

Global solutions to one-dimensional shallow water magnetohydrodynamic equations

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Abstract

In this paper, we study the Cauchy problem for the one-dimensional shallow water magnetohydrodynamic equations. The main difficulty is the case of zero depth ($h = 0$) since the nonlinear flux function $P(h)$ is singular and the definition of solution is not clear near $h = 0$. First, assuming that h has a positive and lower bound, we establish the pointwise convergence of the viscosity solutions by using the div-curl lemma from the compensated compactness theory to special pairs of functions (c, f^ε) , and obtain a global weak entropy solution. Second, under some technical conditions on the initial data such that the Riemann invariants (w, z) are monotonic and increasing, we introduce a "variant" of the vanishing artificial viscosity to select a weak solution. Finally, we extend the results to two special cases, where $P(h)$ is for the polytropic gas or for the Chaplygin gas.

1 Introduction

The following one-dimensional, magnetohydrodynamic shallow water equations over an arbitrary boundary

$$\begin{cases} h_t + (hu)_x = 0, \\ (hu)_t + (hu^2 - hG^2 + \frac{1}{2}gh^2)_x = -ghb_x(x, t), \\ (hG)_t = 0, \\ (hG)_2 = 0, \\ (hv)_t + (huv - hGF)_x = 0, \\ (hF)_t + (hFu - hGv)_x = 0 \end{cases} \quad (1.1)$$

was first derived in [Ros], where x and t are the space and the time variables, $h(x, t)$ is the fluid depth, u and v are fluid velocities, F and G are magnetic field components, g is the gravitational constant and $b(x, t)$ denotes the underlying surface.

The shallow water magnetohydrodynamic equations are important in many applications of magnetohydrodynamic to astrophysical and engineering problems, for instance, in the solar tachocline study [Gi, MG, ZCO, ZOB], in the neutron-star atmosphere dynamics study [HS, SLU], for the optimization of aluminum production process [BP, ZT] and in fusion technologies [MCR] (the details can be found in [KPT, Ros] and references cited therein).

It follows from the third and fourth equations in (1.1), $hG = \text{const.} = -C$. In [KPT], the authors studied the Riemann problem of (1.1) and showed that the simple wave solutions exist only for underlying surface that are slopes of constant inclination, i.e., $b_x(x, t) = \text{const.} = b$. Thus, we rewrite system (1.1) as follows

$$\begin{cases} h_t + (hu)_x = 0, \\ (hu)_t + (hu^2 + \frac{1}{2}gh^2 - \frac{C^2}{h})_x = -gbh, \\ (hv)_t + (hvu + CF)_x = 0, \\ (hF)_t + (hFu + Cv)_x = 0. \end{cases} \quad (1.2)$$

In mathematics, system (1.2) is decoupled since the first two equations are independent. We write these equations as

$$\begin{cases} h_t + (hu)_x = 0, \\ (hu)_t + (hu^2 + \frac{1}{2}gh^2 - \frac{C^2}{h})_x = -gbh. \end{cases} \quad (1.3)$$

System (1.3) could be also considered as the isentropic gas dynamics with a special pressure $P(h) = \frac{1}{2}gh^2 - \frac{C^2}{h}$, where h denotes the density and u is the velocity of gas [Di1]. The third and fourth equations in (1.2) are of the Temple type [Te], where the shock waves and rarefaction waves coincide.

By simple calculations, two eigenvalues (1.3) are

$$\lambda_1 = \frac{m}{h} - \sqrt{P'(h)}, \quad \lambda_2 = \frac{m}{h} + \sqrt{P'(h)}, \quad (1.4)$$

where $m = hu$ and $P(h) = \frac{1}{2}gh^2 - \frac{C^2}{h}$, with corresponding right eigenvectors

$$r_1 = (1, \lambda_1)^T, \quad r_2 = (1, \lambda_2)^T. \quad (1.5)$$

The Riemann invariants of (1.3) are functions

$$w(h, u) = \frac{m}{h} + \int_{h_0}^h \frac{\sqrt{P'(s)}}{s} ds, \quad z(h, u) = \frac{m}{h} - \int_{h_0}^h \frac{\sqrt{P'(s)}}{s} ds, \quad (1.6)$$

where $h_0 > 0$ is a constant. Then

$$\begin{aligned} \nabla \lambda_1 \cdot r_1 &= \left(-\frac{m}{h^2} - \frac{P''(h)}{2\sqrt{P'(h)}}, \frac{1}{h}\right) (1, \lambda_1)^T \\ &= -\frac{hP''(h) + 2P'(h)}{2h\sqrt{P'(h)}} = -\frac{3}{\sqrt{P'(h)}} \end{aligned} \quad (1.7)$$

and

$$\begin{aligned} \nabla \lambda_2 \cdot r_2 &= \left(-\frac{m}{h^2} + \frac{P''(h)}{2\sqrt{P'(h)}}, \frac{1}{h}\right) (1, \lambda_2)^T \\ &= \frac{hP''(h) + 2P'(h)}{2h\sqrt{P'(h)}} = \frac{3}{\sqrt{P'(h)}}. \end{aligned} \quad (1.8)$$

Therefore the system (1.3) is strictly hyperbolic from (1.4), and genuinely non-linear from (1.7)-(1.8) in the region of $h \geq h_0 > 0$.

To study the existence of global solutions for the Cauchy problem (1.2) with bounded measurable initial data

$$(h(x, 0), u(x, 0), v(x, 0), F(x, 0)) = (h_0(x), u_0(x), v_0(x), F_0(x)), \quad h_0(x) > 0, \quad (1.9)$$

the main difficulty is the case of zero depth $h = 0$, where the function $\frac{C^2}{h}$ is singular and the definition of solution near $h = 0$ is not clear.

