

**EXAMPLE 6** Shifted Data Problems

This means initial value problems with initial conditions given at some  $t = t_0 > 0$  instead of  $t = 0$ . For such a problem set  $t = \tilde{t} + t_0$ , so that  $t = t_0$  gives  $\tilde{t} = 0$  and the Laplace transform can be applied. For instance, solve

$$y'' + y = 2t, \quad y(\frac{1}{4}\pi) = \frac{1}{2}\pi, \quad y'(\frac{1}{4}\pi) = 2 - \sqrt{2}.$$

**Solution.** We have  $t_0 = \frac{1}{4}\pi$  and we set  $t = \tilde{t} + \frac{1}{4}\pi$ . Then the problem is

$$\tilde{y}'' + \tilde{y} = 2(\tilde{t} + \frac{1}{4}\pi), \quad \tilde{y}(0) = \frac{1}{2}\pi, \quad \tilde{y}'(0) = 2 - \sqrt{2}$$

where  $\tilde{y}(\tilde{t}) = y(t)$ . Using (2) and Table 6.1 and denoting the transform of  $\tilde{y}$  by  $\tilde{Y}$ , we see that the subsidiary equation of the “shifted” initial value problem is

$$s^2\tilde{Y} - s \cdot \frac{1}{2}\pi - (2 - \sqrt{2}) + \tilde{Y} = \frac{2}{s^2} + \frac{\frac{1}{2}\pi}{s}, \quad \text{thus} \quad (s^2 + 1)\tilde{Y} = \frac{2}{s^2} + \frac{1}{2}\pi s + 2 - \sqrt{2}.$$

Solving this algebraically for  $\tilde{Y}$ , we obtain

$$\tilde{Y} = \frac{2}{(s^2 + 1)s^2} + \frac{\frac{1}{2}\pi}{(s^2 + 1)s} + \frac{\frac{1}{2}\pi s}{s^2 + 1} + \frac{2 - \sqrt{2}}{s^2 + 1}.$$

The inverse of the first two terms can be seen from Example 3 (with  $\omega = 1$ ), and the last two terms give  $\cos$  and  $\sin$ ,

$$\begin{aligned} \tilde{y} &= \mathcal{L}^{-1}(\tilde{Y}) = 2(\tilde{t} - \sin \tilde{t}) + \frac{1}{2}\pi(1 - \cos \tilde{t}) + \frac{1}{2}\pi \cos \tilde{t} + (2 - \sqrt{2}) \sin \tilde{t} \\ &= 2\tilde{t} + \frac{1}{2}\pi - \sqrt{2} \sin \tilde{t}. \end{aligned}$$

Now  $\tilde{t} = t - \frac{1}{4}\pi$ ,  $\sin \tilde{t} = \frac{1}{\sqrt{2}}(\sin t - \cos t)$ , so that the answer (the solution) is

$$y = 2t - \sin t + \cos t. \quad \blacksquare$$

**PROBLEM SET 6.2****1–11** INITIAL VALUE PROBLEMS (IVPS)

Solve the IVPs by the Laplace transform. If necessary, use partial fraction expansion as in Example 4 of the text. Show all details.

- $y' + \frac{2}{3}y = -4 \cos 2t$ ,  $y(0) = 0$
- $y' + 2y = 0$ ,  $y(0) = 1.5$
- $y'' + y' - 6y = 0$ ,  $y(0) = 1$ ,  $y'(0) = 1$
- $y'' + 9y = 10e^{-t}$ ,  $y(0) = 0$ ,  $y'(0) = 0$
- $y'' - \frac{1}{4}y = 0$ ,  $y(0) = 12$ ,  $y'(0) = 0$
- $y'' - 6y' + 5y = 29 \cos 2t$ ,  $y(0) = 3.2$ ,  $y'(0) = 6.2$
- $y'' + 7y' + 12y = 21e^{3t}$ ,  $y(0) = 3.5$ ,  $y'(0) = -10$
- $y'' - 4y' + 4y = 0$ ,  $y(0) = 8.1$ ,  $y'(0) = 3.9$
- $y'' - 3y' + 2y = 4t - 8$ ,  $y(0) = 2$ ,  $y'(0) = 7$
- $y'' + 0.04y = 0.02t^2$ ,  $y(0) = -25$ ,  $y'(0) = 0$
- $y'' + 3y' + 2.25y = 9t^3 + 64$ ,  $y(0) = 1$ ,  $y'(0) = 31.5$

