

Diff. eq'ns 19.3.13

A. Unstable equi-pt.'s

(1) $\dot{x} = f(x)$; $x: \mathbb{R} \rightarrow \mathbb{R}^n$, $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$

Thm. 1: Assume $f(0) = 0$ and f Lip. in domain $B \ni 0$.

Then $x = 0$ unstab. equi-pt. if exists U s.t.

i) $U \in C^1$

ii) $U(0) = 0$

iii) for all $\delta > 0$ exists x s.t. $|x| < \delta$ and $U(x) > 0$

iv) exists $\eta > 0$ s.t.

$$\dot{U}(x) = \nabla U(x) \cdot f(x) > 0$$

for all x s.t. $|x| < \eta$ and $U(x) > 0$.

Rem. 1:

a) Typical U 's: $x_1 x_2$, $x_1^2 - x_2^2$, $\sum_{i \neq j} x_i x_j$, ...

b) Same conclusion w. $U, \dot{U} < 0$ on iii) and iv)
[then $-U$ satisfy i) - iv)]

Ex. 1:

2)

$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -(1-x_1^2)x_2 + x_1 \end{cases}$$

0 equi. pt.

$$U(x_1, x_2) = x_1 \cdot x_2$$

i) - iii) $U \in C^1$, $U(0) = 0$, $U(s, s) = s^2 > 0$ for $s \neq 0$

$$\begin{aligned} \text{iv)} \quad \dot{U} &= \dot{x}_1 x_2 + x_1 \dot{x}_2 = x_2^2 - (1-x_1^2)x_2 x_1 + x_1^2 \\ &\stackrel{x_1^2 < 1}{>} x_1^2 + x_2^2 - \underbrace{|x_1 x_2|}_{\leq \frac{1}{2}(x_1^2 + x_2^2)} \stackrel{x_1 x_2 > 0}{>} \frac{1}{2}(x_1^2 + x_2^2) > 0 \end{aligned}$$

when $U = x_1 \cdot x_2 > 0$ (and $x_1^2 < 1$)

Thm. 1 \Rightarrow 0 unstab.

Pf. of Thm. 1:

1) Let $0 < \delta < \frac{1}{2}$ and x_0 s. f.

$$|x_0| < \delta \text{ and } U(x_0) > 0 \quad (\text{iii})$$

Def.

$$K = \left\{ x : |x| \leq \frac{1}{2}, U(x) \geq U(x_0) \right\}$$

K is closed, bnd. (U cont.)

If x solves (1) and $x(t) \in K$ for all $t \geq t_0$,

then

$$\frac{d}{dt} U(x(t)) \stackrel{(1)}{\geq} \min_{x \in K} \dot{U}(x) \stackrel{U \text{ cont. (iv), ii)}}{=} \gamma > 0$$

K closed, bnd

for all $t \geq t_0$.

2) Let $x(t) = \varphi(t; x_0, t_0)$ ($x_0 \in K!$)

3.)

Assume $x(t) \in K$, $t \geq t_0$

$$\stackrel{1)}{\Rightarrow} \frac{d}{dt} U(x(t)) \geq \gamma > 0$$

$$\Rightarrow U(x(t)) \xrightarrow[t \rightarrow \infty]{} \infty$$

Contradiction, since K closed, bnd and U cont.

(so $\max_{x \in K} U(x) < \infty$)

Hence $x(t)$ leaves K and then $\{|x| \leq \frac{\eta}{2}\}$

(since $U(x_0) > 0$, $\dot{U} > 0 \Rightarrow U(x(t)) > 0, t > t_0$)

in finite time.

Conclusion: For all $\delta > 0$ exists x_0 s.t.

$$|x - x_0| < \delta \Rightarrow \max_{t \geq t_0} |\varphi(t; x_0, t_0) - 0| > \frac{\eta}{2}$$

and 0 unstab. □

B. Linearization again

Thm. 2: (earlier)

Assume $f \in C^1$, $f(x_0) = 0$, λ_i eig-val's of $Df(x_0)$,

then

$\max_i \operatorname{Re} \lambda_i > 0 \Rightarrow x = x_0$ unstab. equi.pt. of (1).