First, under the strong assumption $h^\varepsilon(x, t) \geq h_0 > 0$, where h_0 is a constant independent of ε , and $h^\varepsilon(x, t)$ are the viscosity approximation solutions of the parabolic system

$$\begin{cases} h_t + (hu)_x = \varepsilon h_{xx}, \\ (hu)_t + (hu^2 + \frac{1}{2}gh^2 - \frac{C^2}{h})_x = \varepsilon(hu)_{xx} - gbh, \\ (hv)_t + (hvu + CF)_x = \varepsilon(hv)_{xx}, \\ (hF)_t + (hFu + Cv)_x = \varepsilon(hF)_{xx} \end{cases} \quad (1.10)$$

with the initial data (1.9), we establish the following existence theorem

Theorem 1 (I). *Let the initial data $(h_0(x), u_0(x), v_0(x), F_0(x))$ be bounded, $h_0(x) \geq c_0 > 0$ for a positive constant c_0 . Then for any fixed $\varepsilon > 0$, the viscosity solution*

$(h^\varepsilon(x, t), u^\varepsilon(x, t), v^\varepsilon(x, t), F^\varepsilon(x, t))$ of the Cauchy problem (1.10) and (1.9) exists and satisfies

$$0 < c(t, c_0, \varepsilon) \leq h^\varepsilon(x, t) \leq M(t), \quad |u^\varepsilon(x, t)| \leq M(t), \quad |v^\varepsilon| \leq M, \quad |F^\varepsilon| \leq M, \quad (1.11)$$

where $M(t)$ is a positive bounded function, independent of ε , in any compact set $t \in [0, T]$ and $c(t, c_0, \varepsilon)$ could tend to zero as the time t tends to infinity or ε tends to zero.

(II). If the conditions in (I) are satisfied and the total variation of $(v_0(x), F_0(x))$ is bounded, then

$$\int_{-\infty}^{\infty} |v_x^\varepsilon|(x, t) dx \leq M, \quad \int_{-\infty}^{\infty} |F_x^\varepsilon|(x, t) dx \leq M, \quad (1.12)$$

where M is a positive constant depending only on the bound of the total variation of $(v_0(x), F_0(x))$, but independent of ε .

(III). Assume that $h^\varepsilon(x, t)$ have the positive, lower bound estimate $h^\varepsilon(x, t) \geq h_0 > 0$, where h_0 is a constant independent of ε , then there exists a subsequence (still labelled) $(h^\varepsilon(x, t), u^\varepsilon(x, t), v^\varepsilon(x, t), F^\varepsilon(x, t))$ such that

$$(h^\varepsilon(x, t), u^\varepsilon(x, t), v^\varepsilon(x, t), F^\varepsilon(x, t)) \rightarrow (h(x, t), u(x, t), v(x, t), F(x, t)), \quad (1.13)$$

a.e. on any bounded and open set $\Omega \subset R \times R^+$, and the limit functions (h, u, v, F) is a weak solution of the Cauchy problem (1.2) and (1.9), namely (h, u, v, F) satisfies (1.2) in the sense of distributions.

Second, we choose some special initial data such that the Riemann invariants (w, z) satisfy

$$\begin{cases} l_1 \leq z_0(x) = z(h_0(x), u_0(x)) \leq l_2 < m_1 \leq w_0(x) = w(h_0(x), u_0(x)) \leq m_2, \\ z(h_0(x), u_0(x)) \quad \text{and} \quad w(h_0(x), u_0(x)) \quad \text{are monotonic increasing,} \end{cases} \quad (1.14)$$

where l_1, l_2, m_1 and m_2 are suitable constants, which ensure the a-priori positive, lower bound estimate $h(x, t) \geq h_0$. More precisely, we have

Theorem 2 *Let $(h_0(x), u_0(x), v_0(x), F_0(x))$ be bounded, $(h_0(x), u_0(x))$ satisfy (1.14) and the total variation of $(v_0(x), F_0(x))$ be bounded. Then the Cauchy problem (1.2) and (1.9) has a weak solution $(h(x, t), u(x, t), v(x, t), F(x, t))$, where the Riemann invariants $(z(h(x, t), u(x, t)), w(h(x, t), u(x, t)))$ are monotonic increasing with respect to x , and $(v(\cdot, t)_x, F(\cdot, t)_x)$ are bounded in $L^1(-\infty, \infty)$.*

In the sections 2 and 3, we will prove Theorems 1-2 respectively. Under the assumption $h^\varepsilon \geq h_0 > 0$, the convergence of $(h^\varepsilon, u^\varepsilon)$ can be proved by using the DiPerna's compact framework on strictly hyperbolic and genuinely nonlinear systems [Di2].

The convergence of $(v^\varepsilon, F^\varepsilon)$ is obtained by applying the Div-Curl lemma from the compensated compactness theory [Ta] to some special pairs of functions (c, v^ε) or (c, F^ε) , where c is a constant. To prove Theorem 2, we introduce a "variant" of the vanishing artificial viscosity given by (3.1) and (3.14) to select the solution satisfying $h^\varepsilon \geq h_0 > 0$.

In Section 4, we will extend the results in Theorem 1 to two special cases, where $P(h)$ is for the polytropic gas $h^\gamma, \gamma > 1$ or for the Chaplygin gas $-\frac{C^2}{h}$. For the polytropic gas, the convergence of $(h^\varepsilon, u^\varepsilon)$ is proved in [LPS, LPT] and the proof of the convergence $(v^\varepsilon, F^\varepsilon)$ in Theorem 1 covers the vacuum $h = 0$. For the Chaplygin gas $P(h) = -\frac{C^2}{h}$, the main difficulty in studying the global solution is still the vacuum $h = 0$, where the definition of solution is not clear. So, we will mainly study the bounded measurable weak solution away from the vacuum.

2 Proof of Theorem 1

In this section, we shall prove (I)-(III) in Theorem 1 respectively.

