

TMA 4115 Matematikk 3

Lecture 27 for MTFYMA

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In today's lecture we will discuss

- again least square problems,
- symmetric and orthogonal matrices,
- the Spectral Theorem for symmetric matrices

Least square solutions

A $m \times n$ matrix, $\vec{b} \in \mathbb{R}^m$. $\vec{y} \in \mathbb{R}^n$ is called **least square solution** of $A\vec{x} = \vec{b}$ if

$$\|\vec{b} - A\vec{y}\| \leq \|\vec{b} - A\vec{x}\|, \quad \text{for all } \vec{x} \in \mathbb{R}^n.$$

Note: \vec{y} is a least square solution if and only if

- $A\vec{y} = \text{proj}_{\text{Col}(A)}(\vec{b})$
- It solves the **normal equation** $A^T A\vec{x} = A^T \vec{b}$

For every linear system there is a least square solution. It is the best (approximate) solution we can get.

Revisiting an example

Spring 2011 Problem 5

Let $A = \begin{bmatrix} 1 & 3 & 0 & 1 \\ 2 & 1 & 5 & -3 \\ -1 & -1 & -2 & 1 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 1 \\ 7 \\ 3 \end{bmatrix}$. Find the nearest point in $\text{Col}(A)$ to \vec{b} .

Avoid Gram-Schmidt and compute a least square solution \vec{y} to $A\vec{x} = \vec{b}$ the nearest point is then $A\vec{y}$. Normal equation: $A^T A \vec{x} = A^T \vec{b}$ yields

$$A^T A = \begin{bmatrix} 6 & 6 & 12 & -6 \\ 6 & 11 & 7 & -1 \\ 12 & 7 & 29 & -17 \\ -6 & -1 & -17 & 11 \end{bmatrix}.$$

Can we simplify the problem so that we do not need $A^T A$?

Revisiting an example

Idea: $\text{Col}(A)$ is important, but A is not!

Use the method with simpler matrix B with $\text{Col}(B) = \text{Col}(A)$.

In last lecture we saw that $\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}$ is a basis of $\text{Col}(A)$.

Set $B = \begin{bmatrix} 1 & 3 \\ 2 & 1 \\ -1 & -1 \end{bmatrix}$ and compute:

$$B^T B = \begin{bmatrix} 6 & 6 \\ 6 & 5 \end{bmatrix}, B^T \vec{b} = \begin{bmatrix} 12 \\ 7 \end{bmatrix}$$

Solving $B^T B \vec{x} = B^T \vec{b}$ yields the least square solution $\begin{bmatrix} 3 \\ -1 \end{bmatrix}$

Revisiting an example

The nearest point to \vec{b} in $\text{Col}(A) = \text{Col}(B)$ is

$$B \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 5 \\ -2 \end{bmatrix}$$

as before!

Remark

Can compute nearest points in a subspace by solving least square problems.

→ avoid Gram-Schmidt (= messy computation).

An observation

In setting up the normal equation we computed matrices of the form $A^T A$. Here are some examples:

$$\begin{bmatrix} 17 & 1 \\ 1 & 5 \end{bmatrix}, \quad \begin{bmatrix} 4 & 17 \\ 17 & 81 \end{bmatrix}, \quad \begin{bmatrix} 6 & 6 & 12 & -6 \\ 6 & 11 & 7 & -1 \\ 12 & 7 & 29 & -17 \\ -6 & -1 & -17 & 11 \end{bmatrix}$$

These matrices have an interesting structure:

Their transpose coincides with the matrix!¹

These special matrices are called **symmetric** and we will now investigate them.

¹By the rules of the transpose $(A^T A)^T = A^T (A^T)^T = A^T A$.

Spectral Theorem for symmetric matrices

A symmetric $n \times n$ matrix, then the following holds:

- (a) A has n real eigenvalues counting multiplicities^a
- (b) $\dim E_\lambda$ equals the multiplicity of the eigenvalue λ ,
Recall: E_λ = eigenspace to eigenvalue λ
- (c) $\lambda \neq \mu$ eigenvalues of A , then $E_\lambda \subseteq E_\mu^\perp$,
- (d) A is orthogonally diagonalisable.

^a**Multiplicity of eigenvalue:** Multiplicity of the root of the characteristic polynomial.

Example: If $(\lambda - 1)^n(\lambda + 3)$ is the characteristic polynomial, $\lambda = 1$ is an eigenvalue of multiplicity n , $\lambda = -3$ is eigenvalue of multiplicity 1.

Spectrum (of a matrix) = set of eigenvalues.

$A = PDP^{-1}$ with $P = \begin{bmatrix} \vec{u}_1 & \dots & \vec{u}_n \end{bmatrix}$ orthogonal, D a diagonal matrix (diagonal entries $\lambda_1, \dots, \lambda_n$ the eigenvalues of A .) Since $P^{-1} = P^T$ we have

$$\begin{aligned} A = PDP^T &= \begin{bmatrix} \vec{u}_1 & \dots & \vec{u}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \\ \vdots \\ \vec{u}_n^T \end{bmatrix} \\ &= \begin{bmatrix} \lambda_1 \vec{u}_1 & \dots & \lambda_n \vec{u}_n \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \\ \vdots \\ \vec{u}_n^T \end{bmatrix} \end{aligned}$$

We obtain the so called **spectral decomposition** of A

$$A = \lambda_1 \vec{u}_1 \vec{u}_1^T + \lambda_2 \vec{u}_2 \vec{u}_2^T + \dots + \lambda_n \vec{u}_n \vec{u}_n^T$$

Note: $(\vec{u}_k \vec{u}_k^T) \vec{x} = \text{proj}_{\text{span}\{\vec{u}_k\}}(\vec{x})$