MA8701 Advanced methods in statistical inference and learning Part 3: Ensembles. L14: Boosting

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Added efter class

Part 3: plan Wisdom of the crowds LIS Bagging Trees Rendomforest Boosting + video L15 Hyperperender L16 Stached ensembles Evaluating and comparing results_ LIT from prediction models

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Literature

- [ESL] The Elements of Statistical Learning: Data Mining, Inference, and Prediction, Second Edition (Springer Series in Statistics, 2009) by Trevor Hastie, Robert Tibshirani, and Jerome Friedman. Ebook. Chapter 10.1-10.6, 10.9-10.10, 10.12, 10.13 (in Part 4).
- Video by Berent Lunde (link on Bb), covering Chapter 10 (in particular 10.10) and the Chen and Guestrin paper.
- Chen, T., & Guestrin, C. (2016). XGBoost: A Scalable Tree Boosting System. In Proceedings of the 22nd ACM SIGKDD International Conference on Knowledge Discovery and Data Mining (pp. 785–794). New York, NY, USA: ACM. https://doi.org/10.1145/2939672.2939785. The mathematical notation is not in focus



Figure 1: Hastie, Tibshirani, and Friedman (2009) Figure 10.1



Boosting Iterations

Algorithm 10.1 AdaBoost.M1.

1. Initialize the observation weights $w_i = 1/N, i = 1, 2, ..., N$. Equal weight on all obs.

- 2. For m = 1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training data using weights w_i . In m_i

(b) Compute

$$\operatorname{err}_{m} = \frac{\sum_{i=1}^{N} w_{i} I(y_{i} \neq G_{m}(x_{i}))}{\sum_{i=1}^{N} w_{i}}. \quad \notin \{0, 0\}$$

$$\xrightarrow{} (c) \text{ Compute } \alpha_{m} = \log((1 - \operatorname{err}_{m})/\operatorname{err}_{m}).$$

$$(d) \text{ Set } w_{i} \leftarrow w_{i} \cdot \exp[\alpha_{m} \cdot I(y_{i} \neq G_{m}(x_{i}))], \quad i = 1, 2, \dots, N.$$
3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_{m} G_{m}(x)\right].$

Figure 3: Hastie, Tibshirani, and Friedman (2009) Algorithm 10.1



Understanding AdaBoost.M1

AIM: Why does this work and how to develop further.



${\cal G}(x)$ is an additive model

Gm(x) elementary basis finden and Adakant [4] =n
additue set of these on Gn(x) could be intu
f(x) =
$$\sum_{m=1}^{M} \operatorname{Bm} \cdot D(x; ym)$$
 could be intu
inverproduction
GLA > GAM
expansion with parand (j,s)
result spht
Additue nodes are known outsude boosting and is tit
by minimzing some loss h over the transpect
min $\sum_{j=1}^{N} L(y_i) \sum_{m=1}^{B} \operatorname{Bm} b(x_i; ym)$

Algorithm 10.2 Forward Stagewise Additive Modeling.

- 1. Initialize $f_0(x) = 0$. Initialize $f_0(x) = 0$.
- 2. For m = 1 to M:
 - (a) Compute



Figure 4: Hastie, Tibshirani, and Friedman (2009) Algorithm 10.2

Forward Stagewise Additive Modelling with Exponential loss = Ada Boost, MI



The steps of the develop
1)
$$(p_{m_{j}}b_{m}) = agam \sum_{i=1}^{N} \omega_{i}^{(m-1)} \cdot exp(-y_{i} \cdot pb(x_{i}))$$