Proof of (I). We multiply the first two equations in (1.10) by (w_h, w_m) and (z_h, z_m) respectively, where w, z are given by (1.6), to obtain

$$\begin{aligned} & w_t + \lambda_2 w_x \\ &= \varepsilon w_{xx} + \frac{2\varepsilon}{h} h_x w_x - \frac{\varepsilon}{2h^2 \sqrt{P'(h)}} (2P' + hP'') h_x^2 - gb \leq \varepsilon w_{xx} + \frac{2\varepsilon}{h} h_x w_x - gb \end{aligned} \quad (2.1)$$

and

$$\begin{aligned} & z_t + \lambda_1 z_x \\ &= \varepsilon z_{xx} + \frac{2\varepsilon}{h} h_x z_x + \frac{\varepsilon}{2h^2 \sqrt{P'(h)}} (2P' + hP'') h_x^2 - gb \geq \varepsilon z_{xx} + \frac{2\varepsilon}{h} h_x z_x - gb. \end{aligned} \quad (2.2)$$

Let $\bar{w} = w + gbt$ and $\bar{z} = z + gbt$. Then we have from (2.1) and (2.2) that

$$\begin{cases} \bar{w}_t + \lambda_2 \bar{w}_x \leq \varepsilon \bar{w}_{xx} + \frac{2\varepsilon}{h} h_x \bar{w}_x, \\ \bar{z}_t + \lambda_1 \bar{z}_x \geq \varepsilon \bar{z}_{xx} + \frac{2\varepsilon}{h} h_x \bar{z}_x. \end{cases} \quad (2.3)$$

If we consider (2.3) as inequalities about the variables \bar{w} and \bar{z} , then we can get the estimates $\bar{w}(h^\varepsilon, m^\varepsilon) \leq \bar{w}(h^\varepsilon, m^\varepsilon)|_{t=0} = w(h^\varepsilon, m^\varepsilon)|_{t=0} \leq M$, $\bar{z}(h^\varepsilon, m^\varepsilon) \geq -M$ by applying the maximum principle to (2.3). Thus we obtain the estimates $0 < h^\varepsilon \leq M(t)$ and $|u^\varepsilon| \leq M(t)$ for a suitable function $M(t)$, which is bounded in any compact set $t \in [0, T]$ and independent of ε . Using the estimate $|u^\varepsilon| \leq M(t)$ and Theorem 1.0.2 given in [Lu1], we have the estimate $h^\varepsilon \geq c(t, c_0, \varepsilon) > 0$.

To prove the L^∞ bounds of v^ε and F^ε , we substitute the first equations in (1.10) into the third and fourth equations to obtain

$$\begin{cases} v_t + uv_x + \frac{C}{h}F_x = \varepsilon v_{xx} + 2\varepsilon \frac{h_x}{h}v_x, \\ F_t + uF_x + \frac{C}{h}v_x = \varepsilon F_{xx} + 2\varepsilon \frac{h_x}{h}F_x. \end{cases} \quad (2.4)$$

Let $w_1 = v + F$, $z_1 = v - F$. We have from (2.4) that

$$\begin{cases} w_{1t} + (u + \frac{C}{h})w_{1x} = \varepsilon w_{1xx} + 2\varepsilon \frac{h_x}{h}w_{1x}, \\ z_{1t} + (u - \frac{C}{h})z_{1x} = \varepsilon z_{1xx} + 2\varepsilon \frac{h_x}{h}z_{1x}. \end{cases} \quad (2.5)$$

If we consider (2.5) as equations about the variables w_1 and z_1 , then we have the estimates $|w_1| \leq |w_1|_{t=0} \leq M$, $|z_1| \leq |z_1|_{t=0} \leq M$ by applying the maximum principle to (2.5). Thus we obtain the estimates $|v^\varepsilon| \leq M$ and $|F^\varepsilon| \leq M$ for a suitable positive constant M , which is independent of ε .

So, the proof of (I) about the existence of the viscosity solution for the Cauchy problem (1.10)-(1.9) is completed by the standard theory of semilinear parabolic systems, namely the local existence and the above a priori bounded estimates.

Proof of (II). To prove the BV estimate in (1.12), we use the ideal given in [Se]. Let $\theta = w_{1x}$ and choose one sequence of smooth functions $g(\theta, \alpha)$ such that $g''(\theta, \alpha) \geq 0$, $g'(\theta, \alpha) \rightarrow \text{sign}\theta$, $g(\theta, \alpha) \rightarrow |\theta|$ as $\alpha \rightarrow 0$.

Differentiating the first equation in (2.5) with respect to x and then multiplying the sequence of smooth functions $g'(\theta, \alpha)$ to the result, we have

$$\theta_t + ((u + \frac{C}{h})\theta)_x = \varepsilon \theta_{xx} + (2\varepsilon \frac{h_x}{h}\theta)_x \quad (2.6)$$

and

$$\begin{aligned} & g(\theta, \alpha)_t + ((u + \frac{C}{h})g(\theta, \alpha))_x + (g'(\theta, \alpha)\theta - g(\theta, \alpha))(u + \frac{C}{h})_x \\ &= \varepsilon g(\theta, \alpha)_{xx} - \varepsilon g''(\theta, \alpha)\theta_x^2 \\ &+ (2\varepsilon \frac{h_x}{h}g(\theta, \alpha))_x + (2\varepsilon \frac{h_x}{h})_x(g'(\theta, \alpha)\theta - g(\theta, \alpha)). \end{aligned} \quad (2.7)$$

Now we let $\alpha \rightarrow 0$ in (2.7) to get

$$|\theta|_t + \left(u + \frac{C}{h}\right)|\theta|_x \leq \varepsilon|\theta|_{xx} + \left(2\varepsilon\frac{h_x}{h}|\theta|\right)_x \quad (2.8)$$

in the sense of distributions. Integrating (2.8) in $R \times [0, t]$, we have

$$\int_{-\infty}^{\infty} |w_{1x}|(x, t)dx = \int_{-\infty}^{\infty} |\theta|(x, t)dx \leq \int_{-\infty}^{\infty} |\theta|(x, 0)dx \leq M. \quad (2.9)$$

