

Introduction to Bayesian statistics

- ▶ Example (Thomas Bayes, 1763):
 - ▶ A billiard ball is dropped on the interval $[0, 1]$
 - ▶ it stops at p
 - ▶ assume p is uniformly distributed on $[0, 1]$
 - ▶ Drop the billiard ball n new times
 - ▶ record $y_i = 1$ if ball stops to the left of p
 - ▶ $y_i = 0$ otherwise
 - ▶ set $x = \sum_{i=1}^n y_i$

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- ▶ want to estimate p from observed x
- ▶ standard estimator for p in binomial distr.:

$$\hat{p} = \frac{X}{n}$$

- ▶ but we know $p \sim \text{Uniform}[0, 1]$,

$$f(p) = \begin{cases} 1 & \text{for } p \in [0, 1], \\ 0 & \text{otherwise} \end{cases}$$

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- ▶ Thus

$$\begin{aligned} f(p|x) &= \frac{f(p, x)}{P(X = x)} = \frac{f(p)P(X = x|p)}{\int_0^1 P(X = x|\tilde{p})f(\tilde{p})d\tilde{p}} \\ &= \frac{p^x(1-p)^{n-x}}{\int_0^1 \tilde{p}^x(1-\tilde{p})^{n-x}d\tilde{p}} = \frac{p^x(1-p)^{n-x}}{B(x+1, n-x+1)} \end{aligned}$$

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- ▶ This is a beta-distribution, $\mathcal{B}(x+1, n-x+1)$, with

$$E[p|x] = \frac{x+1}{n+2}$$

- ▶ A natural estimator for p

$$\hat{p} = \frac{X+1}{n+2}$$

Bayesian statistics

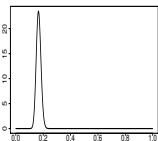
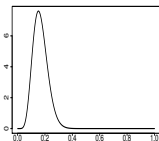
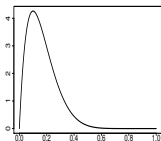
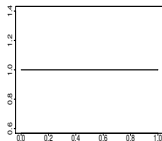
- ▶ In previous example: p is a stochastic variable because it is the result of a stochastic experiment
- ▶ Bayesian modelling: consider parameters as stochastic variables also when their value is not the result of a stochastic experiment

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- ▶ Another (toy) example:
 - ▶ I have a dice, let p : probability of getting a six
 - ▶ Consider p as a stochastic variable, you don't know it is a proper dice
 - ▶ what distribution would you assign to p ?

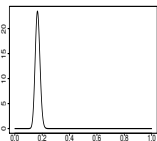
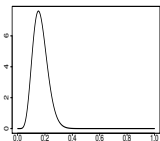
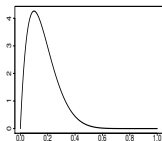
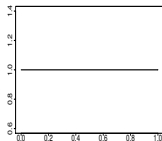
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- ▶ we roll the dice n times, let x : number of sixes

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- ▶ Assume $p \sim \mathcal{B}(\alpha, \beta)$:

$$f(p) = \frac{1}{\mathcal{B}(\alpha, \beta)} p^{\alpha-1} (1-p)^{\beta-1}$$

- ▶ This gives:

$$f(p|x) = \frac{f(p, x)}{P(X = x)}$$

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- ▶ Thus $p|x \sim \mathcal{B}(\alpha + x, \beta + n - x)$, so

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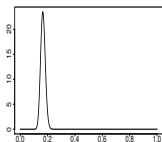
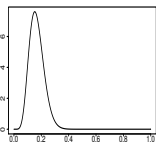
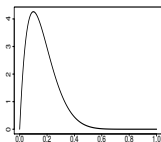
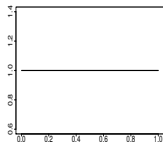
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- ▶ Observed $n = 100$, $x = 26$:

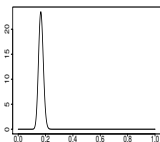
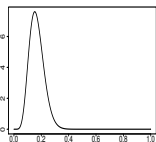
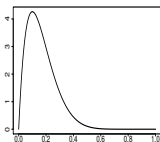
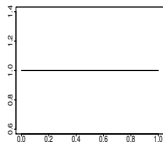
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- ▶ Before observing the value of x , $f(p)$:

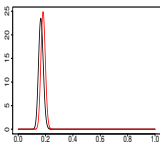
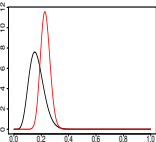
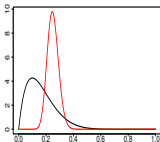
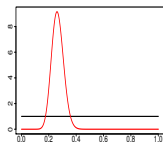


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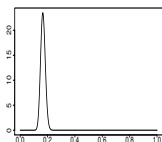
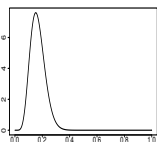
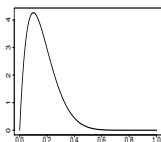
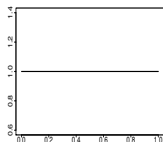


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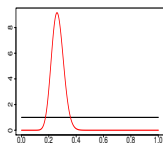