 $exp(-y_{i} \cdot f^{(m-1)}(x_{i}))$
2) $bm : ergmin \left\{ \sum_{i=1}^{N} \omega_{i}^{(m-1)} I(y_{i} \cdot pb(x_{i})) \right\}$
 $bm : ergmin \left\{ \sum_{i=1}^{N} \omega_{i}^{(m-1)} I(y_{i} \cdot pb(x_{i})) \right\}$
 $minimize the weighted model rank
 $gm = \pm ln\left(\frac{l-erc_{n}}{ern}\right)$
 $d_{m} = 2gm$
 $scaly$
 4) $\omega_{i}^{(m)} = \omega_{i}^{(m-1)} \cdot exp\left(dm T(y_{i} \cdot pb(x_{i})) - exp\left(-\frac{dm}{2}\right)\right)$$

Group discussion:

We showed

Iook at this derivation of the equivalence of the AdaBoost.M1 and the forward stagewise modelling with exponential loss.

For the steps 2a-2d in Algorithm 10.1 what is your new insight into what is done at each step? Algorithm 10.1 AdaBoost.M1.

1. Initialize the observation weights
$$w_i = 1/N$$
, $i = 1, 2, ..., N$.
2. For $m = 1$ to M :
 $b_m = \operatorname{argain}(\sum w_i^{(a-i)} \operatorname{I}(y_i \neq b(x_i)))$
(a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
(b) Compute
 $\operatorname{err}_m = \frac{\sum_{i=1}^N w_i I(y_i \neq G_m(x_i))}{\sum_{i=1}^N w_i}$. intermediate
(c) Compute $\alpha_m = \log((1 - \operatorname{err}_m)/\operatorname{err}_m)$. Solution to compare $\sum_{i=1}^N \omega_i^{N-1} \exp(-\psi_i p \log y_i)$
(d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, ..., N$.
3. Output $G(x) = \operatorname{sign}\left[\sum_{m=1}^M \alpha_m G_m(x)\right]$.

Figure 3: Hastie, Tibshirani, and Friedman (2009) Algorithm 10.1

What is great with exponential loss?

1) computational: easy weight schence
2)
$$L(y, for) = exp(-y for))$$
 is not a reg logithhood, but
 $f(x) = argain E_{YIX} (e^{-Yfar})) \stackrel{\text{def}}{=} \frac{1}{2} \ln \frac{P(Y=A|X)}{P(Y=-A|X)} \leftarrow \frac{Exercise!}{ESL Ex (D:2)}$
to derive this
logistics
(line handburk)
Let can be shown that the negative knowed deviant can be written as
 $E(L(Lt e^{-2Yfar}))$ both lowe the minimum $\rightarrow \infty$

But for finite does sets: gue different results, although both functions of y.fa)



Figure 17.12 Exponential loss used in Adaboost, versus the binomial loss used in the usual logistic regression. Both estimate the logit function. The exponential left tail, which punishes misclassifications, is much more severe than the asymptotically linear tail of the binomial.

Figure 5: Efron and Hastie (2016) Figure 17.10: Importance of learning



FIGURE 10.3. Simulated data, boosting with stumps: misclassification error rate on the training set, and average exponential loss: $(1/N) \sum_{i=1}^{N} \exp(-y_i f(x_i))$. After about 250 iterations, the misclassification error is zero, while the exponential loss continues to decrease.

Based on the insight gared from AdaBorst Friedran in 2000 proverled "gradient booshing" - we will book at trees as the base learners.

Estimation of some function of can be done by minimizing a differtiable loss (and also convex) by applying

"functional gradient descent". The function of is en additive expension of base learnes, and each step (new learner) goes in the direction of the negative gradient of the loss function at the current function estimate

Gradient boosting

Algorithm 10.3 Gradient Tree Boosting Algorithm.

- 1. Initialize $f_0(x) = \arg \min_{\gamma} \sum_{i=1}^N L(y_i, \gamma)$. = awely
- 2. For m = 1 to M: (a) For i = 1, 2, ..., N compute $- \underset{f}{\overset{h}{=}} \underbrace{\sharp} (g - f)^2 = (y - f)^k$

$$r_{im} = - \left[\frac{\partial L(y_i, f(x_i))}{\partial f(x_i)} \right]_{f=f_{m-1}}^{\text{regshegodor}}$$

ensure when if $L(y,f) = \frac{1}{2}(y-f)^2$?

