

LAX-FRIEDRICH SCHEME

The scheme presented in [1] relies on a *Riemann solver*. Such solver is meant to give an approximation of the numerical flux at $x = 0$ for the solution of the Riemann problem defined by

$$(0.1) \quad U_t + F(U)_x = 0$$

with initial condition

$$(0.2) \quad U(0, x) = \begin{cases} U_- & \text{if } x < 0 \\ U_+ & \text{if } x > 0. \end{cases}$$

Here U is a vector in \mathbb{R}^n and $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ a function. It can be proven that, for such solution, the value of the flux at $x = 0$, that is $F(U(t, 0))$, is constant in time. It is usually difficult to compute an exact solution of the Riemann problem. Therefore, it is common to use an approximate solution and we denote by $\mathcal{F}(U_-, U_+)$ a numerical approximation of $F(U(t, 0))$. Still approximate solutions have to be chosen with care in order to get the right physical solution. A simple choice is the Lax-Friedrichs flux, which is given by

$$(0.3) \quad \mathcal{F}(U_-, U_+) = \frac{1}{2\lambda}(U_- - U_+) + \frac{1}{2}(F(U_-) + F(U_+))$$

where

$$\lambda = \frac{\Delta t}{\Delta x}.$$

The Lax-Friedrichs is very *dissipative* and sharp fronts will be rapidly smeared out. Small discretization step will compensate for that. You should then be aware of the Courant-Lax-Friedrichs condition. To learn more on that see [2] or, even better, take the course [Nonlinear Partial Differential Equations](#) at NTNU!

REFERENCES

- [1] Emmanuel Audusse et al. “A fast and stable well-balanced scheme with hydrostatic reconstruction for shallow water flows”. In: *SIAM Journal on Scientific Computing* 25.6 (2004), pages 2050–2065.
- [2] Helge Holden and Nils H Risebro. *Front tracking for hyperbolic conservation laws*. Volume 152. Springer, 2013.