

Diff. eqn's 21.2.13

7)

Messages

- Copy of B-R sold at IMF office
- Read B-R chp. 6.5

A. Cont. dep. on f

$$(1) \dot{x} = f(x, t)$$

$$(2) x(t_0) = x_0$$

where $f = (f_1, \dots, f_n)$, $x = (x_1, \dots, x_n)$.

Thm. 1: (cont. dep. on data)

Let $R \subset \mathbb{R}^{n+1}$ be a domain. If

i) f cont. and x -Lip. on R . on domain $R \subset \mathbb{R}^{n+1}$

ii) g cont. on R , and there is $\varepsilon > 0$ s.t.

$$|f(x, t) - g(x, t)| \leq \varepsilon \text{ in } R, \forall t \in R.$$

iii) $(x(t), t), (y(t), t) \in R$ for $t \in [t_0, b)$.

iv) x, y solve

$$\begin{cases} \dot{x} = f(x, t) & \text{in } (t_0, b) \\ x(t_0) = x_0 \end{cases} \text{ and } \begin{cases} \dot{y} = g(y, t) & \text{in } (t_0, b) \\ y(t_0) = y_0 \end{cases}$$

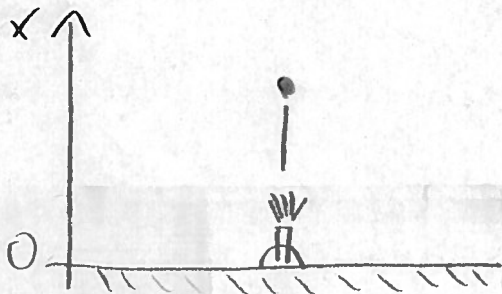
then

2.)

$$|x(t) - y(t)| \leq e^{2L(t-t_0)} |x_0 - y_0| + \frac{\varepsilon}{L} \sqrt{e^{2L(t-t_0)} - 1}, \quad t \in [t_0, b]$$

where $L \leq \max_{(x,t) \in \mathbb{R}} \|Df\| < \infty$.

Ex. 1: Projectile



$$m \frac{d^2 x^*}{dt^{*2}} = -mg \quad (\text{const. } g)$$

$$m \frac{d^2 x^*}{dt^{*2}} = -\frac{mg}{\left(1 + \frac{x^*}{R}\right)^2} \quad (\text{Newton})$$

$$g = \frac{GM}{R^2}, \quad R \text{ planet radius}$$

Scaled eq'ns: $(x^* = \underbrace{X}_{\text{max. height}} x, t^* = \sqrt{\frac{X}{g}} t)$

$$\ddot{x} = -1, \quad \ddot{x}^\varepsilon = -\frac{1}{(1 + \varepsilon x^\varepsilon)^2}; \quad 0 < \varepsilon = \frac{X}{R} \ll 1 \quad (\text{typically})$$

\Downarrow \Updownarrow

$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -1 \end{cases}, \quad \begin{cases} \dot{x}_1^\varepsilon = x_2^\varepsilon \\ \dot{x}_2^\varepsilon = -\frac{1}{(1 + \varepsilon x_1^\varepsilon)^2} \end{cases}$$

$f(x)$ $f_\varepsilon(x)$

$$\text{Obs: } |f(x) - f_\varepsilon(x)| = \sqrt{\underbrace{|x_2 - x_2^\varepsilon|^2}_{=0} + \underbrace{\left| -1 + \frac{1}{(1 + \varepsilon x_1)^\varepsilon} \right|^2}_{f_2 - f_2^\varepsilon}}$$

$$\text{chk. } = \varepsilon |x_1| \frac{|2 + \varepsilon x_1|}{(1 + \varepsilon x_1)^2} \leq \varepsilon |x_1| 2 \leq 2\varepsilon X$$

when $|x_1| \leq X$ (max. height)

$$\text{Obs: } Df = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow \|Df\| = 1 = L$$

3)

(do not need Df_ε !)

init. cond'ns (think!)

$$x_1(0) = 0 = x_1^\varepsilon(0), \quad x_2(0) = \dot{x}_1(0) = v = \dot{x}_1^\varepsilon(0) = x_2^\varepsilon(0)$$

By Thm. 1:

$$|x(t) - x^\varepsilon(t)| \leq 2X\varepsilon \cdot \sqrt{e^{2t} - 1} \quad (|x| \leq H)$$

Obs: $x_\varepsilon(t) \rightarrow x(t)$ (unif. on closed int's) as $\varepsilon \rightarrow 0$!

