



1 If H is a subset of \mathbb{R}^3 , then the three conditions of the definition on page 193 must hold. The first condition is: "The zero vector of \mathbb{R}^3 is in H ." In this case, *any* vector of H has -2 as its second coordinate, and hence the zero vector is not in H . We conclude that H is not a subspace of \mathbb{R}^3 .

2 We have the matrix A , and the task is to find a basis for the null space of A . This is achieved by solving the system $Ax = \mathbf{0}$.

$$[A \ \mathbf{0}] = \begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 1 & 2 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -4 & 3 & 0 \\ 0 & 1 & 2 & 0 & 0 \end{bmatrix}$$

We get $x_1 = 4x_3 - 3x_4$ and $x_2 = -2x_3$, and x_3 and x_4 are free. A general solution is

$$x = \begin{bmatrix} 4x_3 - 3x_4 \\ -2x_3 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} 4 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -3 \\ 0 \\ 0 \\ 1 \end{bmatrix} = x_3 \mathbf{u} + x_4 \mathbf{v}$$

The basis for the null space of A is $\{\mathbf{u}, \mathbf{v}\}$.

3 This time we want to find a basis for the column space of a matrix A . By Theorem 6, page 212, the pivot columns of A form a basis for $\text{Col}(A)$. To find the pivots, we reduce A to echelon form:

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 3 & 2 & 4 \\ 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

The pivot columns are the first and the second, so $\left\{ \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\}$ is a basis for the column space of A .

4 We are supposed to find a basis for $\text{Span}\{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3\}$, where $\mathbf{p}_1 = 2$, $\mathbf{p}_2 = t^2 - 1$ and $\mathbf{p}_3 = 2t^2$. It is obvious that $\mathbf{p}_2 = \frac{1}{2}(\mathbf{p}_3 - \mathbf{p}_1)$, so by Theorem 5 page 210, $\text{Span}\{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3\} = \text{Span}\{\mathbf{p}_1, \mathbf{p}_3\}$. It is also clear that \mathbf{p}_1 and \mathbf{p}_3 are linearly independent. Hence, the set $\{\mathbf{p}_1, \mathbf{p}_3\}$ is a basis for $\text{Span}\{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3\}$.