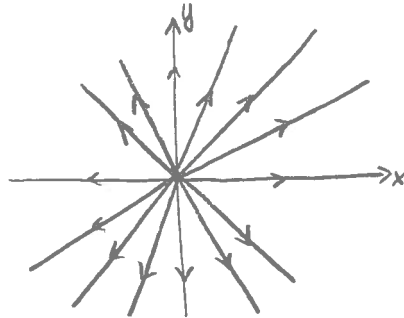


$$\dot{\vec{x}} = A\vec{x} \text{ WITH } \det(A) \neq 0.$$

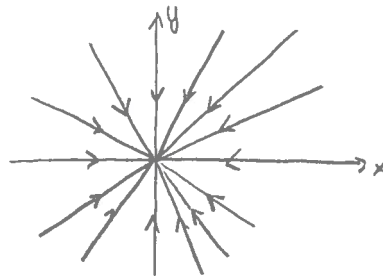
(iii) A... $\lambda_1 = \lambda_2$, TWO LIN. IND. EIGENVECTORS:

$$\lambda_1 > 0:$$



DEGENERATE
UNSTABLE
NODE

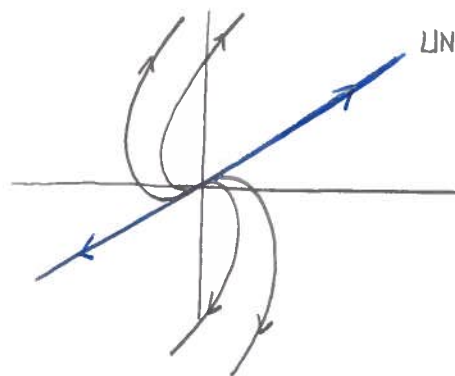
$$\lambda_1 < 0:$$



DEGENERATE
STABLE
NODE

(iii) A... $\lambda_1 = \lambda_2$, ONE LIN. IND. EIGENVECTOR: $A\vec{v}_1 = \lambda_1\vec{v}_1$, $A\vec{v}_2 = \lambda_1\vec{v}_2 + \vec{v}_1$

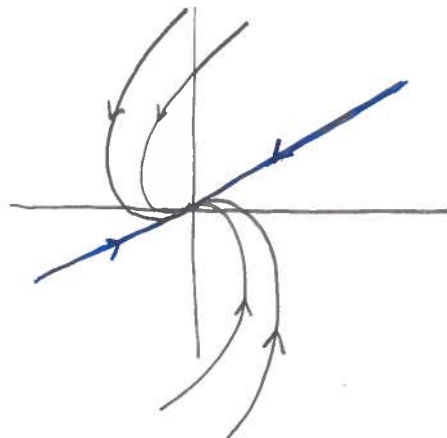
$$\lambda_1 > 0$$



LINE SPANED BY $\vec{v}_1$

DEGENERATE
UNSTABLE
NODE

$$\lambda_1 < 0$$



DEGENERATE
STABLE
NODE

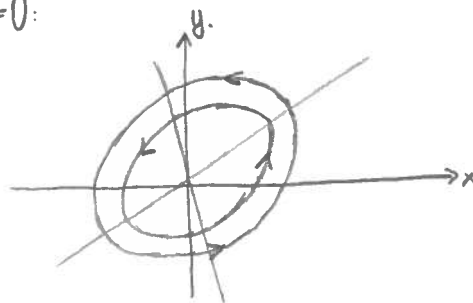
SOLUTION IS OF THE FORM

$$\vec{x}(t) = (B + Ct)e^{\lambda_1 t}\vec{v}_1 + Ce^{\lambda_1 t}\vec{v}_2$$

$$\dot{\vec{x}} = A\vec{x} \text{ WITH } \det(A) \neq 0$$

(iv) $A \dots \lambda_1 = \bar{\lambda}_2 \in \mathbb{C} \setminus \mathbb{R}, A\vec{v}_1 = \lambda_1\vec{v}_1$

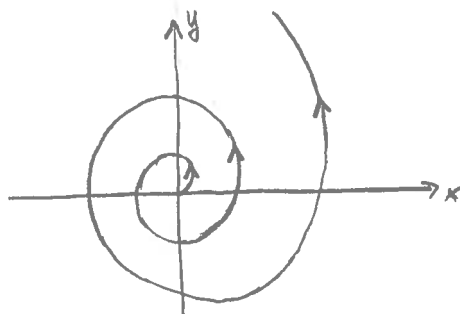
$\operatorname{Re}(\lambda_1) = 0:$



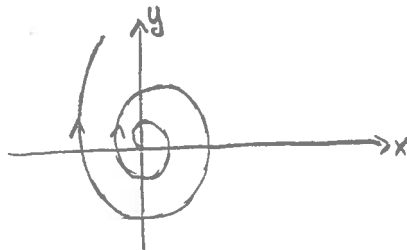
CENTER

ALSO ARROWS IN THE OPPOSITE DIRECTION POSSIBLE.

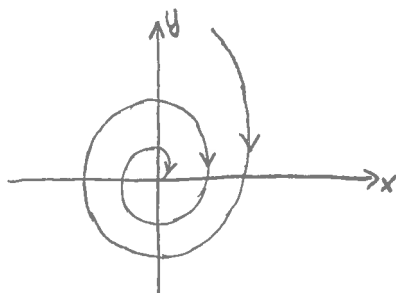
$\operatorname{Re}(\lambda_1) > 0:$



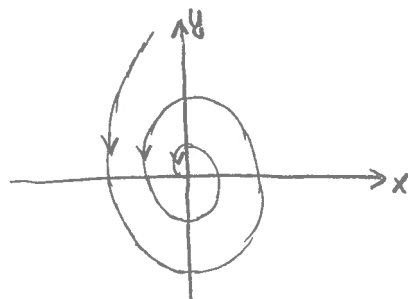
UNSTABLE SPIRAL



$\operatorname{Re}(\lambda_1) < 0$



STABLE SPIRAL



SOLUTION IS OF THE FORM

$$\vec{x}(t) = e^{\operatorname{Re}(\lambda_1)t} ((B \cos(\operatorname{Im}(\lambda_1)t) + C \sin(\operatorname{Im}(\lambda_1)t)) \operatorname{Re}(\vec{v}_1) + (-B \sin(\operatorname{Im}(\lambda_1)t) + C \cos(\operatorname{Im}(\lambda_1)t)) \operatorname{Im}(\vec{v}_1))$$