

Optimisation on Lie Groups Applied to Optical Interference Filters

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- 1 Motivation
 - Picture Tour

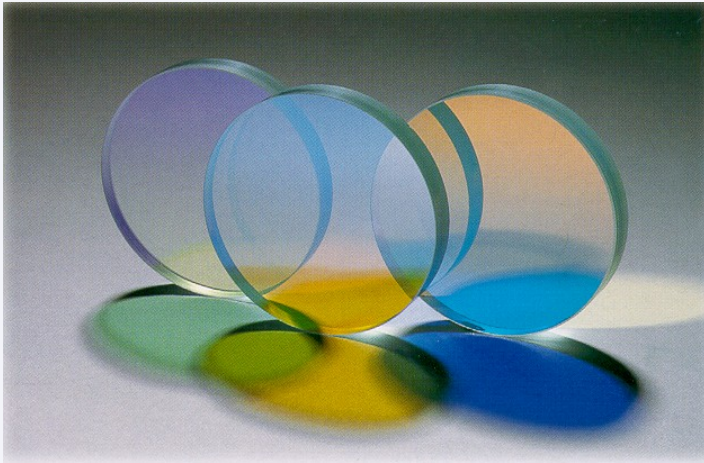
- 1 Motivation
 - Picture Tour
- 2 The Physical Model
 - Overview
 - Derivation of the Model Equation

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- 4 Future Work

Some Pretty Pictures

Optical Interference Filters



Source: Wikipedia

Some Pretty Pictures

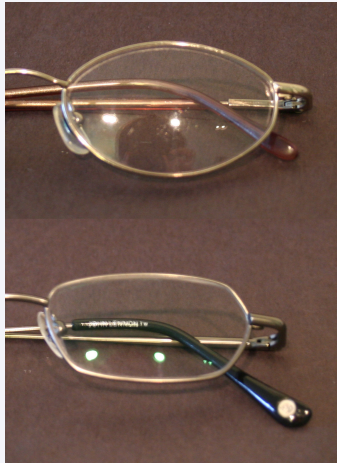
Diesel Rainbow



Source: Wikipedia

Some Pretty Pictures

Anti-Reflective Coating

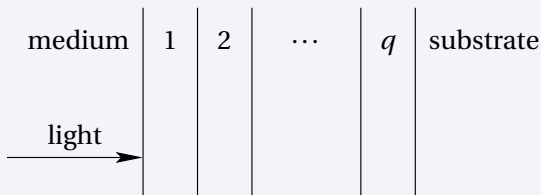


Source: Wikipedia

Layered Structure



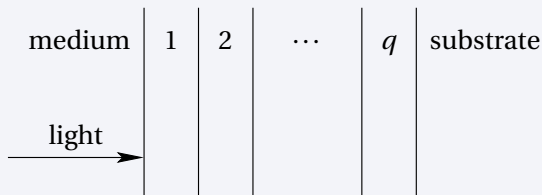
An optical interference filter is layered.



Layered Structure



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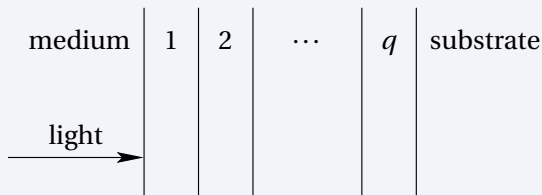


- Each layer corresponds to a matrix in $SL(2, \mathbb{C})$.

Layered Structure



An optical interference filter is layered.



- Each layer corresponds to a matrix in $SL(2, \mathbb{C})$.
- The whole stack is characterised by the product of these matrices.

Goal

Design an optimal one-layer anti-reflective filter.

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Assumptions

- The electromagnetic parameters (the conductivity σ , the permittivity ϵ and the permeability μ), and the layer thickness d are constant within each layer.

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Design an optimal one-layer anti-reflective filter.

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- The light propagates in the x -direction only (1D), perpendicularly to the filter layer interfaces.
- The light is monochromatic.

Derivation of the Electromagnetic Wave Equation



We start from Maxwell's equations

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t},$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t},$$

$$\nabla \cdot \mathbf{D} = \rho,$$

$$\nabla \cdot \mathbf{B} = 0,$$

together with the relations

$$\mathbf{J} = \sigma \mathbf{E},$$

$$\mathbf{D} = \epsilon \mathbf{E} = \epsilon_0 \epsilon_r \mathbf{E},$$

$$\mathbf{B} = \mu \mathbf{H} = \mu_0 \mu_r \mathbf{H}.$$

Derivation of the Electromagnetic Wave Equation



We eliminate **J**, **B** and **D**,

$$\nabla \times \mathbf{H} = \sigma \mathbf{E} + \epsilon \frac{\partial \mathbf{E}}{\partial t},$$

$$\nabla \times \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial t}.$$

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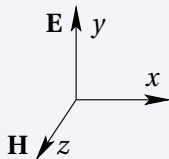
$$\nabla \times \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial t}.$$