Lem. 1: If $A \in \mathbb{R}^{n \times n}$ has eig. val's λ_i s.t.

$$\alpha \leq \operatorname{Re} \lambda_i \leq \beta \quad (\alpha, \beta \in \mathbb{R}),$$

then for all $\varepsilon > 0$ exists \tilde{A} similar to A s.t.

$$(\alpha - \varepsilon)|x|^2 \leq x^T \tilde{A} x \leq (\beta + \varepsilon)|x|^2.$$

Rem. 2:

Can take $\varepsilon = 0$ when A has n lin. indep. eig. vec's!

Pf. of Thm. 2:

1) $x_1, x_2 \equiv x_0$ solves (1)

$\Rightarrow P y = x_1 - x_2$ solves

(*) $\dot{y} = \tilde{A} y + \sigma(|y|)$ as $y \rightarrow 0$

where $\tilde{A} = P^{-1} D f(x_0) P$ can be chosen^m Jordan form

$$\tilde{A} = \begin{bmatrix} B_1 & 0 \\ 0 & \bar{B} \end{bmatrix}$$

s.t. B_1 corresponds to eig. val. λ_j w. max. Re-value

2) Let $\beta = \max_i \operatorname{Re} \lambda_i = \operatorname{Re} \lambda_j$, $\bar{\beta} = \max_{i \neq j} \operatorname{Re} \lambda_i < \beta$.

By Lem. 1, can take P s.t.

$$(\beta - \varepsilon)|y_1|^2 \leq y_1^T B_1 y_1, \quad \bar{y}^T \bar{B} \bar{y} \leq (\bar{\beta} + \varepsilon)|\bar{y}|^2$$

where $y = (y_1, \bar{y})$ and $0 < \varepsilon < \frac{1}{2}(\beta - \bar{\beta})$.

$$3) \text{ Def. } U(y, \bar{y}) = \frac{1}{2}(|y|^2 - |\bar{y}|^2)$$

Obs: U satisfy i), ii), iii) of Thm. 1

$$\frac{d}{dt} U(y(t)) = y \cdot \dot{y} - \bar{y} \cdot \dot{\bar{y}}$$

$$(*) \stackrel{(*)}{=} y_1^T B_1 y_1 - \bar{y}^T \bar{B} \bar{y} + \sigma(|y|^2)$$

$$2) \geq (\beta - \varepsilon)|y|^2 - (\bar{\beta} + \varepsilon)|\bar{y}|^2 + \sigma(|y|^2)$$

$$U(y) > 0 \Rightarrow |y| > |\bar{y}| \geq 0$$

$$\Rightarrow \frac{d}{dt} U(y(t)) \geq \underbrace{(\beta - \bar{\beta} - 2\varepsilon)}_{> 0} |y|^2 + \sigma(|y|^2) > 0$$

for $|y|$ small enough.

Conclusion: U satisfies i) - iv) of Thm. 1

$\Rightarrow y=0$ ($x=x_0$) unstab. equipt. for (*)
(for (1)) □

Ex. 2:

$$(**)_\pm \begin{cases} \dot{x}_1 = x_2 \pm x_1(x_1^2 + x_2^2) \\ \dot{x}_2 = -x_1 \pm x_2(x_1^2 + x_2^2) \end{cases}$$

$$Df(0) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \Rightarrow \lambda_\pm = \pm i, \max_{\pm} \operatorname{Re} \lambda_\pm = 0$$

\Rightarrow no conclusion by linearization.

$$W = \frac{1}{2}(x_1^2 + x_2^2)$$

$$\dot{W} = x_1 \dot{x}_1 + x_2 \dot{x}_2 \stackrel{(**)_\pm}{=} \pm (x_1^2 + x_2^2)^2$$

$V=W$ str. L. func. for $(**)_-$ $\Rightarrow O$ asympt. stab. in $(**)_-$

$U=W$ satisfy Thm. 1 for $(**)_+$ $\Rightarrow O$ unstab. in $(**)_+$

Obs. 1: (not asympt. stab.) (center at $x=0$)

Lin. syst. stab., but non-lin. syst.

either asympt. stab. or unstab. !