Similarly we can prove that

$$\int_{-\infty}^{\infty} |z_{1x}|(x, t)dx \leq \int_{-\infty}^{\infty} |z_{1x}|(x, 0)dx \leq M \quad (2.10)$$

and so the estimates

$$\int_{-\infty}^{\infty} |v_x^\varepsilon|(x, t)dx \leq M, \quad \int_{-\infty}^{\infty} |F_x^\varepsilon|(x, t)dx \leq M. \quad (2.11)$$

Remark 1. The above BV estimates of $(v^\varepsilon(x, t), F^\varepsilon(x, t))$ with respect to the variable x are true when we have the lower, positive estimate depending on ε , $h^\varepsilon(x, t) \geq c(\varepsilon, t) > 0$. However these estimates are not enough to guarantee the pointwise convergence of $(v^\varepsilon(x, t), F^\varepsilon(x, t))$ as ε goes to zero. If one could also prove the uniformly bounded estimates of $(w_{1t}^\varepsilon, z_{1t}^\varepsilon)$ in $L^1_{loc}(R \times R^+)$, then one would have the pointwise convergence of $(v^\varepsilon(x, t), F^\varepsilon(x, t))$. Unfortunately, the terms $2\varepsilon\frac{h_x}{h}w_{1x}$ and $2\varepsilon\frac{h_x}{h}z_{1x}$ in the right-hand side of (2.5) make the L^1 estimates of w_{1t}^ε and z_{1t}^ε very difficult, or even impossible near $h = 0$. In [Lu4, Lu5], the author used the standard method from the compensated compactness theory to study the convergence of $(v^\varepsilon(x, t), F^\varepsilon(x, t))$. Here we introduce a different method.

Proof of (III). Since the assumption $h^\varepsilon(x, t) \geq h_0 > 0$ in Theorem 1, system (1.3) is strictly hyperbolic from (1.4) and genuinely nonlinear from (1.7)-(1.8) in the sense of Lax [Lax], the following DiPerna's compact framework gives us the pointwise convergence of $(h^\varepsilon(x, t), u^\varepsilon(x, t))$ immediately.

Lemma 3 *For the 2×2 strictly hyperbolic and genuinely nonlinear system*

$$\begin{cases} a_t + f(a, b)_x = 0, \\ b_t + g(a, b)_x = 0, \end{cases} \quad (2.12)$$

if the viscosity solutions $(a^\varepsilon, b^\varepsilon)$ of the Cauchy problem for the inhomogeneous system

$$\begin{cases} a_t + f(a, b)_x + f_1(a, b) = \varepsilon a_{xx}, \\ b_t + g(a, b)_x + g_1(a, b) = \varepsilon b_{xx} \end{cases} \quad (2.13)$$

are uniformly bounded, then there exists a subsequence $(a^{\varepsilon_l}(x, t), b^{\varepsilon_l}(x, t))$ such that

$$(a^{\varepsilon_l}(x, t), b^{\varepsilon_l}(x, t)) \rightarrow (a(x, t), b(x, t)), \quad (2.14)$$

pointwisely on any bounded and open set $\Omega \subset R \times R^+$ as ε_l goes to zero.

To prove the pointwise convergence of $(v^\varepsilon(x, t), F^\varepsilon(x, t))$, we first prove the following lemma

Lemma 4

$$c_t + v_x^\varepsilon, \quad h_t^\varepsilon + (h^\varepsilon u^\varepsilon)_x, \quad (h^\varepsilon v^\varepsilon)_t + (h^\varepsilon v^\varepsilon u^\varepsilon)_x \quad (2.15)$$

are all compact in $H_{loc}^{-1}(R \times R^+)$, where c is a constant.

Proof of Lemma 4. Since v_x^ε are bounded in $L_{loc}^1(R \times R^+)$, then they are compact in $W_{loc}^{-1, \alpha}(R \times R^+)$ for a suitable $\alpha \in (1, 2)$ by the Sobolev's embedding theorem. Furthermore since $v_x^\varepsilon(x, t)$ are bounded in $W^{-1, \infty}(R \times R^+)$, so Murat's theorem [Mu] gives that $v_x^\varepsilon(x, t)$ or $c_t + v_x^\varepsilon(x, t)$ are compact in $H_{loc}^{-1}(R \times R^+)$.

$(h^\varepsilon, h^\varepsilon u^\varepsilon)$ is a weak entropy-entropy flux pair corresponding to the system of isentropic gas dynamics (1.3). System (1.3) has a convex entropy $\eta^* = \frac{hu^2}{2} + h \int_0^h \frac{P(s)}{s^2} ds$, which reduces that ([Di1, LPT, LPS, Lu3])

$$\varepsilon(h \int_0^h \frac{P(s)}{s^2} ds)_{hh} (h_x^\varepsilon)^2 = \varepsilon(g + \frac{C^2}{h^3}) (h_x^\varepsilon)^2 \text{ are bounded in } L_{loc}^1(R \times R^+) \quad (2.16)$$

and so

$$\varepsilon(h_x^\varepsilon)^2 \text{ are bounded in } L_{loc}^1(R \times R^+). \quad (2.17)$$

Thus, we have from (1.10) and (2.17) that $h_t^\varepsilon + (h^\varepsilon u^\varepsilon)_x$ are compact in $H_{loc}^{-1}(R \times R^+)$.

Finally we choose $\eta(h, v) = hf(v)$, where f is a strictly convex function of v and multiply the first equation in (1.10) by $f(v)$, the first equation in (2.4) by $hf'(v)$, and add the results to obtain

$$\begin{aligned} & (hf(v))_t + (hf(v)u)_x + Cf'(v)F_x \\ & = \varepsilon(hf(v))_{xx} - \varepsilon f''(v)hv_x^2 \leq \varepsilon(hf(v))_{xx} - \varepsilon c_0 hv_x^2 \end{aligned} \quad (2.18)$$

for a suitable positive constant c_0 . Since F_x is bounded in $L_{loc}^1(R \times R^+)$, we obtain from (2.18) that

$$\varepsilon hv_x^2 \text{ are bounded in } L_{loc}^1(R \times R^+). \quad (2.19)$$

We may rewrite the right-hand side of the third equation in (1.10) as $\varepsilon(hv_x + vh_x)_x$, which is clearly compact in $H_{loc}^{-1}(R \times R_+)$ since the estimates (2.19) and (2.17).

