

## Start

*restart;*  
*with(plots);*

[*animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d, conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot, display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot, implicitplot3d, inequal, interactive, interactiveparams, intersectplot, listcontplot, listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple, odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d, polyhedra\_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions, setoptions3d, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot*]

*with(Student[VectorCalculus]);*

[*&x, `\*`, `+`, `-`, `.` , <, >, <|>, About, ArcLength, BasisFormat, Binormal, ConvertVector, CrossProduct, Curl, Curvature, D, Del, DirectionalDiff, Divergence, DotProduct, FlowLine, Flux, GetCoordinates, GetPVDDescription, GetRootPoint, GetSpace, Gradient, Hessian, IsPositionVector, IsRootedVector, IsVectorField, Jacobian, Laplacian, LineInt, MapToBasis, Nabla, Norm, Normalize, PathInt, PlotPositionVector, PlotVector, PositionVector, PrincipalNormal, RadiusOfCurvature, RootedVector, ScalarPotential, SetCoordinates, SpaceCurve, SpaceCurveTutor, SurfaceInt, TNBFrame, Tangent, TangentLine, TangentPlane, TangentVector, Torsion, Vector, VectorField, VectorFieldTutor, VectorPotential, VectorSpace, diff, evalVF, int, limit, series*]

*with(Student[MultivariateCalculus]);*

[*ApproximateInt, ApproximateIntTutor, CenterOfMass, ChangeOfVariables, CrossSection, CrossSectionTutor, Del, DirectionalDerivative, DirectionalDerivativeTutor, FunctionAverage, Gradient, GradientTutor, Jacobian, LagrangeMultipliers, MultiInt, Nabla, Revert, SecondDerivativeTest, SurfaceArea, TaylorApproximation, TaylorApproximationTutor*]

*with(Student[LinearAlgebra]);*

[*&x, `.` , AddRow, AddRows, Adjoint, ApplyLinearTransformPlot, BackwardSubstitute, BandMatrix, Basis, BilinearForm, CharacteristicMatrix, CharacteristicPolynomial, ColumnDimension, ColumnSpace, CompanionMatrix, ConstantMatrix, ConstantVector, CrossProductPlot, Determinant, Diagonal, DiagonalMatrix, Dimension, Dimensions, EigenPlot, EigenPlotTutor, Eigenvalues, EigenvaluesTutor, Eigenvectors, EigenvectorsTutor, Equal, GaussJordanEliminationTutor, GaussianElimination, GaussianEliminationTutor, GenerateEquations, GenerateMatrix, GramSchmidt, HermitianTranspose, Id, IdentityMatrix, IntersectionBasis, InverseTutor, IsDefinite, IsOrthogonal, IsSimilar, IsUnitary, JordanBlockMatrix, JordanForm, LUdecomposition, LeastSquares, LeastSquaresPlot, LinearSolve, LinearSolveTutor, LinearSystemPlot, LinearSystemPlotTutor, LinearTransformPlot, LinearTransformPlotTutor, MatrixBuilder, MinimalPolynomial, Minor, MultiplyRow, Norm, Normalize, NullSpace, Pivot, PlanePlot, ProjectionPlot, QRdecomposition, RandomMatrix, RandomVector,*

*Rank, ReducedRowEchelonForm, ReflectionMatrix, RotationMatrix, RowDimension, RowSpace, SetDefault, SetDefaults, SumBasis, SwapRow, SwapRows, Trace, Transpose, UnitVector, VectorAngle, VectorSumPlot, ZeroMatrix, ZeroVector]*

*with(Student[Calculus1]);*

*[AntiderivativePlot, AntiderivativeTutor, ApproximateInt, ApproximateIntTutor, ArcLength, ArcLengthTutor, Asymptotes, Clear, CriticalPoints, CurveAnalysisTutor, DerivativePlot, DerivativeTutor, DiffTutor, ExtremePoints, FunctionAverage, FunctionAverageTutor, FunctionChart, FunctionPlot, GetMessage, GetNumProblems, GetProblem, Hint, InflectionPoints, IntTutor, Integrand, InversePlot, InverseTutor, LimitTutor, MeanValueTheorem, MeanValueTheoremTutor, NewtonQuotient, NewtonsMethod, NewtonsMethodTutor, PointInterpolation, RiemannSum, RollesTheorem, Roots, Rule, Show, ShowIncomplete, ShowSolution, ShowSteps, Summand, SurfaceOfRevolution, SurfaceOfRevolutionTutor, Tangent, TangentSecantTutor, TangentTutor, TaylorApproximation, TaylorApproximationTutor, Understand, Undo, VolumeOfRevolution, VolumeOfRevolutionTutor, WhatProblem]* (1.5)