C. Proof of Lem. 1

1) $A = B_i =$ Jordan block of λ_i

a) $B_i = \lambda_i \in \mathbb{R} \Rightarrow x^T B_i x = \lambda_i |x|^2 \quad (x \in \mathbb{R}^1)$

b) $B_i = \lambda_i I + N = \begin{bmatrix} \lambda_i & 1 & 0 \\ 0 & \ddots & \vdots \\ 0 & & \lambda_i \end{bmatrix} \in \mathbb{R}^{d \times d}$

$$D_\varepsilon = \begin{bmatrix} 1 & & 0 \\ & \varepsilon & \\ 0 & & \varepsilon^{d-1} \end{bmatrix}, \quad D_\varepsilon^{-1} B_i D_\varepsilon =$$

$$D_\varepsilon^{-1} B_i D_\varepsilon = \begin{bmatrix} 1 & \frac{1}{\varepsilon} & 0 \\ & \ddots & \\ 0 & & \frac{1}{\varepsilon^{d-1}} \end{bmatrix} \cdot \begin{bmatrix} \lambda_i & \varepsilon & 0 \\ & \varepsilon \lambda_i & \varepsilon^2 \\ 0 & & \varepsilon^{d-1} \lambda_i \end{bmatrix} = \begin{bmatrix} \lambda_i & \varepsilon & 0 \\ & \varepsilon \lambda_i & \varepsilon^2 \\ 0 & & \lambda_i \end{bmatrix}$$

$$= \lambda_i I + \varepsilon N$$

Obs: $|x^T N x| = |x_1 x_2 + x_2 x_3 + \dots + x_{d-1} x_d|$

$$\leq \frac{1}{2}(x_1^2 + x_2^2) + \dots + \frac{1}{2}(x_{d-1}^2 + x_d^2)$$

$$\leq x_1^2 + \dots + x_d^2 = |x|^2$$

Hence

$$(\lambda_i - \varepsilon) |x|^2 \leq \underbrace{x^T \lambda_i x + \varepsilon x^T N x}_{x^T B_i x}$$

$$\leq (\lambda_i + \varepsilon) |x|^2$$

c) $B_i = D_i = \begin{bmatrix} \operatorname{Re} \lambda_i & \operatorname{Im} \lambda_i \\ -\operatorname{Im} \lambda_i & \operatorname{Re} \lambda_i \end{bmatrix}$

$$\Rightarrow x^T B_i x \stackrel{\text{chk}}{=} x^T \frac{1}{2} (B_i + B_i^T) x = \operatorname{Re} \lambda_i |x|^2 \quad (x \in \mathbb{R}^2)$$

$x^T (B_i - B_i^T) x = 0$

d) $B_i = \begin{bmatrix} D_i & I & 0 \\ & \ddots & \ddots \\ 0 & & D_i \end{bmatrix}, \quad D_\varepsilon = \begin{bmatrix} I & & 0 \\ & \varepsilon I & \\ 0 & & \varepsilon^{m-1} I \end{bmatrix}$

$$\stackrel{\text{chk}}{\leadsto} (\operatorname{Re} \lambda_i - \varepsilon) |x|^2 \leq x^T D_\varepsilon^{-1} B_i D_\varepsilon x \leq (\operatorname{Re} \lambda_i + \varepsilon) |x|^2$$

2) General $A \in \mathbb{R}^{n \times n}$:

A similar w. Jordan form $J = \begin{bmatrix} B_1 & & 0 \\ & \ddots & \\ 0 & & B_m \end{bmatrix}$

$$x^T J x = \sum x_j^T B_j x_j; \quad x = (x_1, \dots, x_m)$$

$\uparrow \quad \quad \quad \uparrow$
vectors

where B_j Jordan blocks as in 1).

By 1), exists P_j and $\tilde{B}_j = P_j B_j P_j^{-1}$ s.t.

8.)

$$(\alpha - \varepsilon) |x_j|^2 \leq (\operatorname{Re} \lambda_i - \varepsilon) |x_j|^2$$

$$\leq x_j^T B_j x_j$$

$$\leq (\operatorname{Re} \lambda_i + \varepsilon) |x_j|^2 \leq (\beta + \varepsilon) |x_j|^2$$

$$\Rightarrow (\alpha - \varepsilon) |x|^2 = (\alpha - \varepsilon) \sum_j |x_j|^2$$

$$\leq \sum x_j^T B_j x_j = x^T \tilde{A} x$$

$$\leq (\beta + \varepsilon) \sum |x_j|^2 = (\beta + \varepsilon) |x|^2$$

where $\tilde{A} = \begin{bmatrix} \tilde{B}_1 & 0 \\ 0 & \tilde{B}_m \end{bmatrix} = P J P^{-1}$, $P = \begin{bmatrix} P_1 & 0 \\ 0 & P_m \end{bmatrix}$ \square