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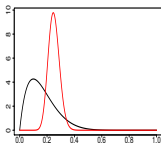
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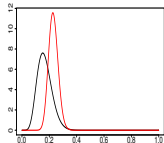
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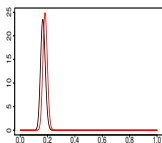
$$E[p|x] = 0.265$$



$$E[p|x] = 0.255$$



$$E[p|x] = 0.230$$



$$E[p|x] = 0.183$$

Interpretation of probability

- ▶ Frequentist (objective): Probability of event A is

$$P(A) = \lim_{n \rightarrow \infty} \frac{m}{n}$$

where m : # times A occurs in n identical and independent trials

- ▶ Bayesian (subjective): Probability of event A , $P(A)$, is a measure of someone's degree of belief in the occurrence of A .
 - ▶ different persons may have different $P(A)$

Prior and posterior distribution

- ▶ Prior distribution: $f(\theta)$
 - ▶ a measure of our belief about the value of θ before we have observed the data, based on prior information/experience
- ▶ Observation and Likelihood: $f(x|\theta)$
 - ▶ observed value x , and its probability distribution given θ
- ▶ Posterior distribution: $f(\theta|x)$
 - ▶ a measure of our belief about the of value of θ after we have observed the data x , based on prior information/experience *and* the observed data x
 - ▶ Bayes theorem

$$f(\theta|x) = \frac{f(\theta, x)}{f(x)} \propto f(\theta, x) = f(\theta)f(x|\theta)$$

Conjugate priors

- ▶ In examples: posteriors are all available on closed form
 - ▶ this is because we have used *conjugate* priors
- ▶ binomial conjugate prior
 - ▶ $x|p \sim \text{binomial}(n, p)$
 - ▶ $p \sim \text{beta}(\alpha, \beta)$
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- ▶ normal (mean) conjugate prior
 - ▶ $x_1, \dots, x_n | \mu \sim N(\mu, \sigma_0^2)$
 - ▶ $\mu \sim N(\mu_0, \tau^2)$
 - ▶ $\mu | x_1, \dots, x_n \sim N(\cdot, \cdot)$

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- ▶ Conjugate priors makes analytical evaluations easier
 - ▶ and may make sampling from the posterior easier ...

Hierarchical Bayesian modeling — a simple example

- ▶ A simple example (from George et al., 1993)
 - ▶ Analysis of 10 power plant pumps
 - ▶ x_i, t_i : number of failures for pump i and length of operation time on that pump (in 1000 hours)
 - ▶ Modelling:

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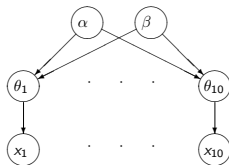
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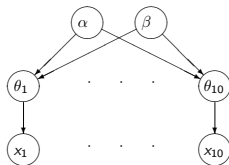


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- ▶ graphical model:



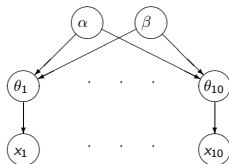
- ▶ observed: x_1, \dots, x_n

Hierarchical Bayesian modeling — a simple example

- ▶ A simple example (from George et al., 1993)
 - ▶ Analysis of 10 power plant pumps
 - ▶ x_i, t_i : number of failures for pump i and length of operation time on that pump (in 1000 hours)
 - ▶ Modelling:
 - ▶ $x_i|\theta_i \sim \text{Poisson}(\theta_i; t_i)$
 - ▶ conjugate prior for θ_i : $\theta_i|\alpha, \beta \sim \text{Gamma}(\alpha, \beta)$
 - ▶ hyper-prior distribution on α and β

$$\alpha \sim \text{Exp}(1.0) , \beta \sim \text{Gamma}(0.1, 1.0)$$

- ▶ graphical model:



- ▶ observed: x_1, \dots, x_n
- ▶ posterior distribution of interest:

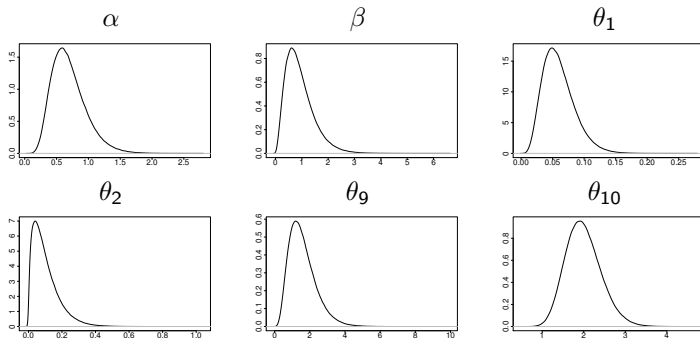
$$f(\alpha, \beta, \theta_1, \dots, \theta_{10} | x_1, \dots, x_{10})$$

Hierarchical Bayesian modeling — a simple example

► Data:

Pump	1	2	3	4	5	6	7	8	9	10
t_i	94.3	15.7	62.9	126	5.24	31.4	1.05	1.05	2.1	10.5
x_i	5	1	5	14	3	19	1	1	4	22

► Posterior density plots:



Hierarchical Bayesian modeling — a simple example

- ▶ Data:

Pump	1	2	3	4	5	6	7	8	9	10
t_i	94.3	15.7	62.9	126	5.24	31.4	1.05	1.05	2.1	10.5
x_i	5	1	5	14	3	19	1	1	4	22

- ▶ Posterior mean for θ_i compared to x_i/t_i

parameter	posterior mean	x_i/t_i
θ_1	0.0598	0.0530
θ_2	0.1017	0.0636
θ_3	0.0892	0.0795
θ_4	0.1157	0.1111
θ_5	0.6011	0.5725
θ_6	0.6095	0.6051
θ_7	0.8910	0.9524
θ_8	0.8928	0.9524
θ_9	1.5867	1.9047
θ_{10}	1.9901	2.0952

