$$\begin{bmatrix} y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 6 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \quad A = \begin{bmatrix} 0 & 1 \\ 6 & 1 \end{bmatrix}$$

Diagonalisier:

Eigenwertes:

$$\lambda(\lambda - 1) - 6 = 0$$

$$\lambda^2 - \lambda - 6 = 0$$

$$\lambda_1 = 3, \quad \lambda_2 = -2$$

Eigenvektoren: λ_1

$$\begin{bmatrix} -3 & 1 \\ 6 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0 \quad \left\} \rightarrow \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

λ_2

$$\begin{bmatrix} 2 & 1 \\ 6 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0 \quad \left\} \rightarrow \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 1 \\ 3 & -2 \end{bmatrix}$$

$$P^{-1}AP = D = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix}$$

Lösung som i förrige uppgift:

$$u_1 = c_1 e^{3x}$$

$$u_2 = c_2 e^{-2x}$$

$$y_1 = c_1 e^{3x} + c_2 e^{-2x}$$

$$y_2 = 3c_1 e^{3x} - 2c_2 e^{-2x}$$

$$y = y_1 =$$

$$c_1 e^{3x} + c_2 e^{-2x}$$