

## Simulation from discrete distributions

- ▶ Let  $x$  be a stochastic variable so that  $x \in \{x_1, \dots, x_k\}$ , and

$$P(x = x_i) = p_i \quad \text{where} \quad \sum_{i=1}^k p_i = 1$$

- ▶ Define  $F_i = \sum_{j=1}^i p_j$  for  $i = 0, 1, \dots, k$
- ▶ General simulation algorithm:

```
u ~ U[0, 1]
for i = 1, 2, ..., k do
  if u ∈ (Fi-1, Fi] then
    x = xi
  end if
end for
```

- ▶ Note:
  - ▶ can be used for any discrete distribution, but can be inefficient
  - ▶ more efficient search algorithm can make the algorithm faster
  - ▶ specialised algorithm for specific distributions: binomial, negative binomial, poisson

## Simulation from continuous distributions

- ▶ Probability integral transform (inversion method)
- ▶ Let  $x$  have density  $f(x)$ ,  $x \in \mathbf{R}$ ,  $F(x) = \int_{-\infty}^x f(z)dz$
- ▶ General simulation algorithm:

$u \sim U[0, 1]$   
 $x = F^{-1}(u)$   
return  $x$

- ▶ Note:
  - ▶ can only be used when we can find a formula for  $F^{-1}(u)$
  - ▶ specialised algorithms for specific distributions: gamma
  - ▶ easy to handle scale and location parameters

## Bivariate transformation formula

- ▶ Result: Assume

$$(x_1, x_2) \sim f_x(x_1, x_2) \quad (\text{density})$$

and

$$\begin{aligned}(y_1, y_2) &= g(x_1, x_2) \\ &\Downarrow \\ (x_1, x_2) &= g^{-1}(y_1, y_2).\end{aligned}$$

Then

$$f_y(y_1, y_2) = f_x(g^{-1}(y_1, y_2)) \cdot |J|,$$

where

$$J = \begin{vmatrix} \frac{\partial x_1}{\partial y_1} & \frac{\partial x_2}{\partial y_1} \\ \frac{\partial x_1}{\partial y_2} & \frac{\partial x_2}{\partial y_2} \end{vmatrix}$$

- ▶ Thus, if we are interested in a density  $f_y(y_1, y_2)$  we need to find a density  $f_x(x_1, x_2)$  and a one-to-one transformation  $(y_1, y_2) = g(x_1, x_2)$  so that the above result holds true

## Example: Standard normal (Box-Muller, 1958)

- ▶ Assume  $x_1$  and  $x_2$  independent and

$$x_1 \sim U[0, 2\pi] \quad , \quad x_2 \sim \text{Exp}\left(\frac{1}{2}\right).$$

- ▶ Thus,

$$f_x(x_1, x_2) = \frac{1}{2\pi} \cdot \frac{1}{2} e^{-\frac{1}{2}x_2} \quad \text{for } x_1 \in [0, 2\pi], x_2 > 0.$$

- ▶ Define

$$\begin{aligned} y_1 &= \sqrt{x_2} \cos x_1 & \text{and} & & y_2 &= \sqrt{x_2} \sin x_1 \\ & & & & \Updownarrow & \\ x_1 &= \tan^{-1}\left(\frac{y_2}{y_1}\right) & \text{and} & & x_2 &= y_1^2 + y_2^2 \end{aligned}$$