This gives us (under the previous assumptions)

$$-\nabla \times (\nabla \times \mathbf{E}) = \nabla^2 \mathbf{E} = \sigma \mu \frac{\partial \mathbf{E}}{\partial t} + \epsilon \mu \frac{\partial^2 \mathbf{E}}{\partial t^2},$$

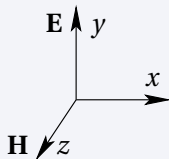
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Sinusoidal Wave Solution



$$\mathbf{E} = E\hat{\mathbf{y}} = \mathcal{E}e^{i\omega(t-x/v)}\hat{\mathbf{y}}, \quad \mathbf{H} = H\hat{\mathbf{z}} = \mathcal{H}e^{i\omega(t-x/v)}\hat{\mathbf{z}}$$

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Dispersion relation

Sinusoidal solution if

$$\frac{\omega^2}{v^2} = \epsilon\mu\omega^2 - i\sigma\mu\omega$$

Sinusoidal Wave Solution



In vacuum, $\sigma = 0$, $\epsilon = \epsilon_0$, $\mu = \mu_0$ and $v = c$. We then get

$$c^2 = \frac{1}{\epsilon_0 \mu_0}.$$

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Complex Refractive Index

$$N \stackrel{\text{def}}{=} n - ik \stackrel{\text{def}}{=} \frac{c}{v}$$

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Letting $\lambda_0 \stackrel{\text{def}}{=} 2\pi c/\omega$,

$$\frac{E}{\mathcal{E}} = \frac{H}{\mathcal{H}} = e^{i(\omega t - (2\pi N/\lambda_0)x)} = e^{-(2\pi k/\lambda_0)x} e^{i(\omega t - (2\pi n/\lambda_0)x)}.$$

Relationship Between the Electric and Magnetic Fields



$$\nabla \times \mathbf{H} = \sigma \mathbf{E} + \epsilon \frac{\partial \mathbf{E}}{\partial t}, \quad \mathbf{E} = E \hat{\mathbf{y}} = \mathcal{E} e^{i\omega(t-x/v)} \hat{\mathbf{y}}, \quad \mathbf{H} = H \hat{\mathbf{z}} = \mathcal{H} e^{i\omega(t-x/v)} \hat{\mathbf{z}}$$

Relationship Between the Electric and Magnetic Fields □

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$$-\frac{\partial H}{\partial x} \hat{\mathbf{y}} = (\sigma + i\epsilon\omega) E \hat{\mathbf{y}}$$

$$i \frac{\omega}{v} H = i \frac{\omega N^2 \epsilon_0}{\mu_r} E$$

$$H = \frac{N}{c\mu} E$$

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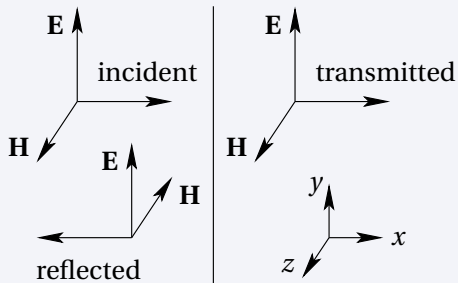
$$i \frac{\omega}{v} H = i \frac{\omega N^2 \epsilon_0}{\mu_r} E$$

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Characteristic Optical Admittance

$$y \stackrel{\text{def}}{=} \frac{N}{c\mu} \implies H = yE$$

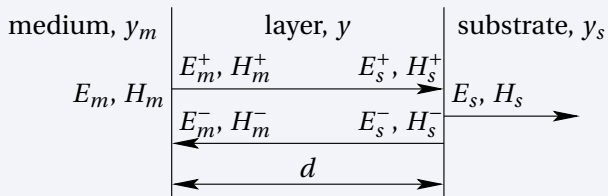
What Happens at an Interface?