Since F_x is bounded both in $L_{loc}^1(R \times R^+)$ and in $W^{-1,\infty}(R \times R^+)$, we have from the Murat's theorem ([Mu]) and the third equation in (1.10) that

$$(h^\varepsilon v^\varepsilon)_t + (h^\varepsilon v^\varepsilon u^\varepsilon)_x = \varepsilon(h^\varepsilon v^\varepsilon)_{xx} - CF_x^\varepsilon \quad \text{are compact in } H_{loc}^{-1}(R \times R^+), \quad (2.20)$$

which ends the proof of Lemma 4.

Now we apply for the div-curl lemma in the compensated compactness theory [Ta, Lu2] to the following special pairs of functions

$$(c, v^\varepsilon), \quad (h^\varepsilon, h^\varepsilon u^\varepsilon) \quad (2.21)$$

and

$$(c, v^\varepsilon), \quad (h^\varepsilon v^\varepsilon, h^\varepsilon v^\varepsilon u^\varepsilon), \quad (2.22)$$

respectively for any constant c , to obtain

$$\overline{h^\varepsilon \cdot v^\varepsilon} = \overline{h^\varepsilon v^\varepsilon} \quad \text{and} \quad \overline{h^\varepsilon v^\varepsilon \cdot v^\varepsilon} = \overline{h^\varepsilon (v^\varepsilon)^2}, \quad (2.23)$$

where $\overline{f(\theta^\varepsilon)}$ denotes the weak-star limit of $f(\theta^\varepsilon)$.

Let $(\overline{h^\varepsilon}, \overline{v^\varepsilon}) = (h, v)$. By simple calculations, we have

$$\overline{h^\varepsilon (v^\varepsilon - v)^2} = \overline{h^\varepsilon (v^\varepsilon)^2} - 2v \overline{h^\varepsilon v^\varepsilon} + hv^2 = 0 \quad (2.24)$$

due to (2.23), which implies the pointwise convergence of v^ε on any compact, support set $\{(x, t) : h(x, t) > 0\}$. Similarly we can prove the pointwise convergence of F^ε on any compact, support set $\{(x, t) : h(x, t) > 0\}$. Therefore, we complete the proof of Theorem 1.

3 Proof of Theorem 2

We introduce a "variant" of the vanishing artificial viscosity to study system (1.3). Consider the following parabolic system

$$\begin{cases} w_t + \lambda_2 w_x = \varepsilon w_{xx} - gb, \\ z_t + \lambda_1 z_x = \varepsilon z_{xx} - gb \end{cases} \quad (3.1)$$

with initial data

$$(w^{\varepsilon_1}(x, 0), z^{\varepsilon_1}(x, 0)) = (w(h_0(x), u_0(x)), z(h_0(x), u_0(x))) * G^{\varepsilon_1}, \quad (3.2)$$

where w, z are Riemann invariants given in (1.6) and G^{ε_1} is a mollifier such that $w^{\varepsilon_1}(x, 0)$ and $z^{\varepsilon_1}(x, 0)$ are smooth, monotonic, increasing functions satisfying

$$\begin{cases} \lim_{\varepsilon_1 \rightarrow 0} (w^{\varepsilon_1}(x, 0), z^{\varepsilon_1}(x, 0)) = (w_0(x), z_0(x)), a.e. \text{ on } R, \\ l_1 \leq z^{\varepsilon_1}(x, 0) \leq l_2 < m_1 \leq w^{\varepsilon_1}(x, 0) \leq m_2 \\ 0 \leq \varepsilon_1 z_x^{\varepsilon_1}(x, 0) \leq M, \quad 0 \leq \varepsilon_1 w_x^{\varepsilon_1}(x, 0) \leq M, \quad \varepsilon = o((\varepsilon_1)^2). \end{cases} \quad (3.3)$$

We rewrite (3.1) as

$$\begin{cases} \bar{w}_t + \lambda_2 \bar{w}_x = \varepsilon \bar{w}_{xx}, \\ \bar{z}_t + \lambda_1 \bar{z}_x = \varepsilon \bar{z}_{xx}, \end{cases} \quad (3.4)$$

where $\bar{z} = z + bgt, \bar{w} = w + bgt$. We differentiate (3.4) with respect to x and let $\bar{w}_x = r, \bar{z}_x = s$; then

$$\begin{cases} r_t + \lambda_2 r_x + (\lambda_{2w} r + \lambda_{2z} s) r = \varepsilon r_{xx}, \\ s_t + \lambda_1 s_x + (\lambda_{1w} r + \lambda_{1z} s) s = \varepsilon s_{xx}. \end{cases} \quad (3.5)$$

A simple calculation yields

$$u_w = \frac{1}{2}, \quad h_w = \frac{h}{2\sqrt{P'(h)}}, \quad u_z = \frac{1}{2}, \quad h_z = -\frac{h}{2\sqrt{P'(h)}} \quad (3.6)$$

and

$$\lambda_{1w} = \lambda_{2z} = \frac{2P'(h) - hP''(h)}{4P'(h)} > 0, \quad \lambda_{1z} = \lambda_{2w} = \frac{2P'(h) + hP''(h)}{4P'(h)} > 0. \quad (3.7)$$

