

Functions of several variables.

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A function f of n real variables is a rule that assigns a unique number $f(x_1, \dots, x_n)$ to each point $(x_1, \dots, x_n) \in D \subseteq \mathbb{R}^n$. The set D is called the domain of f .

Here, we will usually let $D = \mathbb{R}^n$.

Ex 1: $f(x, y) = x^2 \cdot \sin(y)$ $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

Ex 2: $f(x, y, z) = x^2 + y^2 \cdot z^4$ $f: \mathbb{R}^3 \rightarrow \mathbb{R}$

Ex 3: $f(x, y) = x \cdot \sqrt{y}$ $f: \mathbb{R} \times \mathbb{R}^+ \rightarrow \mathbb{R}$, $\mathbb{R}^+ = [0, \infty)$

Partial derivatives

For simplicity, let $f = f(x, y)$.

The first partial derivative of f with respect to x and y are the functions given by

$$\frac{\partial f}{\partial x}(x, y) = \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h}$$

$$\frac{\partial f}{\partial y}(x, y) = \lim_{h \rightarrow 0} \frac{f(x, y+h) - f(x, y)}{h}$$

In general:

The partial derivative of f with respect to one variable is the derivative of the one-variable function obtained by keeping all other constant.

Ex 1: $f(x, y) = x^2 \cdot \sin(y)$, $\frac{\partial f}{\partial x} = 2x \sin(y)$, $\frac{\partial f}{\partial y} = x^2 \cos(y)$

Ex 2: $f(x, y, z) = x^2 + y^2 \cdot z^4$

$$\frac{\partial f}{\partial x} = 2x, \quad \frac{\partial f}{\partial y} = 2y z^4, \quad \frac{\partial f}{\partial z} = 4y^2 z^3$$

Notation: Unfortunately, there are many different notation for the partial derivatives, and they are not always used in a consistent way. So, given $f(x,y)$, ②

$\frac{\partial f}{\partial x}$, f_x , $\partial_x f$ are all the same.

and similar for y , etc.

The gradient

Given $f: \mathbb{R}^n \rightarrow \mathbb{R}$. The gradient of f is the vector function

$$\vec{\nabla} f = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right), \text{ so } \nabla f : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\text{Ex 1: } f(x,y) = x^2 \sin(y), \quad \vec{\nabla} f = (2x \sin(y), x^2 \cos(y))$$

$$\text{Ex 2: } f(x,y,z) = x^2 + y^2 z^4, \quad \vec{\nabla} f = (2x, 2yz^4, 3y^2 z^3)$$

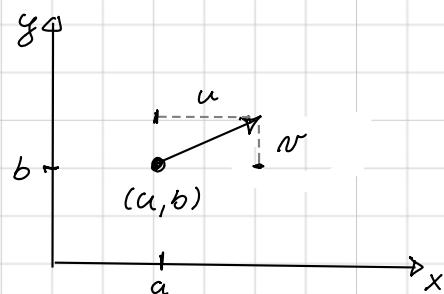
Directional derivative:

For simplicity, let $n=2$.

Given a function $f(x,y)$, a point $\vec{a} = (a,b)$ and a unit vector $\vec{u} = (u,v)$ ($u^2 + v^2 = 1$).

$$\begin{aligned} \vec{x}(t) &= \vec{a} + t \cdot \vec{u} \\ &= (a + tu, b + tv), \quad t \in \mathbb{R} \\ &= (x(t), y(t)) \end{aligned}$$

represent a straight line through \vec{a} in the direction \vec{u} .



$f(\vec{x}(t))$ is then the cross section of the surface $f(x,y)$ along $\vec{x}(t)$. It is a function of t alone, so, by the chain rule we obtain:

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dt} = \frac{\partial f}{\partial x} \cdot u + \frac{\partial f}{\partial y} \cdot v = \vec{\nabla} f \cdot \vec{u}$$

which is called the directional derivative of f , in the direction \vec{u} , denoted as $D_{\vec{u}} f$.

$$\text{Ex 1: } f(x, y) = x^2y + y^2, \vec{a} = (2, 1), \vec{u} = \frac{1}{\sqrt{2}}(1, 1) \quad (3)$$

$$\vec{\nabla}f = (2xy, x^2 + 2y)$$

$$\vec{\nabla}f(\vec{a}) = (2 \cdot 2 \cdot 1, 2^2 + 2 \cdot 1) = (4, 6)$$

$$D_{\vec{u}} f(\vec{a}) = (4, 6) \cdot \frac{1}{\sqrt{2}}(1, 1) = \frac{10}{\sqrt{2}}$$

$$\text{Ex 2: } f(x, y, z) = xe^z + y, \vec{a} = (1, 1, 0), \vec{u} = \frac{1}{3}(2, 2, 1)$$

$$\vec{\nabla}f = (e^z, 1, xe^z)$$

$$\vec{\nabla}f(\vec{a}) = (e^0, 1, 1 \cdot e^0) = (1, 1, 1)$$

$$D_{\vec{u}} f(\vec{a}) = (1, 1, 1) \cdot \frac{1}{3}(2, 2, 1) = \frac{5}{3}.$$

Interpretation of the gradient:

At a point \vec{a} , the function $f(\vec{x})$ increase most rapidly in the direction of the vector $\vec{\nabla}f(\vec{a}) / \|\vec{\nabla}f(\vec{a})\|$, and the maximum rate of increase is $\|\vec{\nabla}f(\vec{a})\|$.

$$\text{NB! } \|\vec{x}\| = \left(\sum_{i=1}^n x_i^2 \right)^{1/2}.$$

Jacobi-matrix (Jacobian).