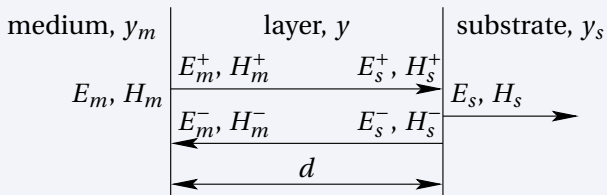
$$E_t = E_i + E_r,$$

$$H_t = H_i - H_r.$$

Interference



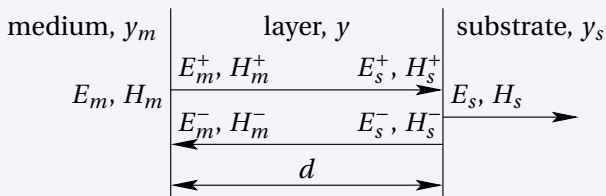
Interference



$$\delta \stackrel{\text{def}}{=} \frac{2\pi Nd}{\lambda_0}$$

$$E_m^+ = E_s^+ e^{i\delta}, \quad E_m^- = E_s^- e^{-i\delta}.$$

Interference



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$$E_m^+ = E_s^+ e^{i\delta}, \quad E_m^- = E_s^- e^{-i\delta}.$$

$$\begin{bmatrix} E_m \\ H_m \end{bmatrix} = \begin{bmatrix} \cos \delta & (i \sin \delta) / y \\ i y \sin \delta & \cos \delta \end{bmatrix} \begin{bmatrix} E_s \\ H_s \end{bmatrix}$$

Generalisation to q Layers



$$\begin{bmatrix} E_m \\ H_m \end{bmatrix} = \left(\prod_{r=1}^q \begin{bmatrix} \cos \delta_r & (i \sin \delta_r) / y_r \\ iy_r \sin \delta_r & \cos \delta_r \end{bmatrix} \right) \begin{bmatrix} E_s \\ H_s \end{bmatrix}$$

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Normalised Version

$$\begin{bmatrix} B \\ C \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} E_m / E_s \\ H_m / E_s \end{bmatrix} = \left(\prod_{r=1}^q \begin{bmatrix} \cos \delta_r & (i \sin \delta_r) / y_r \\ iy_r \sin \delta_r & \cos \delta_r \end{bmatrix} \right) \begin{bmatrix} 1 \\ y_s \end{bmatrix}$$

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Reflectance

$$R = \left| \frac{y_m B - C}{y_m B + C} \right|^2$$

Parametrisation



$$R: \mathrm{SL}(2, \mathbb{C}) \rightarrow \mathbb{R}$$

Parametrisation



$$R: \mathrm{SL}(2, \mathbb{C}) \rightarrow \mathbb{R}$$

Parametrisation in the Lie algebra $\mathfrak{sl}(2, \mathbb{C})$ which consists of trace-free matrices.

Basis of $\mathfrak{sl}(2, \mathbb{C})$

$$E_1 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \quad E_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad E_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

Parametrisation



Suppose $V \in \mathfrak{sl}(2, \mathbb{C})$ and λ is an eigenvalue of V . Then

$$e^V = I \cosh \lambda + V \frac{\sinh \lambda}{\lambda} \in \mathrm{SL}(2, \mathbb{C}).$$

Parametrisation



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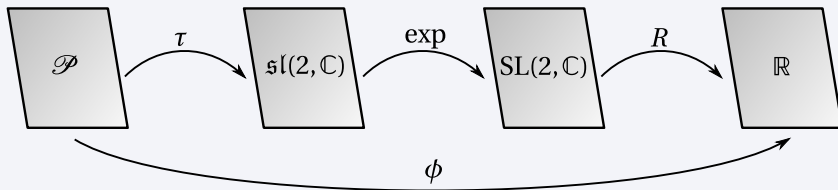
All physically realisable matrices in $\mathfrak{sl}(2, \mathbb{C})$ are matrices of the form

$$V = -\lambda \begin{bmatrix} 0 & 1/y \\ y & 0 \end{bmatrix},$$

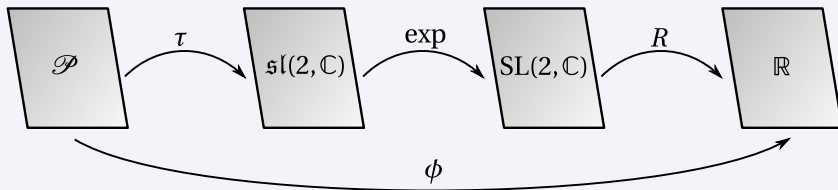
or by using the basis,

$$= -\frac{\lambda}{y} E_2 - \lambda y E_3.$$

Parametrisation



Parametrisation



BFGS-minimisation of

$$\phi = R \circ \exp \circ \tau.$$



- Multiple layers



- Multiple layers
- Consider the whole spectrum



- Multiple layers
- Consider the whole spectrum
- Continuously varying parameters



- Multiple layers
- Consider the whole spectrum
- Continuously varying parameters
- Other optimisation algorithms

Further Reading



H. Angus Macleod.

Thin-Film Optical Filters, 3rd ed.

Institute of Physics Publishing, 2001.



Stéphane Larouche and Ludvik Martinu.

OpenFilters: Open-Source Software for the Design, Optimization, and Synthesis of Optical Filters.

Applied Optics 47, 219–230, 2008.