By applying the maximum principle to (3.4) and (3.5), we can get the following estimates immediately for the solutions $(w^{\varepsilon, \varepsilon_1}(x, t), z^{\varepsilon, \varepsilon_1}(x, t))$ of the Cauchy problem (3.1) and (3.2) ([Lu1])

$$\begin{cases} l_1 - gbt \leq z^{\varepsilon, \varepsilon_1}(x, t) \leq l_2 - gbt < m_1 - gbt \leq w^{\varepsilon, \varepsilon_1}(x, t) \leq m_2 - gbt \\ 0 \leq \varepsilon_1 z_x^{\varepsilon, \varepsilon_1}(x, t) \leq M, \quad 0 \leq \varepsilon_1 w_x^{\varepsilon, \varepsilon_1}(x, t) \leq M \end{cases} \quad (3.8)$$

which imply the following estimates on $(h^{\varepsilon, \varepsilon_1}(x, t), u^{\varepsilon, \varepsilon_1}(x, t))$

$$h_0 \leq h^{\varepsilon, \varepsilon_1} \leq M(t), \quad |u^{\varepsilon, \varepsilon_1}| \leq M(t), \quad 0 \leq \varepsilon_1 u_x^{\varepsilon, \varepsilon_1} \leq M, \quad \varepsilon_1 |h_x^{\varepsilon, \varepsilon_1}| \leq M, \quad (3.9)$$

where M is a positive constant, $M(t)$ a positive bounded function on any compact set $t \in [0, T]$ and both are independent of $\varepsilon, \varepsilon_1$.

Now we consider the matrix

$$A = \begin{pmatrix} w_h & w_m \\ z_h & z_m \end{pmatrix}^{-1} = \begin{pmatrix} \frac{h}{2\sqrt{P'(h)}} & -\frac{h}{2\sqrt{P'(h)}} \\ \frac{1}{2}(h + \frac{m}{\sqrt{P'(h)}}) & \frac{1}{2}(h - \frac{m}{\sqrt{P'(h)}}) \end{pmatrix},$$

where $m = hu$. Multiply (3.1) by A , then (3.1) can be rewritten as follows:

$$\begin{cases} h_t + (hu)_x = \frac{\varepsilon h}{2\sqrt{P'(h)}}(w_{xx} - z_{xx}) = \varepsilon h_{xx} + \varepsilon \frac{h}{\sqrt{P'(h)}} \left(\frac{\sqrt{P'(h)}}{h}\right)' h_x^2, \\ (hu)_t + (hu^2 + P(h))_x = \frac{\varepsilon h}{2}(w_{xx} + z_{xx}) + \frac{\varepsilon m}{2\sqrt{P'(h)}}(w_{xx} - z_{xx}) - bgh. \end{cases} \quad (3.10)$$

Then for any smooth entropy-entropy flux pair $(\eta(h, m), q(h, m))$ of system (1.3), we multiply (3.10) by $(\eta_h(h, m), \eta_m(h, m))$ to obtain

$$\begin{aligned} & \eta_t(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1}) + q_x(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1}) \\ &= \eta_h(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1}) \left(\frac{\varepsilon h}{2\sqrt{P'(h)}}(w_{xx} - z_{xx})\right) \\ &+ \eta_m(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1}) \left(\frac{\varepsilon h}{2}(w_{xx} + z_{xx}) + \frac{\varepsilon m}{2\sqrt{P'(h)}}(w_{xx} - z_{xx}) - bgh\right). \end{aligned} \quad (3.11)$$

Since the estimates given in (3.9) and $\varepsilon = o((\varepsilon_1)^2)$, we can easily prove that

$$\eta_t(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1}) + q_x(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1}) \quad \text{are compact in } H_{loc}^{-1}(R \times R^+) \quad (3.12)$$

as $\varepsilon, \varepsilon_1$ go to zero. Thus DiPerna's compactness framework (Lemma 3) reduces again the pointwise convergence of $(h^{\varepsilon, \varepsilon_1}, m^{\varepsilon, \varepsilon_1})$ as $\varepsilon, \varepsilon_1$ go to zero. The limit (h, m) satisfies system (1.3) in the sense of distributions

$$\begin{cases} \int_0^\infty \int_R h \phi_t + hu \phi_x dx dt + \int_{t=0} h_0 \phi dx = 0, \\ \int_0^\infty \int_R hu \phi_t + (hu^2 + P(h)) \phi_x - gbh \phi dx dt + \int_{t=0} h_0 u_0 \phi dx = 0 \end{cases} \quad (3.13)$$

for all $\phi \in C_0^1(R \times R^+)$.

Now let $(v^{\varepsilon, \varepsilon_1}, F^{\varepsilon, \varepsilon_1})$ be the solutions of the parabolic system

$$\begin{cases} (hv)_t + (hvu + CF)_x = \varepsilon (hv)_{xx} + \varepsilon \frac{h}{\sqrt{P'(h)}} \left(\frac{\sqrt{P'(h)}}{h}\right)' h_x^2 v, \\ (hF)_t + (hFu + Cv)_x = \varepsilon (hF)_{xx} + \varepsilon \frac{h}{\sqrt{P'(h)}} \left(\frac{\sqrt{P'(h)}}{h}\right)' h_x^2 F \end{cases} \quad (3.14)$$

with the initial data

$$(v(x, 0), F(x, 0)) = (v_0(x), F_0(x)). \quad (3.15)$$

Substituting the first equation in (3.10) into (3.14), then (v, F) satisfies (2.4). Since the estimates in (3.9) and $\varepsilon = o((\varepsilon_1)^2)$, then both terms

$$\varepsilon \frac{h}{\sqrt{P'(h)}} \left(\frac{\sqrt{P'(h)}}{h} \right)' h_x^2 v \quad \text{and} \quad \varepsilon \frac{h}{\sqrt{P'(h)}} \left(\frac{\sqrt{P'(h)}}{h} \right)' h_x^2 F \quad (3.16)$$

in (3.14) converge to zero as $\varepsilon, \varepsilon_1$ go to zero. Using the same technique in the proof of (III) in Theorem 1, we may prove the pointwise convergence of $(v^{\varepsilon, \varepsilon_1}(x, t), F^{\varepsilon, \varepsilon_1}(x, t)) \rightarrow (v(x, t), F(x, t))$, as $\varepsilon, \varepsilon_1$ go to zero, and the limit (v, F) satisfies the third and the fourth equations in system (1.2) in the sense of distributions. Therefore we complete the proof of Theorem 2.