Cor. 1:

Let $R \subset \mathbb{R}^{n+1}$ be a domain. ~~Assume~~ If

i) f cont. and x -Lip. on R

ii) f_ε cont. on R and

$$\max_{(x,t) \in R} |f(t,x) - f_\varepsilon(t,x)| \xrightarrow{\varepsilon \rightarrow 0} 0,$$

iii) $(x(t), t), (x_\varepsilon(t), t) \in R$ for $\varepsilon > 0, t \in [t_0, b]$,

iv) $|x_0 - x_0^\varepsilon| \xrightarrow{\varepsilon \rightarrow 0} 0$

v) x and y solve

$$\begin{cases} \dot{x} = f(x,t), \text{ in } (t_0, b) \\ x(t_0) = x_0 \end{cases} \quad \text{and} \quad \begin{cases} \dot{x}^\varepsilon = f^\varepsilon(x,t), \text{ in } (t_0, b) \\ x^\varepsilon(t_0) = x_0^\varepsilon, \end{cases}$$

then $x_\varepsilon(t) \xrightarrow{\varepsilon \rightarrow 0} x(t)$, unif. on int's $[t_0, b_1]$ for $b_1 < b$.

Pf.: Use Thm. 1.!

Rem. 1:

Cor. 1 \Rightarrow solⁿs of (1) and (2) dep. cont.
on the data f and x_0 when f cont., x -Lip.

B. Pf. of Thm. 1

$$1) \sigma(t) = |x(t) - y(t)|^2$$

$$\dot{\sigma}(t) = 2(x-y) \cdot (\dot{x} - \dot{y}) = 2(x-y) \cdot (f(x,t) - g(y,t))$$

$$\stackrel{C-S}{\leq} 2|x-y| \cdot |f(x,t) - g(y,t)|$$

$$2) | \underbrace{f(x,t) - f(y,t)}_{=0} + f(y,t) - g(y,t) |$$

$$\leq |f(x,t) - f(y,t)| + |f(y,t) - g(y,t)|$$

$$\stackrel{i), ii)}{\leq} L|x-y| + \varepsilon \quad \begin{matrix} \downarrow i) \\ ii) \end{matrix}$$

3) By 1) and 2)

$$\dot{\sigma} \leq 2L \underbrace{|x-y|^2}_{=\sigma} + 2|x-y|\varepsilon$$

Obs: $0 \leq (a-b)^2 = a^2 - 2ab + b^2 \Rightarrow 2ab \leq a^2 + b^2$

Let $a = \sqrt{L}|x-y|$, $b = \frac{1}{\sqrt{L}}\varepsilon$, then

$$2|x-y|\varepsilon = 2a \cdot b \leq a^2 + b^2 = L|x-y|^2 + \frac{1}{L}\varepsilon^2$$

Hence

$$\dot{\sigma} \leq 3L\sigma + \frac{1}{L}\varepsilon^2$$

4) Int. factor e^{-3Lt}

5)

$$\frac{d}{dt}(e^{-3Lt} \sigma) = e^{-3Lt} (\dot{\sigma} - 3L\sigma) \stackrel{3)}{\leq} e^{-3Lt} \frac{\varepsilon^2}{L}$$

$$\Downarrow \int_{t_0}^t$$

$$e^{-3Lt} \sigma(t) - e^{-3Lt_0} \sigma(t_0) \leq \frac{\varepsilon^2}{L} \int_{t_0}^t e^{-3Ls} ds$$

$$\Downarrow$$

$$\sigma(t) \leq e^{3L(t-t_0)} \sigma(t_0) + \frac{\varepsilon^2}{3L^2} (e^{3L(t-t_0)} - 1)$$

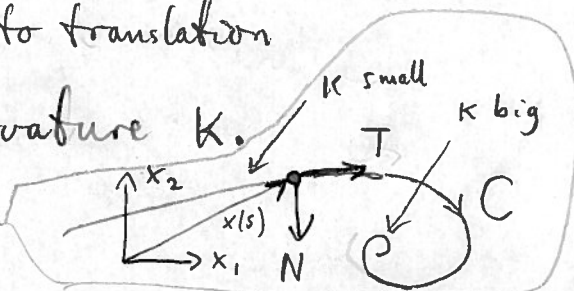
5) $\sqrt{\sigma} \leq \dots$ use $\sqrt{|a|+|b|} \leq \sqrt{|a|} + \sqrt{|b|}$ (chk)

(obs: $\frac{3}{2} \leq 2$, $\frac{1}{\sqrt{3}} \leq 1$) \square

C. Application: Regular curves (geometry)

Thm. 2: A regular C^3 -curve C in \mathbb{R}^2 is uniquely determined (up to translation and rotation) by its curvature κ .

