On infinite dimensional systems of conservation laws of Keyfitz-Kranzer type

E.Yu. Panov

Abstract

We prove existence and uniqueness of strong generalized entropy solution to the Cauchy problem for an infinite dimensional system of Keyfitz-Kranzer type, in which the unknown vector takes its value in an arbitrary Banach space.

We study the Cauchy problem for an equation

$$u_t + (\varphi(\|u\|)u)_x = 0$$
 (1)

with initial condition

$$u(0,x) = u_0(x).$$
 (2)

Here the unknown vector u = u(t, x) is defined in a half-plane $\Pi = \mathbb{R}_+ \times \mathbb{R}$, $\mathbb{R}_+ = (0, +\infty)$ and takes its values in some real Banach space X equipped with norm $\|\cdot\|$. We suppose that the function $\varphi(r) \in C(\mathbb{R}_+)$ and

$$r\varphi(r) \to 0 \text{ as } r \to 0 + .$$
 (3)

The initial function $u_0(x) \in L^{\infty}(\mathbb{R}, X)$, i.e. it is an essentially bounded strongly measurable function on \mathbb{R} .

Remark that in the case when $X = L^{p}(\mathbb{R})$ equation (1) can be written as the following integral-differential equation

$$\frac{\partial}{\partial t}u(t,x,\lambda) + \frac{\partial}{\partial x}\left[\varphi\left(\int |u(t,x,\mu)|^p d\mu\right)u(t,x,\lambda)\right] = 0, \ p \ge 1.$$

In the case of finite dimensional X equation (1) is reduced to the known Keyfitz-Kranzer system (see [1]). This case was completely investigated in [7], where in particular existence and uniqueness of a strong generalized entropy solution (strong g.e.s.) of problem (1), (2) were proved. In the present paper these results are extended for the case of an arbitrary Banach space X.

Let $f(r) = r\varphi(|r|) \in C(\mathbb{R})$, for r = 0 we set f(r) = 0 in accordance with (3). By analogy with finite-dimensional case we define a notion of a strong g.e.s. of problem (1), (2).

Definition. A function $u = u(t, x) \in L^{\infty}(\Pi, X)$ is called a strong g.e.s. of (1), (2) if:

1) u(t,x) satisfies (1) in the sense of distributions (in $\mathcal{D}'(\Pi, X)$);

2) the function r = ||u(t, x)|| is a g.e.s. of the Cauchy problem for the scalar equation

$$r_t + f(r)_x = 0, \quad r(0, x) = ||u_0(x)||$$
(4)

in the sense of S.N. Kruzhkov [2];

3) initial condition (2) is satisfied in the following strict form

$$\operatorname{ess\,lim}_{t\to 0} u(t,\cdot) = u_0 \quad \text{in } L^1_{loc}(\Pi, X).$$

If u(t, x) is a strong g.e.s. of the problem (1), (2) then the function r(t, x) = ||u(t, x)|| is uniquely determined by condition 2), as the unique g.e.s. of scalar problem (4). It is essential here that the spatial variable x is single, for the multidimensional equation $r_t + \operatorname{div}_x f(r) = 0, x \in \mathbb{R}^n, n > 1$ with only continuous flux vector $f(r) \in C(\mathbb{R}, \mathbb{R}^n)$ a g.e.s. of the Cauchy problem can be nonunique, see [3, 4, 8].

Thus, for the construction of a strong g.e.s. of problem (1), (2) we have only to find the value v = u/r (here for r = 0 the value of v can be chosen arbitrarily, for instance we can set v = 0). From condition 1) it follows that the vector v = v(t, x) must satisfy in $\mathcal{D}'(\Pi, X)$ the linear equation

$$(rv)_t + (f(r)v)_x = 0, \ v = v(t,x) \in L^{\infty}(\Pi, X)$$
 (5)

and the initial condition $rv(0, x) = u_0(x)$. In the scalar case $v \in \mathbb{R}$ the theory of generalized solutions (g.s.) of the Cauchy problem for equation of the kind (5) was developed in papers [5, 6, 7], where existence and uniqueness (for the product rv) of g.s. were proved together with the following important property:

any continuous function of a finite set of g.s. to problem (5) is also a g.s. to this problem with corresponding initial data.