4 Applications on Polytropic and Chaplygin gas

In this section, we study the following system

$$\begin{cases} h_t + (hu)_x = 0, \\ (hu)_t + (hu^2 + P(h))_x = -gbh, \\ (hv)_t + (hvu + CF)_x = 0, \\ (hF)_t + (hFu + Cv)_x = 0 \end{cases} \quad (4.1)$$

for the polytropic gas $P(h) = h^\gamma, \gamma > 1$ and for the Chaplygin gas $P(h) = -\frac{1}{h}$. Since the global weak solution for the polytropic gas is well studied in [LPS, LPT], we have the following existence theorem immediately

Theorem 5 *Let $P(h) = h^\gamma, \gamma > 1$ and the initial data $(h_0(x), u_0(x), v_0(x), F_0(x))$ be bounded, $h_0(x) \geq 0$, the total variation of $(v_0(x), F_0(x))$ be bounded. Then the Cauchy problem (4.1) and (1.9) has a global bounded weak solution (h, u, v, F) satisfying (4.1) in the sense of distributions, where $h(x, t) \geq 0$, $v_x(\cdot, t)$ and $F_x(\cdot, t)$ are bounded in L^1 .*

Remark 2. In Theorem 5, the initial date $h_0(x) \geq 0$. We may first add a small ε to $h_0(x)$ and consider system (4.1) with the initial date $h_0(x) + \varepsilon > 0$. The proof of Theorem 5 is similar to that of Theorem 1.

Now we consider the case of Chaplygin gas and rewrite the first two equations in (4.1) as

$$\begin{cases} h_t + (hu)_x = 0 \\ (hu)_t + (hu^2 - h^{-1})_x = -gbh. \end{cases} \quad (4.2)$$

By simple calculations, two eigenvalues of system (4.2) are

$$\lambda_1 = u - h^{-1}, \quad \lambda_2 = u + h^{-1} \quad (4.3)$$

with corresponding right eigenvectors

$$r_1 = (1, u - h^{-1})^T, \quad r_2 = (1, u + h^{-1})^T; \quad (4.4)$$

the two corresponding Riemann invariants are

$$z = u + h^{-1}, \quad w = u - h^{-1}; \quad (4.5)$$

and

$$\begin{cases} \nabla \lambda_1 \cdot r_1 = (-uh^{-1} + h^{-2}, h^{-1})(1, u - h^{-1})^T = 0, \\ \nabla \lambda_2 \cdot r_2 = (-uh^{-1} - h^{-2}, h^{-1})(1, u + h^{-1})^T = 0. \end{cases} \quad (4.6)$$

Therefore, it follows from (4.3) that $\lambda_1 < \lambda_2$ for all $0 < h < \infty$, and from (4.6) that both characteristic fields are linearly degenerate on all the points (h, hu) (Temple's type also [Te]).

Any entropy-entropy flux pair $(\eta(h, m), q(h, m))$ of system (4.2) satisfies the additional system

$$q_h = u\eta_h + h^{-3}\eta_u, \quad q_u = h\eta_h + u\eta_u. \quad (4.7)$$

Eliminating the q from (4.7), we have

$$\eta_{hh} = h^{-4}\eta_{uu}. \quad (4.8)$$

Let $\eta = hH(h, u)$, then $\eta_h = H + hH_h, \eta_{hh} = 2H_h + hH_{hh}, \eta_u = hH_u, \eta_{uu} = hH_{uu}$. Thus using the entropy equation (4.8), we have the following equation on the function H

$$2H_h + hH_{hh} = h^{-3}H_{uu}. \quad (4.9)$$

Let $H(h, u) = L(w, z)$, then

$$H_h = h^{-2}(L_w - L_z), \quad H_u = L_w + L_z, \quad H_{uu} = L_{ww} + L_{zz} + 2L_{wz},$$

$$H_{hh} = h^{-4}(L_{ww} + L_{zz}) - 2h^{-4}L_{wz} - 2h^{-3}(L_w - L_z).$$

Substituting all above equalities into (4.9), we have $L_{wz} = 0$ or $L(w, z) = f(w) + g(z)$ and so the following lemma.

Lemma 6 *System (4.2) has two special families of entropy-entropy flux pairs:*

$$(A). \quad \eta_1(h, u) = hf(u - h^{-1}), \quad q_1(h, u) = \lambda_2 \eta_1(h, u) = (hu + 1)f(u - h^{-1});$$

$$(B). \quad \eta_2(h, u) = hg(u + h^{-1}), \quad q_2(h, u) = \lambda_1 \eta_2(h, u) = (hu - 1)g(u + h^{-1}),$$

where f, g are two arbitrary differentiable functions.

Proof of Lemma 6: We need to prove that the entropy-entropy flux pairs $(\eta_1, q_1), (\eta_2, q_2)$ satisfy (4.7). By simple calculations,

$$q_{1h} = uf + h^{-2}(uh + 1)f', \quad q_{1u} = hf + (uh + 1)f',$$

$$\eta_{1h} = f + h^{-1}f', \quad \eta_{1u} = hf'.$$

So (η_1, q_1) satisfy (4.7). Similarly we can prove that (η_2, q_2) satisfy (4.7) also.