## ▼ Eksamensoppgave 2006 vår / 5

▼ a) Gitt  $F$  og  $\text{Curl}F$ , finn  $f(y,z)$  når  $f(0,0) = 1$

$$F := (x, y, z) \rightarrow \langle f(y, z), 2 \cdot y \cdot z, g(y, z) \rangle;$$

$$(x, y, z) \rightarrow \text{Student:-VectorCalculus:-} \langle, \rangle (f(y, z), 2 y z, g(y, z)) \quad (2.1.1)$$

**Curl F**

$$\text{Curl}(F) = \langle h(y, z), 2 y z, -z^2 \rangle;$$

$$\left( (x, y, z) \rightarrow \text{VectorCalculus:-Vector} \left( \left[ \frac{\partial}{\partial y} g(y, z) - 2 y, \frac{\partial}{\partial z} f(y, z), - \left( \frac{\partial}{\partial y} f(y, z) \right) \right] \right), \right. \quad (2.1.2)$$

$$\left. \text{attributes} = [\text{vectorfield}, \text{coords} = \text{cartesian}_{x, y, z}] \right) = (h(y, z)) e_x + 2 y z e_y - z^2 e_z$$

$$f(y,z) = \dots + C(y)$$

$$\text{int}(2 \cdot y \cdot z, z);$$

$$y z^2 \quad (2.1.3)$$

$$f(y,z) = \dots + C(z)$$

$$\text{int}(z^2, y);$$

$$y z^2 \quad (2.1.4)$$

$$f(y,z) = y z^2 + 1$$

▼ b) Gitt  $S$ , regn ut  $\text{Curl}$  integralet

$S$  er en del av en paraboloid

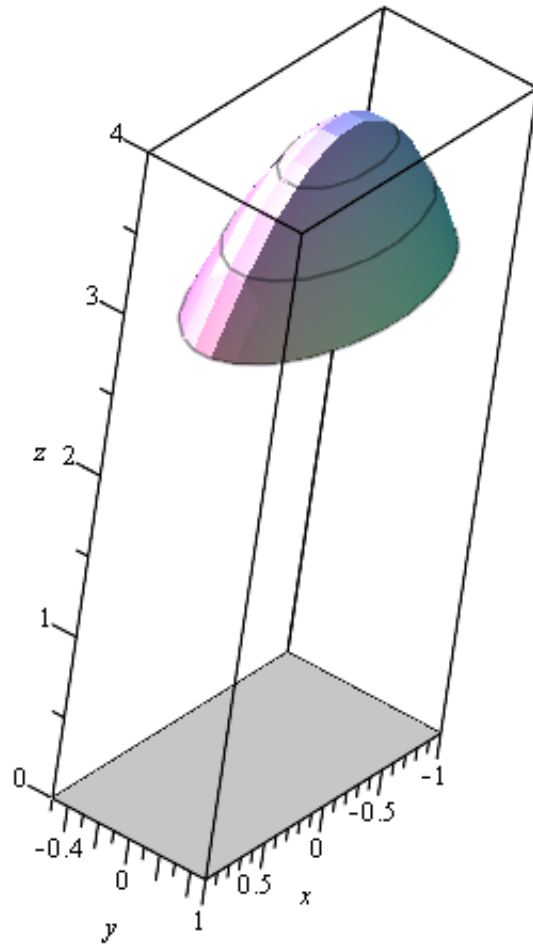
```
S := implicitplot3d(z = 4 - x^2 - 4*y^2, x = -1 .. 1, y = -1/2 .. 1/2, z = 3 .. 4, style = surfacecontour,  
  axes = boxed, scaling = constrained);
```

```
XYplanet := plot3d([x, y, 0], x = -1 .. 1, y = -1/2 .. 1/2, color = gray, style = surface);
```

```
display(S, XYplanet);
```

*PLOT3D(...)*

*PLOT3D(...)*



Stokes teorem -> det er nok å finne sirkulasjonen på randkurven

Randkurven er en ellipse

$$r := t \rightarrow \left\langle \cos(t), \frac{1}{2} \cdot \sin(t), 3 \right\rangle;$$

$$t \rightarrow \text{Student:-VectorCalculus:-} \langle, \rangle \left( \cos(t), 1 \frac{1}{2} \sin(t), 3 \right)$$

