

# TMA 4115 Matematikk 3

## Lecture 12 for MTFYMA

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In this lecture we discuss

- Solving linear systems (Recap)
- Linear (in-)dependence of vectors...
- ... what this means for solutions of linear systems

# Linear systems and associated equations

## Multiplication Matrix $\times$ Vector

For  $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_k]$  and  $\vec{x} = (x_1, x_2, \dots, x_k)$  we defined

$$A\vec{x} = x_1\vec{a}_1 + x_2\vec{a}_2 + \dots + x_k\vec{a}_k$$

Note: The product is a linear combination of the columns of  $A$ .

Linear system  $\leftrightarrow$  vector equation  $\sum_{i=1}^k r_i \vec{a}_i = \vec{b}$   
 $\leftrightarrow$  matrix equation  $A\vec{x} = \vec{b}$

To solve the equations apply *Gaussian elimination* to  $[A \ \vec{b}]$

## Linear systems and associated equations II

A linear system is **homogeneous** if we can write it as  $A\vec{x} = \vec{0}$ .

The general solution to  $A\vec{x} = \vec{b}$  in **parametric vector form** is:

$$\vec{x} = \vec{v}_p + r_1 \vec{v}_1 + \dots + r_k \vec{v}_k$$

where  $\vec{v}_p$  is a particular solution to  $A\vec{x} = \vec{b}$  and  $\vec{v}_1, \dots, \vec{v}_k$  are the solutions of  $A\vec{x} = \vec{0}$  associated to the free variables.

## Solutions of matrix equations

We were interested in the following questions about  $A\vec{x} = \vec{b}$

1. Is there a solution at all (i.e. is the system consistent)?
2. Is there a unique solution?

For  $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$  question 1 can be rephrased as:

- Is  $\vec{b} \in \text{span}\{\vec{a}_1, \dots, \vec{a}_n\}$ ?

What about the second question?

**Idea:** The general solution of  $A\vec{x} = \vec{b}$  will produce a unique solution if  $A\vec{x} = \vec{0}$  has a unique solution.

The trivial solution  $\vec{0}$  always exists. Hence,  $A\vec{x} = \vec{0}$  has a unique solution if and only if  $\vec{0}$  is the only solution.

## Summary: span and linear (in-)dependence

Let  $\vec{v}_1, \dots, \vec{v}_p$  be vectors and  $A = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_p \end{bmatrix}$ .

- $\text{span}\{\vec{v}_1, \dots, \vec{v}_p\}$  is the set of all vectors which can be generated from  $\vec{v}_1, \dots, \vec{v}_p$ .

**Test for  $\vec{b} \in \text{span}\{\vec{v}_1, \dots, \vec{v}_p\}$**

If  $A\vec{x} = \vec{b}$  is consistent,  $\vec{b}$  is in the span.

- Linear (in-)dependence is about redundancy, i.e. whether we can combine vectors from fewer vectors.

**Test for linear (in-)dependence of  $\{\vec{v}_1, \dots, \vec{v}_p\}$**

If  $[A \ \vec{0}]$  contains only basic variables, the family is linearly independent. Otherwise, the family is linearly dependent.

**Moral:** Use Gaussian elimination to settle these questions!