We consider the Cauchy problem for the related parabolic system

$$\begin{cases} h_t + (hu)_x = \varepsilon h_{xx} \\ (hu)_t + (hu^2 - h^{-1})_x = \varepsilon (hu)_{xx} - gbh \end{cases} \quad (4.10)$$

with bounded initial data

$$(h(x, 0), u(x, 0)) = (h_0(x), u_0(x)), \quad h_0(x) > 0, \quad (4.11)$$

and multiply (4.10) by (w_h, w_m) and $(z_h, z_m), m = hu$ respectively to obtain

$$\begin{aligned} w_t + \lambda_2 w_x &= \varepsilon w_{xx} - \varepsilon(w_{hh}h_x^2 + 2w_{hm}h_x m_x + w_{mm}m_x^2) - gb \\ &= \varepsilon w_{xx} - \varepsilon(-2h^{-2}h_x m_x + 2(m - 1)h^{-3}h_x^2) - gb \\ &= \varepsilon w_{xx} + 2\varepsilon h^{-1}h_x w_x - gb, \end{aligned} \quad (4.12)$$

and

$$\begin{aligned} z_t + \lambda_1 z_x &= \varepsilon z_{xx} - \varepsilon(z_{hh}h_x^2 + 2z_{hm}h_x m_x + z_{mm}m_x^2) - gb \\ &= \varepsilon z_{xx} - \varepsilon(-2h^{-2}h_x m_x + 2(m + 1)h^{-3}h_x^2) - gb \\ &= \varepsilon z_{xx} + 2\varepsilon h^{-1}h_x z_x - gb. \end{aligned} \quad (4.13)$$

Lemma 7 (A). *Let the initial data $(h_0(x), u_0(x))$ be bounded measurable and $h_0(x) \geq c_0 > 0$ such that*

$$c_1 \leq w(h_0(x), u_0(x)) \leq c_2 < d_1 \leq z(h_0(x), u_0(x)) \leq d_2 \quad (4.14)$$

for some constants $c_i, d_i, i = 1, 2$. Then the viscosity solutions of the Cauchy problem (4.10) and (4.11) exist and have the estimates

$$c_1 - gbt \leq w(h^\varepsilon, u^\varepsilon) \leq c_2 - gbt < d_1 - gbt \leq z(h^\varepsilon, u^\varepsilon) \leq d_2 - gbt. \quad (4.15)$$

(B). *If the total variations of $w(h_0(x), u_0(x))$ and $z(h_0(x), u_0(x))$ are bounded in $(-\infty, \infty)$, then $z_x^\varepsilon(\cdot, t)$ and $w_x^\varepsilon(\cdot, t)$ are uniformly bounded in L^1 .*

(C). *If the conditions in (A) and (B) are satisfied, we may select a subsequence (still labelled) $(h^\varepsilon(x, t), u^\varepsilon(x, t))$ such that*

$$(h^\varepsilon(x, t), u^\varepsilon(x, t)) \rightarrow (h(x, t), u(x, t)), \quad (4.16)$$

a.e. on any bounded and open set $\Omega \subset R \times R^+$.

Proof of Lemma 7. By using the maximum principle to (4.12) and (4.13), we can easily prove the estimates in (4.15), which coupled with (4.5) and (4.15) reduce the following L^∞ estimates about $(h^\varepsilon, u^\varepsilon)$

$$0 < \frac{2}{d_2 - c_1} \leq h^\varepsilon \leq \frac{2}{d_1 - c_2}, \quad \frac{c_1 + d_1}{2} - gbt \leq u^\varepsilon \leq \frac{c_1 + d_1}{2} - gbt, \quad (4.17)$$

which ensure the existence of the viscosity solutions for the Cauchy problem (4.10) and (4.11).

Applying for the technique in the proof of Theorem 1, we can also prove that $z_x^\varepsilon(\cdot, t)$ and $w_x^\varepsilon(\cdot, t)$ are uniformly bounded in $L^1(R)$.

Finally, from the conclusions in (B), we have that $h_x^\varepsilon(\cdot, t)$ and $u_x^\varepsilon(\cdot, t)$ are bounded in $L^1(R)$, and so compact in $H_{loc}^{-1}(R \times R^+)$. Using the same technique in the proof of Theorem 1, we can easily prove that $h_t^\varepsilon + (h^\varepsilon u^\varepsilon)_x$ and $(h^\varepsilon u^\varepsilon)_t + (h^\varepsilon (u^\varepsilon)^2 - \frac{1}{h^\varepsilon})_x$ are compact in $H_{loc}^{-1}(R \times R^+)$. So we may apply for the div-curl lemma to the following pairs of functions

$$(c, h^\varepsilon), \quad (h^\varepsilon, h^\varepsilon u^\varepsilon) \quad (4.18)$$

to obtain

$$\overline{h^\varepsilon} \cdot \overline{h^\varepsilon} = \overline{(h^\varepsilon)^2} \quad (4.19)$$

which implies the pointwise convergence of h^ε . Then we apply for the div-curl lemma to the pairs of functions

$$(c, u^\varepsilon), \quad (h^\varepsilon u^\varepsilon, h^\varepsilon (u^\varepsilon)^2 - \frac{1}{h^\varepsilon}) \quad (4.20)$$

to obtain

$$\overline{u^\varepsilon} \cdot \overline{h^\varepsilon u^\varepsilon} = \overline{h^\varepsilon (u^\varepsilon)^2} \quad (4.21)$$

which implies the pointwise convergence of u^ε since the pointwise convergence of h^ε . Thus we complete the proof of Lemma 7.

Now we end this paper by the following theorem.

Theorem 8 *Let $P(h) = -h^{-1}$. If the initial data $(h_0(x), u_0(x), v_0(x), F_0(x))$ are bounded in L^∞ ; $(h_{0x}(x), u_{0x}(x), v_{0x}(x), F_{0x}(x))$ are bounded in $L^1(R)$; $h_0(x) \geq c_0 > 0$ such that*

$$c_1 \leq w(h_0(x), u_0(x)) \leq c_2 < d_1 \leq z(h_0(x), u_0(x)) \leq d_2 \quad (4.22)$$

for some constants $c_i, d_i, i = 1, 2$, then the Cauchy problem (4.1) and (1.9) has a weak solution (h, u, v, F) . Moreover, $(h_x(\cdot, t), u_x(\cdot, t), v_x(\cdot, t), F_x(\cdot, t))$ are uniformly bounded in $L^1(R)$.

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