

# Exercise 1 - Solutions

## Time Series Models

### 2.1

$y_t$	-1	1
$P(Y_t = y_t)$	$\frac{1}{2}$	$\frac{1}{2}$

$$E[Y_t] = 0 ; \quad Var[Y_t] = 1$$

$$Z_t = \begin{cases} Y_t & t \text{ even} \\ Y_{t-1} & t \text{ odd} \end{cases}$$

a)

$$P(Z_t \leq z) = P(Y_t \leq z), \quad t \text{ even}$$

$$P(Z_t \leq z) = P(Y_{t-1} \leq z) = P(Y_t \leq z), \quad t \text{ odd} \Rightarrow \text{first order stationary}$$

b)

$$E[Z_t Z_{t-1}] = \begin{cases} E[Y_t Y_{t-2}] = 0, & t \text{ even} \\ E[Y_{t-1}^2] = 1, & t \text{ odd} \end{cases} \Rightarrow \text{is not second order stationary}$$

### 2.2

$$Z_t = U \sin(2\pi t) + V \cos(2\pi t)$$

$$E[U] = E[V] = 0$$

$$Var[U] = Var[V] = 1$$

$t$  is integer  $\Rightarrow Z_t = V$  ;  $\forall t \Rightarrow Z_t$  is strictly stationary

$$E[Z_t, Z_{t-k}] = E[V^2] = 1 \Rightarrow Z_t \text{ is covariance stationary}$$

### 2.3

$$Z_t = A \sin(\omega t + \theta)$$

$$\Rightarrow E[Z_t] = E[A] E[\sin(\omega t + \theta)]$$

$$E[Z_t Z_{t+k}] = E[A^2] E[\sin(\omega t + \theta) \sin(\omega(t+k) + \theta)] =$$

$$= \frac{E[A^2]}{2} (E[\cos(\omega t)] - E[\cos(2\omega t + \omega k + 2\theta)])$$

a)

A constant,  $\theta \sim U[0, 2\pi]$

$$\Rightarrow E[Z_t] = 0, \gamma_k = \frac{A^2 \cos(\omega k)}{2} = \frac{A^2}{2} \text{ for } \omega = 2\pi \Rightarrow Z_t \text{ is covariance stationary}$$

b)

$\theta$  constant,  $E[A] = 0, \text{Var}[A] = 1$

$$\Rightarrow E[Z_t] = 0, \gamma_k = \frac{1}{2} [\cos(\omega k) - \cos(\omega(2t - k) + 2\theta)] =$$

$$\omega = 2\pi \Rightarrow \gamma_k = \frac{1}{2} [1 - \cos(2\theta)] = \sin^2(\theta) \Rightarrow Z_t \text{ is covariance stationary}$$

c)

$Z_t = (-1)^t A, E[A] = 0, \text{Var}[A] = 1$

$$E[Z_t] = (-1)^t E[A] = 0$$

$$E[Z_t Z_{t+k}] = E[A^2] (-1)^{2t+k} = 1 \cdot (-1)^k$$

$\Rightarrow Z_t$  is covariance stationary

## 2.4

$$\rho_k = \begin{cases} 1 & k = 0 \\ \phi & |k| = 1 \quad \frac{1}{2} < \phi < 1 \\ 0 & |k| \geq 2 \end{cases}$$

$$\sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j \rho_{|t_i - t_j|} = [\alpha_1 \quad \alpha_2] \begin{bmatrix} 1 & \phi \\ \phi & 1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = [\alpha_1 \quad \alpha_2] \begin{bmatrix} 1 & \phi \\ \phi & 1 \end{bmatrix} \begin{bmatrix} \alpha_1 + \phi \alpha_2 \\ \phi \alpha_1 + \alpha_2 \end{bmatrix}$$

$$= \alpha_1^2 + \alpha_2^2 + 2\phi \alpha_1 \alpha_2 = f(\phi)$$

$$\left. \begin{aligned} f\left(\frac{1}{2}\right) &= \alpha_1^2 + \alpha_2^2 + \alpha_1 \alpha_2 > 0 \\ f(1) &= (\alpha_1 + \alpha_2)^2 \geq 0 \\ f'(\phi) &= 2\alpha_1 \alpha_2 \text{ constant} \end{aligned} \right\} \Rightarrow \frac{1}{2} < \phi < 1 \text{ OK}$$

$$\left. \begin{aligned} f\left(-\frac{1}{2}\right) &= \alpha_1^2 + \alpha_2^2 - \alpha_1 \alpha_2 > 0 \\ f(-1) &= (\alpha_1 - \alpha_2)^2 \geq 0 \\ f'(\phi) &\text{ constant} \end{aligned} \right\} \Rightarrow -1 < \phi < -\frac{1}{2} \text{ OK}$$

Yes it is a valid real-valued autocorrelation function because it is positive semidefinite.