Norwegian University of Science and Technology Department of Mathematical Sciences Page 1 of 3



Contact during the exam: Espen R. Jakobsen, tlf. 91 61 87 27.

Exam in TMA4165 Differential equations and dynamical systems

English Thursday May 30. 2013 Time: 15:00 - 19:00

Permitted aids (Code D): Simple calculator (HP 30S or Citizen SR-270X). Grades: 20. juni 2013.

All answers should be justified.

Problem 1 Given the system of differential equations:

$$\begin{cases} \dot{x} = (2 - x^2 - y^2)x\\ \dot{y} = x - y. \end{cases}$$

a) Find and classify all equilibrium points of the system.

b) Sketch the phase diagram of the system, with orientations.

Problem 2 Write up a system of differential equations with Hamiltonian

$$H(x,y) = \cos x \cos y.$$

Show that (0,0) and $(\frac{\pi}{2},\frac{\pi}{2})$ are equilibrium points for the system.

Classify the equilibrium points (0,0) and $(\frac{\pi}{2},\frac{\pi}{2})$.

Problem 3 Find the general solution of the system

$$\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -4 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}.$$

Problem 4 Compute the index of the origin for the system

$$\begin{cases} \dot{x} = x^2 - y^2 \\ \dot{y} = -2xy. \end{cases}$$

Problem 5 Determine if all the solutions of the following systems are stable, asymptotically stable, or unstable.

(i)
$$\begin{bmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{bmatrix} = \begin{bmatrix} 0 & -10 & 2 \\ 10 & 0 & 1 \\ 0 & 0 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

(ii) $\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} -5 & 0 \\ 10 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$
(iii) $\begin{bmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{bmatrix} = \begin{bmatrix} -3 & 2 & \frac{1}{1+t^2} \\ 0 & -7 & 0 \\ e^{-t} & 0 & -7 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

Problem 6 Let $A \in \mathbb{R}^{n \times n}$, $b \in \mathbb{R}^n$, and $x : \mathbb{R} \to \mathbb{R}^n$ be a solution of

$$\dot{x}(t) = Ax(t) + b.$$

Define what it means for x(t) to be stable (Liapunov stable).

Show that all solutions of the equation are stable if there is a fundamental matrix Φ : $\mathbb{R} \to \mathbb{R}^{n \times n}$ for $\dot{x} = Ax$ such that

$$\|\Phi(t)\| \le C < \infty \quad \text{for all} \quad t \ge 0.$$

Problem 7 Show that (0,0) is an asymptotically stable equilibrium point for the system

$$\begin{cases} \dot{x} = 2(x^2 + 2y^2)y - x^3\\ \dot{y} = -(x^2 + 2y^2)x - e^x y. \end{cases}$$

Show that the domain of attraction of (0,0) is all of \mathbb{R}^2 .

Problem 8 Determine whether or not the system has non-constant periodic solutions.

$$\begin{cases} \dot{x} = -y + x \sin(3x^2 + 2y^2) \\ \dot{y} = x + y \sin(3x^2 + 2y^2). \end{cases}$$

Problem 9 The velocity v of a relativistic electron in a constant electric field in one dimension satisfies

$$\begin{cases} \dot{v} = (1 - \epsilon^2 v^2)^{\frac{3}{2}}, \\ v(0) = v_0, \end{cases}$$

where $|\epsilon| < 1$ and $|v_0| < 1$.

Show, using a direct argument, that the initial value problem cannot have more than one solution.

Show that the solution exists for |t| < 1.

Hint: Show that the domain $|v| \leq \frac{1}{\epsilon}$ is invariant.