



1 ( $\approx$ Exercise 6.8 in Saad.)

- a) Compute the matrices  $V_m, \tilde{H}_m, m = 1, \dots, 5$  resulting from the application of Arnoldi process to

$$A = \begin{pmatrix} & & & & 1 \\ & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & 1 & \\ & & & & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad \text{and} \quad x_0 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

- b) Describe in detail the QR-factorization of  $\tilde{H}_m, m = 1, \dots, 5$ , using Givens rotations.  
c) Compute the GMRES iterates  $y_m, x_m, m = 1, \dots, m$  (when possible).

2 (Saad, Exercise 6.4) Consider a variant of the GMRES algorithm in which the Arnoldi process starts with  $v_1 = Av_0 / \|Av_0\|_2$ , where  $v_0 = r_0$ . The Arnoldi process is performed the same way as before to build an orthonormal system  $v_1, v_2, \dots, v_{m-1}$ . Now the approximate solution is expressed in the basis  $\{v_0, v_1, \dots, v_{m-1}\}$ .

- a) Show that the least-squares problem that must be solved to obtain the approximate solution is now triangular instead of Hessenberg.  
b) Show that the residual vector  $r_m$  is orthogonal to  $v_1, v_2, \dots, v_m$ .  
c) Find a formula that computes the residual norm (without computing the approximate solution) and write the complete algorithm.

3 Assume that a real matrix  $A$  is anti-symmetric, that is,  $A^T = -A$ . Explain the structure of the Hessenberg matrix  $H_m$  resulting from Arnoldi process in this case. Explain how this structure can be utilized for performing Arnoldi process efficiently in this case.

4 Show that both CG and GMRES are scaling independent. That is, when applied to a system  $(\delta A)x = \delta b$  for some  $\delta \in \mathbb{R} \setminus \{0\}$  ( $\delta > 0$  in the case of CG) they produce exactly the same sequence of iterates in exact arithmetics. (Of course since the residual vectors will be scaled by  $\delta$  this may affect stopping criteria of the methods.)