Going to investigation of infinite-dimensional case $v \in X$, let us consider the Cauchy problem for a general linear transport equation

$$(Av)_t + (Bv)_x = 0, (6)$$

with initial condition

$$v(0,x) = v_0(x) \in L^{\infty}(\mathbb{R}, X).$$

$$\tag{7}$$

Suppose, as in [5, 6, 7], that the coefficients $A, B \in L^{\infty}(\Pi)$ satisfy the following conditions:

$$\operatorname{ess\,lim}_{t\to 0+} A(t,x) = A(0,x) \quad \text{in } L^1_{loc}(\mathbb{R}), \quad A(0,x) \in L^\infty(\mathbb{R}); \tag{8}$$

$$\forall \varepsilon > 0 \quad |B| \le N(\varepsilon) \cdot (A + \varepsilon) \quad \text{a.e. on } \Pi \ , \ \varepsilon N(\varepsilon) \mathop{\rightarrow}_{\varepsilon \to 0+} 0; \tag{9}$$

$$A_t + B_x = 0 \quad \text{in } \mathcal{D}'(\Pi). \tag{10}$$

As was shown in [7], coefficients A = r, B = f(r) satisfy conditions (8)-(10), moreover one can take in (9) $N(\varepsilon) = \omega(\varepsilon)/\varepsilon$, where $\omega(\sigma)$ is the modulus of continuity of f(u) on the segment [-R, R], $R = ||r||_{\infty}$. From condition (9) it easily follows that $A \ge 0$ a.e. on Π and B = 0 a.e. on the set, where A = 0.

The notion of a g.s. of problem (6), (7) is defined in the same way as in [5, 7]:

Definition 2. A function $v = v(t, x) \in L^{\infty}(\Pi, X)$ is called a g.s. of Cauchy problem (6), (7) if for any test function h = h(t, x) from the space $C_0^{\infty}(\bar{\Pi})$ with $\bar{\Pi} = [0, +\infty) \times \mathbb{R}$

$$\int_{\Pi} [Avh_t + Bvh_x] dt dx + \int_{\mathbb{R}} A(0, x) v_0(x) h(0, x) dx = 0.$$
(11)

Since the function v is supposed to be bounded and strongly measurable the integrals in (11) are well-defined. It is clear that a vector $v = v(t, x) \in L^{\infty}(\Pi, X)$ is a g.s. of problem (6), (7) if and only if the scalar functions $\langle x', v \rangle$ are g.s. of this problem for all linear continuous functionals $x' \in X'$, here X' being a conjugate space to X. Remark also that values of the functions v(t, x) and $v_0(x)$ on the sets, where respectively A(t, x) = 0, $A_0(x) = 0$ do not matter and we can consider these functions as elements of the spaces $L^{\infty}(\cdot, X)$ with respect to weighted measures Adtdx and A_0dx .

To extend results of the papers [5, 6, 7] to the general case $v \in X$ we shall need the following technical lemma, which was proved in [7]:

Lemma 1. Let $\alpha_t + \beta_x \leq 0$ in $\mathcal{D}'(\Pi)$, where $\alpha = \alpha(t, x), \ \beta = \beta(t, x) \in L^{\infty}(\Pi);$ ess $\lim_{t \to 0^+} \alpha(t, x) = \alpha(0, x)$ in $L^1_{loc}(\mathbb{R}); \forall \varepsilon > 0$ $|\beta(t, x)| \leq N(\varepsilon)(\alpha(t, x) + \varepsilon)$ a.e. on Π (in particular this condition implies that $\alpha \geq 0$ a.e. on Π), $N(\varepsilon) \geq 1$. Then for a.e. t > 0 the following estimate holds:

$$\int \alpha(t,x) e^{-|x|} dx \le e^t \cdot \inf_{\varepsilon > 0} \left(\int \alpha(0,x) e^{-|x|/N(\varepsilon)} dx + 2\varepsilon N(\varepsilon) \right).$$

Now, we can prove the following

Theorem 1.

1) There exists a g.s. $v = v(t, x) \in L^{\infty}(\Pi, X)$ of problem (6), (7);

2) ess $\lim_{t\to 0+} A(t,x)v(t,x) = A_0(x)v_0(x)$ in $L^1_{loc}(\mathbb{R},X)$;

3) for any continuous function $p(u) \in C(X)$, which is bounded on bounded subsets of X, the composition p(v(t, x)) is a scalar g.s. of (6), (7) with initial data $p(v_0(x))$;

4) if $A(0,x)v_0(x) = 0$ a.e. on \mathbb{R} then A(t,x)v(t,x) = 0 a.e. on Π (uniqueness).