(b) Fit a regression tree to the targets r_{im} giving terminal regions $R_{jm}, j = 1, 2, ..., J_m$. (c) For $j = 1, 2, ..., J_m$ compute $\gamma_{jm} = \arg \min_{\gamma} \sum_{x_i \in R_{jm}} L(y_i, f_{m-1}(x_i) + \gamma)$. But, there is no weighty of the observe hore! Now insked We work with the value of the negetive greatent at the bot shep of the algo - for each observe in shep observe to the sum of the residuals.

this method is called first order GTB - and second order involves the Heilian (done kyboost) - watch Berent-rides.

Gradient boosting (1'st order)





Figure 9: Guest lecture by Berent (at 25 minutes in the video)

Comments from Berent: essential to add an extra learning rate δ between 0 and 1 and $\delta = 0.05$ not uncommon. In Hastie, Tibshirani, and Friedman (2009) 10.12.1 Equation (10.41).



Figure 17.10 Boosted d = 3 models with different shrinkage parameters, fit to a subset of the ALS data. The solid curves are validation errors, the dashed curves training errors, with red for $\epsilon = 0.5$ and blue for $\epsilon = 0.02$. With $\epsilon = 0.5$, the training error drops rapidly with the number of trees, but the validation error starts to increase rapidly after an initial decrease. With $\epsilon = 0.02$ (25 times smaller), the training error drops more slowly. The validation error also drops more slowly, but reaches a lower minimum (the horizontal dotted line) than the $\epsilon = 0.5$ case. In this case, the slower learning has paid off.





FIGURE 10.9. Boosting with different sized trees, applied to the example (10.2) used in Figure 10.2. Since the generative model is additive, stumps perform the best. The boosting algorithm used the binomial deviance loss in Algorithm 10.3;

Regularization

(10.12)

- \triangleright The number of weak learners, M, is chosen by monitoring prediction risk on a validation sample (same as early stopping in Deep nets - stop training when error validation set increases). fm(x) = fm (x) + 2. tree
- Learning rate low rate generally recommended, but may lead to \underline{M} then being large. (2d in Algo 10.3 add $\underline{\nu}$.) Sharkege on
- Decorrelated functions: subsampling of both obserations (rows) and variables (columns). Same motivation as for random forest. When subsampl observations this is also called stochastic gradient boosting.



L1 and L2 regularization term can be added (more in 16.2)



FIGURE 10.11. Test error curves for simulated example (10.2) of Figure 10.9, using gradient boosting (MART). The models were trained using binomial deviance, either stumps or six terminal-node trees, and with or without shrinkage. The left panels report test deviance, while the right panels show misclassification error. The beneficial effect of shrinkage can be seen in all cases, especially for deviance in the left panels.

Video by Berent — part 1

Repleces lecture 03.07.2023

01:40 Berent starts - with motivation

- 11:45: Boosting timeline
- 16:27: Boosting principle
- 18:42: AdaBoost
- 22:45: From AdaBoost to gradient boosting
- 31:26: Relationship to L1 regularization
- 34:39: Techniques for improvement

End of first part

Video by Berent — part 2

-38:10 Gradient Tree Boosting 127 39:15: Why does trees work 43:49: 2nd order GTB 52:17: Algorithm for 2nd order GTB 55:07: Loss vs complexity trade-off in GTB 56:05: XGBoost 1:02 XGBoost regularization 1:03 Hyperparameter tuning 1:10: Other GTB implmentations (LightGBM, CatBoost, NGBoost) End of part two



Video by Berent — part 3

1:20 Answer questions1:22 Automatic GTB (not on the reading list - the phd-topic of Berent)1:49 Full lecture recap