**12–15** SHIFTED DATA PROBLEMS

Solve the shifted data IVPs by the Laplace transform. Show the details.

- $y'' + 2y' - 3y = 0$ ,  $y(2) = -3$ ,  $y'(2) = -5$
- $y' - 6y = 0$ ,  $y(-1) = 4$
- $y'' + 2y' + 5y = 50t - 100$ ,  $y(2) = -4$ ,  $y'(2) = 14$
- $y'' + 3y' - 4y = 6e^{2t-3}$ ,  $y(1.5) = 4$ ,  $y'(1.5) = 5$

**16–21** OBTAINING TRANSFORMS BY DIFFERENTIATION

Using (1) or (2), find  $\mathcal{L}(f)$  if  $f(t)$  equals:

- $t \cos 4t$
- $\cos^2 t$
- $\sin^4 t$ . Use Prob. 19.
- $t \sinh^2 t$

**22. PROJECT. Further Results by Differentiation.**

Proceeding as in Example 1, obtain

$$(a) \quad \mathcal{L}(t \cos \omega t) = \frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$$

and from this and Example 1: (b) formula 21, (c) 22, (d) 23 in Sec. 6.9,

$$(e) \quad \mathcal{L}(t \cosh at) = \frac{s^2 + a^2}{(s^2 - a^2)^2},$$

$$(f) \quad \mathcal{L}(t \sinh at) = \frac{2as}{(s^2 - a^2)^2}.$$

**23–29** INVERSE TRANSFORMS BY INTEGRATION

Using Theorem 3, find  $f(t)$  if  $\mathcal{L}(F)$  equals:

$$23. \frac{2}{s^2 + s/3} \quad 24. \frac{20}{s^3 - 2\pi s^2}$$

$$25. \frac{1}{s(s^2 + \omega^2/4)} \quad 26. \frac{1}{s^4 - s^2}$$

$$27. \frac{s + 8}{s^4 + 4s^2} \quad 28. \frac{3s + 4}{s^4 + k^2s^2}$$

$$29. \frac{1}{s^3 + as^2}$$

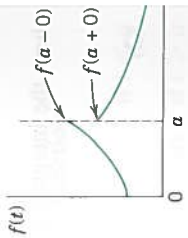


Fig. 117. Formula (1\*)

**6.3** Unit Step Function (Heaviside Function) Second Shifting Theorem (t-Shifting)

This section and the next one are extremely important because we shall see that the Laplace transform method shows its real power in a superiority over the classical approach of Chap. 2. The reason is that two auxiliary functions, the *unit step function* or *Heaviside function*  $u(t)$  (in Sec. 6.4), and the *Dirac's delta*  $\delta(t - a)$  (in Sec. 6.4). These functions are suitable for complicated right sides of considerable engineering interest, such as *driving forces* that are discontinuous or act for some time only, *generalized forces* that are just cosine and sine, or *impulsive forces* acting for an instant for example).

**Unit Step Function (Heaviside Function)  $u(t)$** 

The *unit step function* or *Heaviside function*  $u(t - a)$  is 0 for  $t < a$ , and 1 for  $t = a$  (where we can leave it undefined), and is 1 for  $t > a$ , in a

$$u(t - a) = \begin{cases} 0 & \text{if } t < a \\ 1 & \text{if } t > a \end{cases} \quad (1)$$