Proof. Remark firstly that for the finite-dimensional space X problem (6), (7) reduces to the scalar problem for the corresponding coordinate functions and in this case assertions 1)-4) have been already proved in [5, 6, 7] (see for instance Propositions 4-6 in [7]). In the general case to prove existence of g.s. we apply the technique of finite-dimensional approximations.

Thus, let $v_{0n} = v_{0n}(x), n \in \mathbb{N}$ be a sequence of simple functions such that $v_{0n} \xrightarrow[n \to \infty]{\to} v_0$ in $L^1_{loc}(\mathbb{R}, X)$. Recall that a simple function is a measurable function, which takes only a finite number of values in X. Since $v_0(x)$ is strongly measurable the approximated sequence v_{0n} really exists, and in addition we can suppose that $||v_{0n}||_{\infty} \leq M = ||v_0||_{\infty} \quad \forall n \in \mathbb{N}$. Let $x_{nk} \in X$, $k = 1, \ldots, m_n$ be values of the functions v_{0n} , and $X_n \subset X$ be a finitedimensional linear space generated by the vectors x_{nk} , $k = 1, \ldots, m_n$. As was mentioned above, there exists a unique g.s. $v_n = v_n(t, x) \in L^{\infty}(\Pi, X_n)$ of problem (6), (7) with initial functions v_{0n} . Applying property 3 to this g.s. with $p(u) = \max(||u|| - M, 0)$, we obtain the g.s. $p(v_n)$ of scalar problem (6), (7) with initial function $p(v_{0n}) = 0$ and by the uniqueness property 4) $Ap(v_n) = 0$ a.e. on Π . The latter means (after appropriate definition of v_n on the set, where A(t,x) = 0) that $||v_n||_{\infty} \leq M \ \forall n \in \mathbb{N}$. For $k, l \in \mathbb{N}$ the difference $v_k - v_l$ takes its values in the finite-dimensional subspace $X_k + X_l$ and by property 3) with p(u) = ||u|| the function $\theta = ||v_k - v_l||$ is a g.s. of scalar problem (6), (7) with initial data $\theta_0 = ||v_{0k} - v_{0l}||$.

Further, observe that in view of (9) $\forall \varepsilon > 0$

$$|B|\theta \le N(\varepsilon)(A+\varepsilon)\theta \le N(\varepsilon)(A\theta+\varepsilon\theta) \le N(\varepsilon)(A\theta+2M\varepsilon) \le \bar{N}(\varepsilon)(A\theta+\varepsilon) \text{ a.e. on } \Pi,$$

where $\bar{N}(\varepsilon) = \max(2M, 1)N(\varepsilon) + 1.$

We see that the functions $\alpha(t, x) = A\theta = A ||v_k - v_l||$,

 $\beta(t,x) = B\theta = B ||v_k - v_l||$ satisfy the conditions of Lemma 1 with $N(\varepsilon) = \overline{N}(\varepsilon), \ \alpha(0,x) = A(0,x)\theta_0(x) = A(0,x)||v_{0k} - v_{0l}||$. By Lemma 1 for a.e. t > 0 and all $k, l \in \mathbb{N}$

$$\int A(t,x) \|v_k(t,x) - v_l(t,x)\| e^{-|x|} dx \le e^t \omega_{kl},$$
(12)

where

$$\omega_{kl} = \inf_{\varepsilon > 0} \left(\int A(0, x) (v_{0k}(x) - v_{0l}(x)) e^{-|x|/\bar{N}(\varepsilon)} dx + 2\varepsilon \bar{N}(\varepsilon) \right).$$

By the construction the sequence v_{0k} converges as $k \to \infty$ to the function v_0 in $L^1_{loc}(\mathbb{R}, X)$ and it is bounded in $L^{\infty}(\mathbb{R}, X)$: $||v_{0k}||_{\infty} \leq M$. From this and the condition $\varepsilon \bar{N}(\varepsilon) \xrightarrow{} 0$ it easily follows (see the proof of Proposition 9 in [6]) that $\lim_{k,l\to\infty} \omega_{kl} = 0$ and (12) implies that for any T > 0 the sequence $v_k(t, x)$ is fundamental in the spaces $L^1([0, T] \times \mathbb{R}, X)$ equipped with measure $e^{-|x|}A(t, x)dtdx$. By the Cauchy criterion this sequence converges in the indicated spaces to some function v = v(t, x). Besides, we can assume that $v_k(t, x) = v(t, x) = 0$ on the set, where A = 0. Then $v_k(t, x) \to v(t, x)$ as $k \to \infty$ in the space $L^1_{loc}(\Pi, X)$ as well. In particular, the function v(t, x)is strongly measurable and bounded, clearly $||v||_{\infty} \leq M$. From relation (11) with $v = v_k, v_0 = v_{0k}$ it follows in the limit as $k \to \infty$ that the limit function $v \in L^{\infty}(\Pi, X)$ satisfies this relation with initial data v_0 . Thus, v is a g.s. of problem (6), (7). Existence of g.s. is proved.