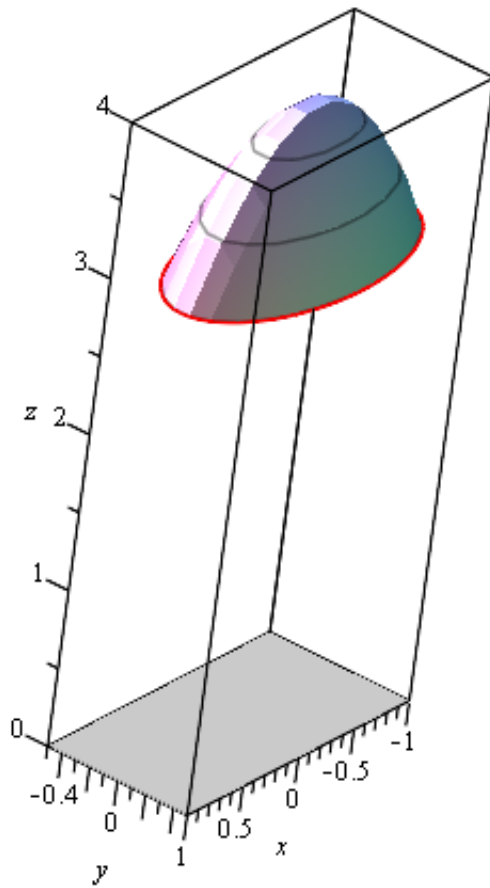
**(2.2.1)**

**Se på bildet**

$C := \text{SpaceCurve}(r(t), t=0 ..2 \cdot \text{Pi}, \text{color} = \text{red});$

$\text{display}(S, \text{XYplanet}, C);$

*PLOT3D(...)*



Graph of the curve represented parametrically by the components of the given vector.

**Tangentvektoren**

$$T := t \rightarrow \text{TangentVector}(r(t));$$

$$t \rightarrow \text{Student:-VectorCalculus:-TangentVector}(r(t))$$

(2.2.2)

$T(t);$

$$\begin{bmatrix} -\sin(t) \\ \frac{1}{2} \cos(t) \\ 0 \end{bmatrix} \quad (2.2.3)$$

$convert(r(t), list);$

$$\left[ \cos(t), \frac{1}{2} \sin(t), 3 \right] \quad (2.2.4)$$

**F langs kurven**

$$F\left(\cos(t), \frac{1}{2} \sin(t), 3\right);$$
$$\left(f\left(\frac{1}{2} \sin(t), 3\right)\right)e_x + 3 \sin(t)e_y + \left(g\left(\frac{1}{2} \sin(t), 3\right)\right)e_z \quad (2.2.5)$$

**F \* T**

$$DotProduct\left(F\left(\cos(t), \frac{1}{2} \sin(t), 3\right), T(t)\right);$$
$$-f\left(\frac{1}{2} \sin(t), 3\right) \sin(t) + \frac{3}{2} \sin(t) \cos(t) \quad (2.2.6)$$

**f(y,z) fra del a)**

$$f := (y, z) \rightarrow y \cdot z^2 + 1;$$
$$(y, z) \rightarrow y z^2 + 1 \quad (2.2.7)$$

**Integralet**

$$int\left(DotProduct\left(F\left(\cos(t), \frac{1}{2} \sin(t), 3\right), T(t)\right), t=0 .. 2 \cdot \text{Pi}\right);$$
$$-\frac{9}{2} \pi \quad (2.2.8)$$

