

A. Invariant and attracting domains

(i)  $\dot{x} = f(x) ; x: \mathbb{R} \rightarrow \mathbb{R}^n, f: \mathbb{R}^n \rightarrow \mathbb{R}^n$

Concepts:

1) Flow:  $\varphi(t; x_0)$ , sol'n of (1) and  $x(0) = x_0$

2) Half trajectory:  $T_{x_0}^{\pm} = \{ \varphi(t; x_0) : \pm t \geq 0 \}$

3) Phase — " — :  $T_{x_0} = T_{x_0}^{-} \cup T_{x_0}^{+}$

4)  $\Omega \subset \mathbb{R}^n$  invariant (positively inv.) under (1):

$$T_{x_0}^{-} \subset \Omega \quad (T_{x_0}^{+} \subset \Omega) \text{ for all } x_0 \in \Omega.$$

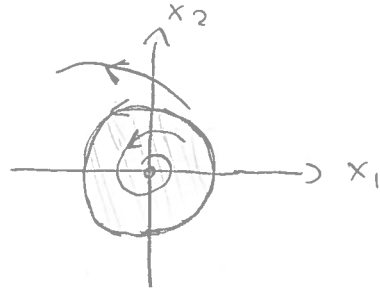
5) Domain of attraction of equi. pt.  $x_0$ :

$$\Omega_a = \{ x \in \mathbb{R}^n : \lim_{t \rightarrow \infty} \varphi(t; x) = x_0 \}$$

Ex. 1:

$$(2) \begin{cases} \dot{r} = r(r^2 - 1) \\ \dot{\theta} = 1 \end{cases}$$

(polar coord's)



Equi. pt.  $(0,0)$ , limit cycle  $r^2 = x_1^2 + x_2^2 = 1$  ( $\dot{r}=0$ )

$$0 < r(0) < 1 \Rightarrow \dot{r} < 0, \quad \lim_{t \rightarrow \infty} r(t) = 0$$

$$r(0) > 1 \Rightarrow \dot{r} > 0 \Rightarrow r(t) > 1 \text{ for } t \geq 0.$$

Domain of attr. of  $(0,0)$ :

$$\Omega_a = \{ (x_1, x_2) : x_1^2 + x_2^2 < 1 \}$$

Inv. domains:

$$\{x : 0 < |x| < 1\}, \{x : |x| > 1\}, \{0\}, \{x : |x| = 1\}, \text{ unions}$$

$$[ |x| < r, |x| > R; 0 < r < 1 < R; \text{ only } \underline{\text{pos. inv.}} ! ]$$

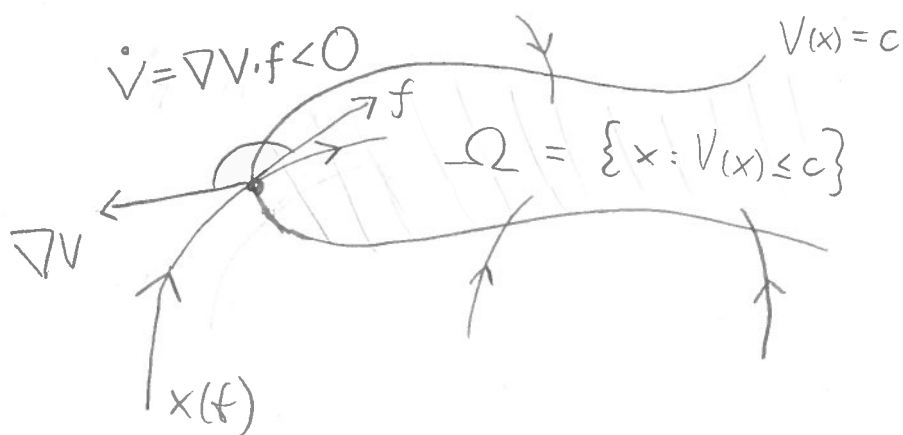
Obs. 1: Closed phase trajectories and equi. pt's are inv.

Lem. 1: Assume  $f \in C^1$ . If  $V \in C^1$  and

$$\nabla V(x) \neq 0 \quad \text{and} \quad \dot{V}(x) = \nabla V(x) \cdot f(x) \leq 0$$

for all  $x$  s.t.  $V(x) = c \in \mathbb{R}$ , then

$$\Omega = \{ x : V(x) \leq c \} \quad \text{is } \underline{\text{pos. inv.}}$$



"Pf. :="

Enough to chk. that  $V(\varphi(t; x)) \leq c$

for  $t \in (0, \varepsilon_x)$ ,  $\varepsilon_x > 0$ , and  $x$  s.f.  $V(x) = c$ .

(i.e. that  $\varphi(t; x)$  do not immediately exit  $V \leq c$ )

Let  $x$  s.f.  $V(x) = c$ .

1)  $\dot{V}(x) < 0 \Rightarrow V(\varphi(t; x)) < c$  for  $t \in (0, \varepsilon_x)$   
for small enough  $\varepsilon_x > 0$

2)  $\dot{V}(x) = 0$ :

Since  $f \in C^1$ ,  $\varphi(t; y)$  exists and are unique for  $\forall y$  near  $x$  and  $t$  near 0.