Further, passing to the limit in estimate (12) as $l \to \infty$ we obtain that $\forall t \in E$, where $E \subset \mathbb{R}_+$ is some set of full measure

$$\int A(t,x) \|v_k(t,x) - v(t,x)\| e^{-|x|} dx \le e^t \omega_k,$$

$$\omega_k = \inf_{\varepsilon > 0} \left(\int A(0,x) (v_{0k}(x) - v_0(x)) e^{-|x|/\bar{N}(\varepsilon)} dx + 2\varepsilon \bar{N}(\varepsilon) \right).$$
(13)

Obviously, $\omega_k \to 0$ as $k \to \infty$ and from (13) it follows that as $k \to \infty$ $A(t, \cdot)v_k(t, \cdot) \to A(t, \cdot)v(t, \cdot)$ in the space $L^1(\mathbb{R}, X)$ (equipped with the measure $e^{-|x|}dx$) uniformly with respect to $t \in [0, T] \cap E, \forall T > 0$. Since for the finite-dimensional solutions $v_k(t, x)$ property 2) is satisfied, and it can be written in the form $\operatorname{ess}_{t\to 0+} A(t,\cdot)v_k(t,\cdot) = A_0v_{0k}$ in $L^1(\mathbb{R},X)$, then due to uniform convergence the limit function is essentially continuous at t = 0:

$$\operatorname{ess\,lim}_{t \to 0+} A(t, x) v(t, x) = A_0(x) v_0(x) \quad \text{in } L^1(\mathbb{R}, X),$$

i.e. condition 2) is satisfied.

After a possible extraction of a subsequence we can assume that $v_k(t, x) \rightarrow v(t, x)$, $v_{0k}(x) \rightarrow v_0(x)$ in X as $k \rightarrow \infty$ a.e. on Π and on \mathbb{R} respectively. Let a function p(u) be continuous on X and be bounded on bounded subsets of X. Then the functions $p(v_k(t, x))$, $k \in \mathbb{N}$ and p(v(t, x)) are bounded and $p(v_k) \rightarrow p(v)$ as $k \rightarrow \infty$ a.e. on Π . By the Lebesgue dominated convergence theorem we see that $p(v_k) \rightarrow p(v)$ in $L^1_{loc}(\Pi, X)$ and, similarly, $p(v_{0k}) \rightarrow p(v_0)$ in $L^1_{loc}(\mathbb{R}, X)$. As was already mentioned, $p(v_k)$ is a scalar g.s. of problem (6), (7) with initial data $p(v_{0k})$. Passing to the limit in the corresponding equality (11) as $k \rightarrow \infty$ we derive that (11) holds for the limit function p(v)and the initial function $p(v_0)$. Thus, p(v) is a g.s. of problem (6), (7) with initial data $p(v_0)$.

It only remains to prove the uniqueness of g.s. Let $A(0, x)v_0(x) = 0$ a.e. on \mathbb{R} and v = v(t, x) be the corresponding g.s. of (6), (7). By strong measurability the set of essential values of v(t, x) is separable (see for example [9]). Thus, we can change X to the closed linear hull of the essential image of v(t, x) and without loss of generality assume that X is a separable Banach space. Then the conjugate space X' is weakly separable (see [9]) and we can choose a countable weakly dense set $S \subset X'$. For any functional $x' \in S$ the function $\langle x', v(t, x) \rangle$ is a g.s. of (6), (7) with zero initial data. By the known uniqueness of scalar solutions we have $\langle x', A(t, x)v(t, x) \rangle = 0$ a.e. on Π . Since S is countable then the set of full measure, on which the latter equality holds, can be chosen common for all $x' \in S$. Then on this set A(t, x)v(t, x) = 0 (in view of density of $S \subset X'$) that is A(t, x)v(t, x) = 0a.e. on Π . The proof is complete.