## Eksempel 2

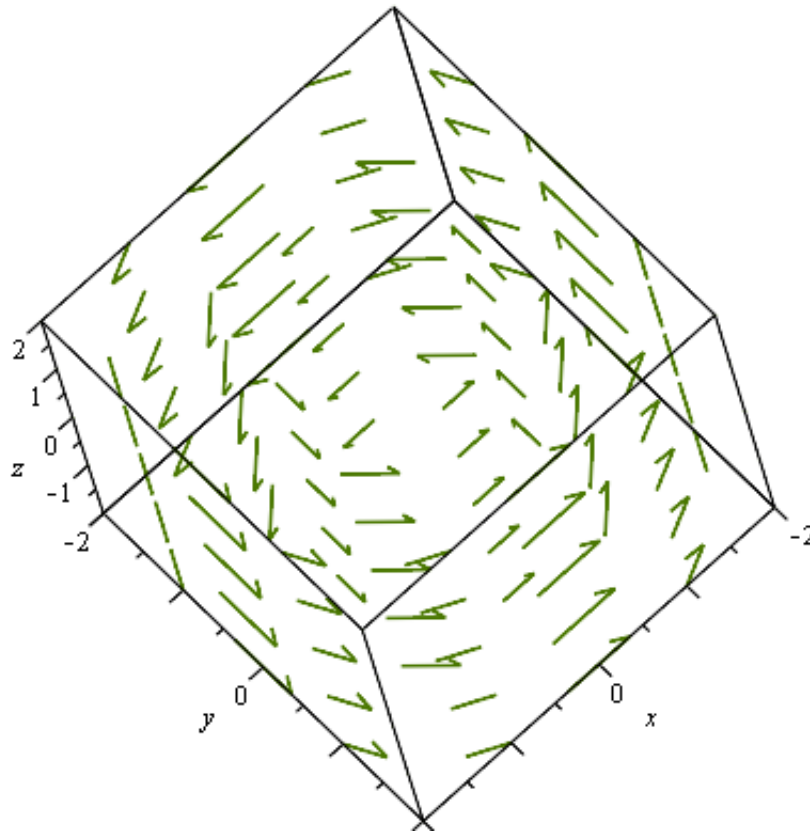
**Rotasjon med vinkel  $\text{Pi} / 2$  og vinkelhastighet  $a$  om z-aksen ( $a = 1 \rightarrow$  vinkelhastighet 1)**

$F := (x, y, z) \rightarrow \langle -a \cdot y, a \cdot x, 0 \rangle;$

$$(x, y, z) \rightarrow \text{Student:-VectorCalculus:-}\langle, \rangle(\text{Student:-VectorCalculus:-}\backslash \cdot \backslash(a y), a x, 0) \quad (3.1)$$

**Rotasjonsfeltet ( $a = 1$ )**

$VectorField(subs(a = 1, F(x, y, z)), output = plot, axes = boxed);$



### Curl

$Curl(F)$ ;

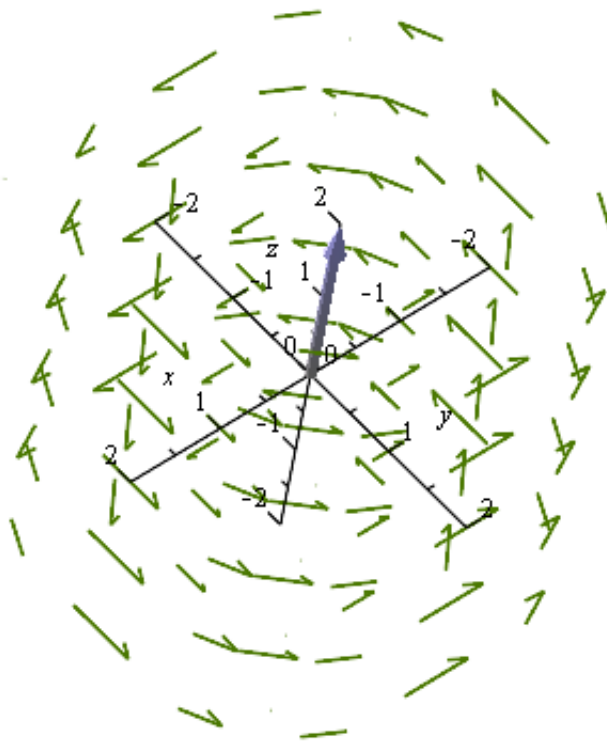
$(x, y, z) \rightarrow \text{VectorCalculus:-Vector}([0, 0, 2a], \text{attributes} = [\text{vectorfield}, \text{coords} = \text{cartesian}_{x, y, z}])$

(3.2)

**Curlvektoren er parallel med rotasjonsakse**

$\text{display}(\text{VectorField}(\text{subs}(a = 1, F(x, y, z)), \text{output} = \text{plot}, \text{axes} = \text{normal}), \text{arrow}(\text{subs}(a = 1, \text{Curl}(F)(x, y, z))))$ ;





**Størrelsen til Curlvektoren er 2 \* vinkelhastighet**  
 $Norm(Curl(F)(x, y, z));$

$$2\sqrt{a^2}$$

**(3.3)**