

## Eksamen juni 2005



HØGSKOLEN  
I SØR-TRØNDELAG

$$\textcircled{1} \quad t \in \mathbb{R} \quad A_t = \begin{bmatrix} t & 0 & 0 & 0 \\ 0 & 1 & t & 0 \\ 0 & 0 & 1 & t \\ 0 & t & 0 & 1 \end{bmatrix}$$

a) Undersøker når  $\det(A_t) = 0$ .

$$\begin{aligned} \det(A_t) &= t \begin{vmatrix} 1 & t & 0 \\ 0 & 1 & t \\ t & 0 & 1 \end{vmatrix} = t \left( 1 \begin{vmatrix} 1 & t \\ 0 & 1 \end{vmatrix} - t \begin{vmatrix} 0 & t \\ t & 1 \end{vmatrix} \right) \\ &= t + t^4 = t(1+t^3) \end{aligned}$$

$$\det(A_t) = 0 \Leftrightarrow t(1+t^3) = 0$$

$$t = 0 \vee t = -1$$

Da er  $\text{rang}(A_t) = 4$  når  $t \neq 0 \wedge t \neq -1$ .  
Undersøker  $A_0, A_{-1}$ :

$$A_0 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad \text{rang}(A_0) = 3$$

$$A_{-1} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & -1 & 0 & 1 \end{bmatrix} \sim \dots \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \quad \text{rang}(A_{-1}) = 3$$

$$\text{så } \text{rang}(A_t) = \begin{cases} 4 & \text{når } t \neq 0 \wedge t \neq -1 \\ 3 & \text{når } t = 0 \vee t = -1 \end{cases}$$

b) 1. Nøyaktig en løsning: når  $\text{rang}(A_t) = 4$ ,  
dvs.  $t \neq 0 \wedge t \neq -1$ .

Setter totalmatrisen til opp systemet for  $t=0$  og  $t=-1$ :

$$\tilde{A}_0 = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

her er  $\text{rang}(A_0) = 3 < \text{rang}(\tilde{A}_0) = 4$ , så  
for  $t=0$  har systemet ingen løsning.

$$\tilde{A}_{-1} = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 & 2 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 1 & 0 & 1 & -3 \end{bmatrix} \sim \begin{bmatrix} -1 & 0 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 & 2 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & -1 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} -1 & 0 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 & 2 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

her er  $\text{rang}(A_{-1}) = 3 = \text{rang}(\tilde{A}_{-1}) < 4$  (# ukjente), så  
for  $t=-1$  har systemet uendelig mange løsninger.

1)  $t \neq 0 \wedge t \neq -1$

2)  $t = 0$

3)  $t = -1$

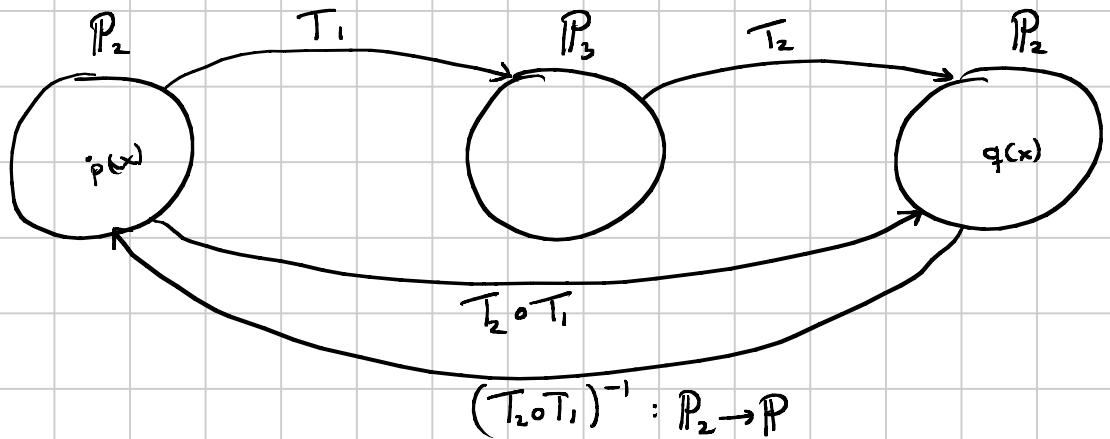
②

$$p_1(x) = a_0 + a_1x + a_2x^2$$

$$p_2(x) = a_0 + a_1x + a_2x^2 + a_3x^3$$

$$T_1: \mathbb{P}_2 \rightarrow \mathbb{P}_3, \quad T_1(p) = xp(x), \quad T_1(p) = a_0x + a_1x^2 + a_2x^3$$

$$T_2: \mathbb{P}_3 \rightarrow \mathbb{P}_2, \quad T_2(p) = \frac{d}{dx}p(x), \quad T_2(p) = a_1 + 2a_2x + 3a_3x^2$$



$$(T_2 \circ T_1)(p) = T_2(T_1(p)) = T_2(a_0x + a_1x^2 + a_2x^3) \\ = a_0 + 2a_1x + 3a_2x^2$$

mit  $q(x) = b_0 + b_1x + b_2x^2 \in \mathbb{P}_2$  vil vi finne  $p(x) = a_0 + a_1x + a_2x^2$

