

TMA 4115 Matematikk 3

Lecture 11 for MTFYMA

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In todays lecture we discuss...

- linear equations and their relations to vector and matrix equations
- again solution sets of linear equations

Vectors

Vectors \approx ordered list of numbers.

\mathbb{R}^n (or \mathbb{C}^n) set of vectors of length n

(i.e. vectors with n entries from \mathbb{R} (or \mathbb{C})).

Have operations $+$, $-$ for vectors and $r \cdot \vec{v}$ for $r \in \mathbb{R}$ (or \mathbb{C}).

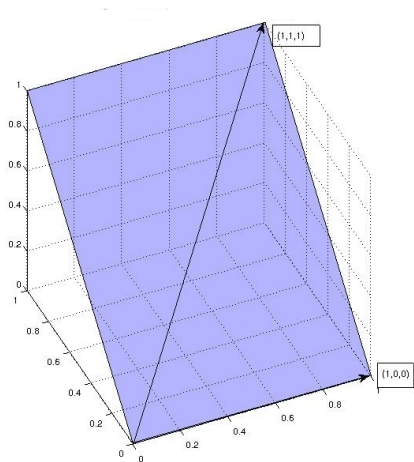
linear combination of vectors

$\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$ is a weighted sum

$$\sum_{l=1}^k r_l \vec{v}_l = r_1 \vec{v}_1 + \dots + r_k \vec{v}_k$$

$\text{span} \{ \vec{v}_1, \dots, \vec{v}_k \} =$ **set of all linear combinations** of $\vec{v}_1, \dots, \vec{v}_k$

Examples of spans (in \mathbb{R}^2) where a point (origin!), lines through the origin and the whole plane.

A picture of $\text{span} \{ (1, 1, 1), (1, 0, 0) \}$ 

The vectors are not multiples of each other (and both are not $\vec{0}$), so they span a plane in \mathbb{R}^3 .

Linear systems vs. vector equations vs. matrices

$$x_1 + 5x_2 + 3x_3 + 2x_4 = 4$$

$$x_1 - 2x_3 + 2x_4 = 0$$

$$2x_2 + 4x_3 + 2x_4 = 1$$

can be rewritten as a **vector equation**

$$x_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_2 \cdot \begin{bmatrix} 5 \\ 0 \\ 2 \end{bmatrix} + x_3 \cdot \begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix} + x_4 \cdot \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}$$

Solutions to the linear system \leftrightarrow solutions to the vector equation.

Also the linear system is **represented** by the augmented matrix

$$\begin{bmatrix} 1 & 5 & 3 & 2 & 4 \\ 1 & 0 & -2 & 2 & 0 \\ 0 & 2 & 4 & 2 & 1 \end{bmatrix}$$

Linear systems vs. vector equations vs. matrices II

The augmented matrix is used to solve the linear system but the matrix representation is a *representation* and not an *equation*.

Question: Can we rewrite the linear system as a matrix equation?

Idea: Compare the coefficients matrix of the linear system

$$A = \begin{bmatrix} 1 & 5 & 3 & 2 \\ 1 & 0 & -2 & 2 \\ 0 & 2 & 4 & 2 \end{bmatrix} = \left[\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 5 \\ 0 \\ 2 \end{bmatrix} \quad \begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix} \quad \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \right]$$

with the vector equation

$$x_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_2 \cdot \begin{bmatrix} 5 \\ 0 \\ 2 \end{bmatrix} + x_3 \cdot \begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix} + x_4 \cdot \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}$$

Linear systems vs. vector equations vs. matrices III

Then we define for $\vec{x} = (x_1, x_2, x_3, x_4)$ the equation $A\vec{x} = \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}$ to mean the same as the vector equation

$$x_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_2 \cdot \begin{bmatrix} 5 \\ 0 \\ 2 \end{bmatrix} + x_3 \cdot \begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix} + x_4 \cdot \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}$$

In fact we can use this principle to define a product $A\vec{x}$ for any suitable vector \vec{x} !