

# Dimensional analysis

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# Exercise classes

- Current favorite (at time of preparing the slides):
  - ▶ Wednesday 12–13 or 13–14.
- Try to move the exercises to one of these times (if available room can be found).
- Try to find a time slot for my office hours that particularly suits those that cannot attend the exercise class.
- Please fill out the doodle poll **today**.

# Dimensional analysis

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Swinging pendulum — relevant quantities:

- Frequency  $\omega$ , dimension  $[\omega] = 1/s$ .
- Length  $L$ , dimension  $[L] = m$ .
- Mass  $m$ , dimension  $[m] = kg$ .
- Gravitational acceleration  $g$ , dimension  $[g] = m/s^2$ .
- Initial angle  $\vartheta_0$ , dimension  $[\vartheta_0] = 1$  (dimensionless!).

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**Physical relations can be rewritten as relations between dimensionless combinations.**

- Identify relevant physical quantities  $R_1, \dots, R_m$ .
- Construct the dimension matrix  $A \in \mathbb{R}^{n \times m}$  and its rank  $r$ .

# Dimensional analysis

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Swinging pendulum — dimension matrix:

	$\omega$	$L$	$m$	$g$	$\vartheta_0$
kg	0	0	1	0	0
m	0	1	0	1	0
s	-1	0	0	-2	0

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- Identify relevant physical quantities  $R_1, \dots, R_m$ .
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- Select  $r$  **core variables** and find  $m - r$  dimensionless combinations  $\Pi_1, \dots, \Pi_{m-r}$ .



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Can choose core variables  $L$ ,  $m$ ,  $g$ , and obtain

$$\Pi_1 = \frac{\omega}{L^? m^? g^?} \stackrel{!}{=} \frac{\omega L^{1/2}}{g^{1/2}},$$

$$\Pi_2 = \frac{\vartheta_0}{L^? m^? g^?} \stackrel{!}{=} \vartheta_0.$$

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- Deduce ( $\Pi$ -theorem) relation of the form

$$\Psi(\Pi_1, \dots, \Pi_{m-r}) = 0.$$

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Swinging pendulum — defining relation:

$$\Psi(\Pi_1, \Pi_2) = \Psi\left(\omega\sqrt{\frac{L}{g}}, \vartheta_0\right) = 0.$$

- Argumentation shows that mass  $m$  of the pendulum is irrelevant.
- Physical argumentation: frequency depends uniquely on  $L$ ,  $g$ ,  $\vartheta_0$ .  
Deduce therefore relation

$$\omega = \sqrt{\frac{g}{L}}\tilde{\Psi}(\vartheta_0).$$

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- Find  $\Psi$  if possible. . .

# Dimensional analysis — model modifications

What happens if we add friction to the model?

- Cannot talk about frequency, as the motion won't be periodic. But still could say:  $\omega$  ... inverse of time to the first local maximum.
- Friction is complicated — simplest model: friction force depends linearly on the velocity.
- Obtain friction force of the form

$$F_f = kv$$

with:

- ▶  $v$  ... velocity of the (weight of the) pendulum.
- ▶  $k$  ... friction constant depending e.g. on medium, shape of the pendulum, ...
- Dimensions:

$$[k] = \frac{[F]}{[v]} = \frac{kg\ m}{s^2} \cdot \frac{s}{m} = \frac{kg}{s}.$$

## Dimensional analysis — model modifications II

Obtain new (enlarged) dimension matrix:

	$\omega$	$L$	$m$	$g$	$\vartheta_0$	$k$
kg	0	0	1	0	0	1
m	0	1	0	1	0	0
s	-1	0	0	-2	0	-1

and dimensionless variables

$$\Pi_1 = \omega \sqrt{\frac{L}{g}}, \quad \Pi_2 = \vartheta_0, \quad \Pi_3 = \frac{k}{m} \sqrt{\frac{L}{g}}.$$

Obtain the relation:

$$\omega = \sqrt{\frac{g}{L}} \Psi\left(\vartheta_0, \frac{k}{m} \sqrt{\frac{L}{g}}\right).$$