$$p(x) = (T_2 \circ T_1)^{-1}(q(x))$$

$$\Downarrow$$

$$(T_2 \circ T_1)p = q$$

$$a_0 + 2a_1x + 3a_2x^2 = b_0 + b_1x + b_2x^2$$

$$\Downarrow$$

$$a_0 = b_0$$

$$a_0 = b_0$$

$$2a_1 = b_1 \quad \Leftrightarrow$$

$$a_1 = \frac{1}{2}b_1$$

$$3a_2 = b_2$$

$$a_2 = \frac{1}{3}b_2$$

$$\text{dvs. } (T_2 \circ T_1)^{-1}(q) = (T_2 \circ T_1)^{-1}(b_0 + b_1x + b_2x^2) = p(x) \\ = b_0 + \frac{b_1}{2}x + \frac{b_2}{3}x^2$$

b)  $B = \{1, (x-1), (x-1)^2\}$  ←

skal finne  $[(T_2 \circ T_1)]_B$ .  
 dvs.

$$\left[ [(T_2 \circ T_1)(1)]_B \quad [(T_2 \circ T_1)(x-1)]_B \quad [(T_2 \circ T_1)((x-1)^2)]_B \right]$$

$$(T_2 \circ T_1)(1) = T_2(T_1(1)) = 1 \quad [(T_2 \circ T_1)(1)]_B = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$(T_2 \circ T_1)(x-1) = T_2(T_1(x-1)) = 2x-1 \quad [(T_2 \circ T_1)(x-1)]_B = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$$

$x^2-x$   
 $2(x-1)+1$

$$c_1 \cdot 1 + c_2 \cdot (x-1) + c_3 \cdot (x-1)^2 = 2x-1$$

$V_1$        $V_2$        $V_3$        $x^2-2x+1$

$$c_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ 0 \end{pmatrix}$$

↑  $\{1, x, x^2\}$

$$\begin{aligned} (T_2 \circ T_1)((x-1)^2) &= T_2(T_1((x-1)^2)) \\ &= T_2(T_1(x^2-2x+1)) = T_2(x^3-2x^2+x) \\ &= 3x^2-4x+1 \end{aligned}$$

$$= 3(x-1)^2 + 2(x-1) + 0 \cdot 1$$

$$\frac{3x^2 - 6x + 3 + 2x - 2}{3x^2 - 4x + 1}$$

$$[(T_2 \circ T_1)((x-1)^2)]_B = \begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix} \quad [(T_2 \circ T_1)]_B = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix}$$

c) Skal finne rang og nullitet til  $T_2: \mathbb{P}_3 \rightarrow \mathbb{P}_2$

Rang-teoremet:  $\text{rang}(T_2) + \text{nullity}(T_2) = \dim(\mathbb{P}_3)$

$$\dim(R(T_2)) + \dim(\ker(T_2)) = 4$$

$$\ker(T_2) = \{q \in \mathbb{P}_3 : T_2(q) = 0\} = \{q \in \mathbb{P}_3 : \frac{dq}{dx} = 0\}$$

$$= \{\text{konstanter}\} = \text{span}\{1\}$$

så  $\dim(\ker(T_2)) = \underline{\underline{1}} = \text{nullity}(T_2)$

Da er  $\text{rang}(T_2) = 4 - \text{nullity}(T_2) = 4 - 1 = \underline{\underline{3}}$

⑤  $A \in M_{nn}$ , og  $A^* = -A$ .  $A^* = \overline{A}^T$

Skal vise at egenverdiene til  $A$  er rene imaginære tall.

$$Ax = \lambda x, \text{ anta at } x^*x = 1$$

$$x^*Ax = x^*\lambda x = \lambda x^*x = \lambda I_1 = \lambda \leftarrow \text{tall}$$

$$\lambda^* = \overline{\lambda}$$

$$\lambda^* = (x^*Ax)^* = x^*A^*x^{**} = x^*A^*x \stackrel{A^* = -A}{=} -x^*Ax = -\lambda$$

Har vist:  $\overline{\lambda} = -\lambda$

$$\left. \begin{array}{l} \lambda = a+ib \\ \overline{\lambda} = a-ib \end{array} \right\} \overline{\lambda} = -\lambda$$
$$\begin{array}{l} a-ib = -(a+ib) \\ a-ib = -a-ib \\ 2a = 0 \end{array}$$

så  $\lambda = ib$ , rent imaginært. ( $i = \sqrt{-1}$ )

## Oppgave 5 nov. 96

1. Skal vise at  $T: P_2 \rightarrow P_2$  gitt ved  $T(f) = f + f' + f''$  er en lineær transformasjon.

$$(*) \quad T(f+g) = T(f) + T(g)$$

$$(**) \quad T(kf) = kT(f)$$

$$(*) \quad T(f+g) = (f+g) + (f+g)' + (f+g)'' = f + g + f' + g' + f'' + g''$$

$$= \underbrace{(f + f' + f'')} + \underbrace{(g + g' + g'')}$$

$$= T(f) + T(g)$$

$$(**) \quad T(kf) = (kf) + (kf)' + (kf)'' = k(f + f' + f'') = kT(f)$$