From Theorem 1 it easily follows our main result:

Theorem 2. There exists a unique strong g.e.s. of problem (1), (2).

Proof. Let r = r(t, x) be the g.e.s. of scalar problem (4) with initial function $r_0 = ||u_0(x)||$. Notice that by the comparison principle (see [2, 3, 4, 8]) $r \ge 0$. By Theorem 1 we can find a g.s. v = v(t, x) of problem (5), (7) with initial data $v_0(x) = \begin{cases} u_0(x)/r_0(x) &, r_0(x) > 0, \\ 0 &, r_0(x) = 0. \end{cases}$

Then $r_0 ||v_0|| \equiv r_0$ and by statement 3) of Theorem 1 ||v(t, x)|| is a g.s. of scalar equation (5) with initial function, which is equals 1. Since constant function are evidently g.s. of (5) (in view of condition (10)) then by uniqueness property 4) r||v|| = r a.e. on Π . We set u = rv. Then $u \in L^{\infty}(\Pi, X)$ and ||u|| = r||v|| = r is a g.e.s. of problem (4). Further,

$$u_t + (\varphi(||u||)u)_x = (rv)_t + (f(r)v)_x = 0 \text{ in } \mathcal{D}'(\Pi, X),$$

because v satisfies equation (5) in the sense of distributions. Finally, as it follows from the definition of g.e.s. of problem (4) and statement 2) of Theorem 1,

$$\operatorname{ess\,lim}_{t\to 0} u(t,\cdot) = u_0 \quad \text{in } L^1_{loc}(\Pi, X).$$

By Definition 1 u = u(t, x) is a strong g.e.s. of original problem (1), (2).

To prove uniqueness of a strong g.e.s. suppose that $u_1 = u_1(t, x)$, $u_2 = u_2(t, x)$ are strong g.e.s. of problem (1), (2). Then $||u_1|| = ||u_2|| = r$ in view of uniqueness of a g.e.s. to problem (4). But then $v_i = u_i/r$, i = 1, 2 are g.s. of problem (5), (7) with the same initial function u_0/r_0 . By uniqueness of this g.s. $u_1 - u_2 = r(v_1 - v_2) = 0$ a.e. on Π , that was to be prove. The proof is complete.

Acknowledgments. This research was partially supported by the Russian Foundation for Basic Research (grant No. 03-01-00444) and the Program "Universities of Russia" (grant No. UR.04.01.184).

References

- B.L. Keyfitz, H.C. Kranzer. A system of nonstrictly hyperbolic conservation laws arising in elasticity theory// Arch. Rational. Mech. Anal. 1980. V. 72. P. 219–241.
- [2] S.N. Kruzhkov. First order quasilinear equations in several independent variables// Math. USSR Sb. 1970. V. 10. No. 2. P. 217–243.
- [3] S.N. Kruzhkov, E.Yu. Panov. Conservative quasilinear first order laws with an infinite domain of dependence on the initial data// Soviet Math. Dokl. 1991. V. 42. No. 2. P. 316–321.
- [4] S.N. Kruzhkov, E.Yu. Panov. Osgood's type conditions for uniqueness of entropy solutions to Cauchy problem for quasilinear conservation laws of the first order// Annali Univ. Ferrara-Sez. 1995. V. XL. P. 31–53.

- [5] E. Yu. Panov A class of systems of quasilinear conservation laws// Sbornik: Mathematics. 1997. V. 188. No. 5. P. 725–751.
- [6] E. Yu. Panov On a nonlocal theory of generalized entropy solutions of the Cauchy problem for a class of hyperbolic systems of conservation laws// Izvestiya: Mathematics. 1999. V. 63. No. 1. P. 129–179.
- [7] E. Yu. Panov. On the theory of generalized entropy solutions of the Cauchy problem for a class of nonstrictly hyperbolic systems of conservation laws// Sbornik: Mathematics. 2000. V. 191. No. 1. P. 121–150.
- [8] E. Yu. Panov. On generalized entropy solutions of the Cauchy problem for a first order quasilinear equation in the class of locally summable functions// Izvestiya: Mathematics. 2002. V. 66. No. 6. P. 1171–1218.
- [9] K. Yosida. Functional analysis. (5th ed.). Springer-Verlag, Berlin. 1978.