If  $\varphi(t; x)$  exits  $V \leq c$  immediately,

then by cont. dep. so must also  $\varphi(t; y)$  for all  $y$  near  $x$  s.t.  $V(y) = c$ .

By 1),  $\dot{V}(y) = 0$  for these  $y$  and hence

$V = c$  is part of a phase trajectory there.

But this trajectory crosses  $\varphi(t; x)$  and contradicts uniqueness, hence  $V(\varphi(t; x)) \leq c$  for  $t \in [0, \varepsilon_x)$ , for some  $\varepsilon_x \geq 0$   $\square$

Cor. 1: If  $f, V \in C^1$  and

$\nabla V(x) \neq 0$  and  $\dot{V}(x) = \nabla V(x) \cdot f(x) \geq 0$   
for all  $x$  s.t.  $V(x) = c$ , then

$\Omega = \{x : V(x) \geq c\}$  pos. inv.

[ $-V(x)$  satisfy Lem. 1]

Ex. 2: (cont.)

(2)  $\stackrel{\text{chk.}}{\Leftrightarrow} \begin{cases} \dot{x}_1 = -x_2 - (1 - x_1^2 - x_2^2)x_1 \\ \dot{x}_2 = x_1 - (1 - x_1^2 - x_2^2)x_2 \end{cases}$

$V(x_1, x_2) = \frac{1}{2}(x_1^2 + x_2^2) \Rightarrow \dot{V} = (x_1^2 + x_2^2)(x_1^2 + x_2^2 - 1)$

$x_1^2 + x_2^2 \leq c^2, c \leq 1$  pos. inv since  $\nabla V \neq 0, \dot{V} \leq 0$  on  $V = \frac{c^2}{2}$   
 $\text{---} \geq \text{---} \geq \text{---} \quad \text{---} \geq 0 \text{---}$

B. LaSalle's inv. principle

Thm. 1:

Assume:

- i)  $\Omega$  pos. inv., closed, bnd.,  $0 \in \Omega$
- ii)  $f(0) = 0, f$  Lop. in  $\Omega$

5.)

iii)  $V(x)$  weak L. func. on  $\Omega$

iv) there is no global sol'n  $x(t)$  of (1) s.t.

$$x(t) \in \Omega \setminus \{0\}, t \in \mathbb{R} \text{ and } V(x(t)) = c = \text{const.}$$

Then  $x=0$  is asympt. stab. and its domain of attraction contains  $\Omega$ .

Obs. 2:

i) Weak L-func. can give asympt. stab.!

ii) Thm. 1 gives info about domain of attr. of 0

iii)  $V$  strong L func.  $\Rightarrow \dot{V} < 0, x \neq 0 \Rightarrow$  iv) satisfied

Ex. 3: Van der Pol eq'n

$$(3) \quad \ddot{x} - \beta(x^2 - 1)\dot{x} + x = 0, \beta > 0$$

$$(4) \quad \begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = \beta(x_1^2 - 1)x_2 - x_1 \end{cases}$$

Only equi. pt. =  $(0, 0)$

$$\text{Energy} = E(\dot{x}, x) = \frac{1}{2} \dot{x}^2 + \frac{1}{2} x^2$$

$$[(3) \cdot \dot{x} \Leftrightarrow \frac{d}{dt} \underbrace{\left( \frac{1}{2} \dot{x}^2 + \frac{1}{2} x^2 \right)}_E = \beta(x^2 - 1)\dot{x}^2]$$

$V(x_1, x_2) = E(x_1, x_2)$  weak L-func. for  $|x_1| \leq 1$ :

6.)

i) - ii)  $V \in C^1$ ,  $V(0) = 0$ ,  $V > 0$  for  $x \neq 0$ ,  $|x| < 1$ ii)  $\dot{V}(x) = x_1 \dot{x}_1 + x_2 \dot{x}_2 = \beta(x_1^2 - 1)x_2^2 \leq 0$  for  $|x| \leq 1$  $\Omega = \{x : V(x) \leq \frac{1}{2}\}$  (closed, bnd) pos. inv.[by Lem. 1 since  $\nabla V(x) \neq 0$  and  $\dot{V} \leq 0$  on  $V = \frac{1}{2}$ ]Assume  $x(t)$  glob. sol'n s.t.  $V(x(t)) = \text{const.}$ 

$$\Rightarrow 0 = \dot{V}(x(t)) = \beta(x_1^2 - 1)x_2$$

$$\Rightarrow x_2 = 0 \text{ or } x_1 = \pm 1$$

Hence, if  $x_1(t_1) \neq \pm 1 \Rightarrow x_1(t) \neq \pm 1$  in  $(- \varepsilon + t_1, t_1 + \varepsilon)$   
 $\varepsilon$  small enough

$$\Rightarrow x_2(t) = 0 \text{ in } (- \varepsilon + t_1, t_1 + \varepsilon)$$

$$\stackrel{(4)}{\Rightarrow} \dot{x}_1(t) = 0 \text{ and } x(t) = \text{const. } (x_2 = 0, x_1 = \text{const.})$$