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Given $\vec{f}: \mathbb{R}^n \rightarrow \mathbb{R}^n$, thus

$$\vec{f}(\vec{x}) = \begin{pmatrix} f_1(x_1, x_2, \dots, x_n) \\ f_2(x_1, x_2, \dots, x_n) \\ \vdots \\ f_n(x_1, x_2, \dots, x_n) \end{pmatrix}$$

The Jacobian of f is the matrix function $J: \mathbb{R}^n \rightarrow \mathbb{R}^{n \times n}$ with elements

$$J_{ij}(x) = \frac{\partial f_i}{\partial x_j}.$$

So, for $n=2$, and

$$\vec{f}(\vec{x}) = \begin{pmatrix} f(x, y) \\ g(x, y) \end{pmatrix}$$

the Jacobian is

$$J(\vec{x}) = \begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix}$$

$$\vec{f}(\vec{x}) = \begin{pmatrix} x^2 \sin(y) + z^3 \\ x \cdot z \\ x^2 + y^2 + e^{xy} \end{pmatrix}$$

$$J(\vec{x}) = \begin{pmatrix} 2x \sin(y) & x^2 \cos(y) & 3z^2 \\ z & 0 & x \\ 2x & 2y + ze^{xy} & ye^{xy} \end{pmatrix}$$

Higher order partial derivatives.

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This is again best described by example.

Let $n = 2$. Given $f(x, y)$ ($f: \mathbb{R}^2 \rightarrow \mathbb{R}$)

Then $\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right)$, $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right)$
 $\frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right)$, $\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)$

NB! $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$ (there are exceptions, those will not be covered in this course)

Notation: $\frac{\partial^2 f}{\partial x^2} = f_{xx} = \frac{\partial^2 f}{\partial x^2}$, $\frac{\partial^2 f}{\partial y^2} = f_{yy} = \frac{\partial^2 f}{\partial y^2}$
 $\frac{\partial^2 f}{\partial x \partial y} = f_{xy} = \frac{\partial}{\partial x} \frac{\partial f}{\partial y}$

The Hessian (Hess matrix) is the matrix function

$H_f(\vec{x})$ with elements $\frac{\partial^2 f}{\partial x_i \partial x_j}$.

So if $f = f(x, y)$, then

$$H_f(\vec{x}) = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

- The Hessian is the Jacobian of the gradient.

Ex: $f(x, y) = x^2 y^3$

$$\vec{\nabla} f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) = (2x y^3, 3x^2 y^2)$$

$$\frac{\partial^2 f}{\partial x^2} = 2y^3, \quad \frac{\partial^2 f}{\partial x \partial y} = 6x y^2, \quad \frac{\partial^2 f}{\partial y^2} = 6x^2 y$$

and $H_f(\vec{x}) = \begin{pmatrix} 2y^3 & 6x y^2 \\ 6x y^2 & 6x^2 y \end{pmatrix}$

The chain rule:

Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ and $\vec{x}: \mathbb{R} \rightarrow \mathbb{R}^n$, e.g.

$$g(t) = f(x_1(t), x_2(t), \dots, x_n(t)).$$

Then $g(t)$ is a function of one variable, and the total derivative of g (with respect to t) is

$$\frac{dg}{dt} = \frac{\partial f}{\partial x_1} \frac{dx_1}{dt} + \frac{\partial f}{\partial x_2} \frac{dx_2}{dt} + \dots + \frac{\partial f}{\partial x_n} \frac{dx_n}{dt} = \vec{\nabla} f \circ \frac{d\vec{x}}{dt}$$

NB! We use $\frac{d\vec{x}}{dt}$ if there is only one free variable.

Ex: $\vec{x}(t) = (x(t), y(t)) = (\cos(t), \sin(t))$

$$f(x, y) = x^2 \cdot y^3 \quad \text{and} \quad g(t) = f(x(t), y(t)), \text{ then}$$

$$\frac{dg}{dt} = 2 \cdot x(t) \cdot y(t)^3 \cdot \frac{dx}{dt} + 3x(t)^2 \cdot y(t)^2 \cdot \frac{dy}{dt}$$

$$= 2\cos(t) \cdot \sin^3(t) \cdot (-\sin(t)) + 3\cos^2(t) \cdot \sin(t) \cdot \cos^2(t)$$

$$= \cos(t) \cdot \sin^2(t) \cdot (3\cos^2(t) - 2\sin^2(t))$$

Taylor-series:

Given $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $\vec{a} \in \mathbb{R}^n$ and $\vec{v} \in \mathbb{R}^n$.
Then

$$f(\vec{a} + \vec{v}) = f(\vec{a}) + \vec{\nabla} f(\vec{a}) \cdot \vec{v} + \vec{v}^T \cdot H_f(\vec{a}) \cdot \vec{v} + \dots.$$