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Regular C^3 -curve C :

There is arclength param. $x(s) \in C^3$ s.t. $\dot{x} \neq 0$; \dot{x}, \ddot{x} lin. indep. and

$$C = \{x(s) : s \in I\}$$

$$\div | \text{Lem. 1: } u \in C^1(I; \mathbb{R}^2), |u| = 1 \Rightarrow 0 = \left(\frac{d}{dt} \frac{1}{2} |u|^2 \right) = u \cdot \frac{du}{dt}$$

Δ By Obs. 7, x

Recall: (calculus)

a) By def. $\left| \frac{dx}{ds} \right| = 1$ (speed = 1)

b) $\vec{T} = \frac{dx}{ds}$, $\vec{N} = \frac{\frac{d\vec{T}}{ds}}{\left| \frac{d\vec{T}}{ds} \right|}$, $K(s) = \left| \frac{d\vec{T}}{ds} \right|$
 unit tangent u. normal since \dot{x}, \ddot{x} lin. indep.

c) $|\vec{T}| = 1 = |\vec{N}|$, $\vec{T} \cdot \vec{N} = 0$ $\left[0 = \frac{d}{ds} \frac{1}{2} |\vec{T}|^2 = \vec{T} \cdot \frac{d\vec{T}}{ds} \right]$

d) $x(s) = x(0) + \int_0^s \vec{T}(s) ds$

$\Rightarrow T$ determines x (and C) uniquely up to a transl. $x(0)$.

Obs:

(3) $\begin{cases} \frac{d\vec{T}}{ds} = K(s) \vec{N} \\ \frac{d\vec{N}}{ds} = -K(s) \vec{T} \end{cases}$

Frenet-Serret eq'ns

$\left[0 = \frac{d}{ds} (\vec{T} \cdot \vec{N}) = \frac{d\vec{T}}{ds} \cdot \vec{N} + \vec{T} \cdot \frac{d\vec{N}}{ds} \Rightarrow \frac{d\vec{N}}{ds} \cdot \vec{T} = -K \right]$

$|\vec{N}| = 1 \Rightarrow \frac{d\vec{N}}{ds} \cdot \vec{N} = 0$ (see c)]

Pf. of Thm. 2:

(3) lin. 6×6 syst. (\Rightarrow loc. x -Lip. since K cont.) $[K = |\dot{x}| \in C^0]$

~~HK cond. ($x \in C^2$)~~ \Rightarrow exists unique soln of (3) and

$T(0) = T_0$, $N(0) = N_0$

d) $\Rightarrow x(s)$ determined up to $x(0)$, $T(0)$, $N(0)$ □

Ex. 2:

Circle C : $x(s) = x_0 + r \left(\cos \frac{s}{r}, \sin \frac{s}{r} \right)$ radius r
center x_0

$\dot{x} = \left(-\sin \frac{s}{r}, \cos \frac{s}{r} \right), |\dot{x}| = 1 \Rightarrow s = \text{arc length}, T = \dot{x}$



$K(s) = \left| \frac{dT}{ds} \right| = |\ddot{x}| = \frac{1}{r} \sqrt{\cos^2 \frac{s}{r} + \sin^2 \frac{s}{r}} = \frac{1}{r}$

\Rightarrow any circle (in \mathbb{R}^2) has $K(s) = \text{const} \neq 0$.

Thm. 2
 \Rightarrow all reg. C^3 curves in \mathbb{R}^2 w. $K = \text{const.} \neq 0$
uniqueness are (parts of) circles.

Rem. 3: Reg. C^4 -curves in \mathbb{R}^3

$\dot{T} = K(s)\vec{N}, \dot{N} = -K(s)\vec{T} + \tau(s)\vec{B}, \dot{B} = -\tau(s)\vec{N}$ (F-S eq's)

\uparrow \uparrow
 torsion binormal
 (def.) $\vec{B} = \vec{T} \times \vec{N}$

Curves uniquely determined by $K(s) \neq 0, \tau(s)$
(up to transl./rot.)

HW: Read B-R chp. 6.5

17.02

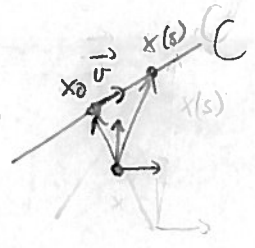
lvs
for

Ex. 3:

Line C : $x(s) = x_0 + s\vec{v}; \vec{v} \text{ const}, |\vec{v}| = 1$.

$|\dot{x}| = |\vec{v}| = 1 \Rightarrow s \text{ arc length}, T = \vec{v}$

$\frac{dT}{ds} = 0 \Rightarrow$ any line has $K(s) \equiv 0$



Obs: Thm. 2 does not apply. C not reg. ($\dot{x}, \ddot{x} = 0$ not lin. indep.)