$$\Rightarrow (x_1, x_2) = (0, 0) \text{ (only equi. pt.)}$$

Similarly, if  $x_2(t_2) \neq 0 \Rightarrow x_1(t) = \pm 1$ 

$$\stackrel{(4)}{\Leftarrow} \Rightarrow x_2 = \dot{x}_1 = 0 \text{ in } (- \varepsilon + t_2, t_2 + \varepsilon)$$

$$\Rightarrow (x_1, x_2) = (0, 0)$$

Conclusion: i) - iv) of Thm. 1 hold

 $\Rightarrow (0, 0)$  asympt. stab. and

$$\{x : |x| \leq 1\} \subset \Omega_a$$

Obs. 3:

i)  $V(x) = \frac{1}{2}x_1^2 + ax_1x_2 + \frac{b}{2}x_2^2$  str. L-func. (4)

when e.g.  $a = \frac{b}{2} = \frac{2}{3}$  (J-S p. 363)

ii) Chk.: Linearization gives asympt. stab.  
but no info about  $\Omega_a$ .

Ex. 4:

$$\dot{x}_1 = -x_1(x_1^2 + x_2^2) + x_2$$

$$\dot{x}_2 = -x_2(x_1^2 + x_2^2) - x_1$$

Chk.:  $V = \frac{1}{2}(x_1^2 + x_2^2)$  str. L-func. ( $\dot{V} = -(x_1^2 + x_2^2)^2$ )

$$\Rightarrow B_R = \{x: V(x) \leq \frac{R^2}{2}\} \text{ pos. inv. (Lem. 1)}$$

Thm. 1 and Obs. 2

$\Rightarrow x=0$  asympt. stab. and  $B_R \subset \Omega_a$  for all  $R > 0$

Hence  $\Omega_a = \mathbb{R}^2$ ,  $x=0$  glob. asympt. stab. equi. pt.

C. Pf. of Thm. 1

1) Assume Thm. 1 wrong, then exists sol'n  $x(t)$

s.t.

$$x(t) \in \Omega, t \geq 0 \quad \text{and} \quad x(t) \not\rightarrow 0 \text{ as } t \rightarrow \infty.$$

2) Since  $\Omega \subset \mathbb{R}^n$  closed, bnd. all sequences in  $\Omega$  have conv. subsequences (Bolzano-Weierstrass)

Hence  $\{x(t_n)\}_n, t_n \rightarrow \infty$ , has subsequence s.t.

$$(\Delta) \quad x(t_n) \xrightarrow{n \rightarrow \infty} x_0 \in \Omega$$

By 1) we may assume  $x_0 \neq 0$ .

[If all conv. subsequences  $\rightarrow 0$ , then  $x(t) \rightarrow 0$  since  $\Omega$  bnd.]

3)  $\bar{x}(t) = \varphi(t; x_0)$  glob. sol'n in  $\Omega$ :  
( $\bar{x}(t)$  exists for  $t \in \mathbb{R}$  since  $f$  Lip.)

i)  $\Omega$  pos. inv.  $\Rightarrow \bar{x}(t) \in \Omega$  for  $t \geq 0$

ii)  $\varphi(t; x(t_{n+k}))$  def. for  $t \in [-t_n, 0], k \geq 0$

$$[\varphi(-t_n; x(t_n)) = \varphi(0; x(0)) = x(0)]$$

By cont. dep. of init. data and (i),

$$\varphi(t; x(t_{n+k})) \rightarrow \varphi(t; x_0) \text{ for } t \in [-t_n, 0]$$

Since  $\Omega$  closed,  $\varphi(t; x_0) \in \Omega$ , and

since  $t_n > 0$  arbitrarily big,  $\bar{x}(t)$  exists

for all  $t \leq 0$ .

4)  $V(\bar{x}(t)) = \text{const.}$ :

Let  $V(x_0) =: \alpha$ . Then  $\alpha > 0$  ( $x_0 \neq 0$ ) and

$$(\square) \quad \lim_{n \rightarrow \infty} V(x(t_n)) = \alpha \quad (V \text{ cont.} + (\delta))$$



Let  $t_{n_1} \leq t_n + s \leq t_{n_2}$  <sup>(s ∈ ℝ)</sup> then

$$V(x(t_{n_1})) \geq V(x(t_n + s)) \geq V(t_{n_2}) \quad (\dot{V} \leq 0)$$

and  $V(x(t_n + s)) \xrightarrow[n \rightarrow \infty]{} V(x_0)$  by (B).

But  $x(t_n + s) = \varphi(s; x(t_n)) \rightarrow \varphi(s; x_0) = \bar{x}(s)$

$V$  cont.

$$\Rightarrow V(x(t_n + s)) \rightarrow V(\bar{x}(s))$$

Hence  $V(\bar{x}(t)) = \alpha > 0, t \in \mathbb{R}$ .

3 and 4 contradicts (v), so assumption

in 1 is wrong and Thm. 1 holds  $\square$