

1a) LET $A = \begin{pmatrix} 0 & -2 \\ 4 & 6 \end{pmatrix}$

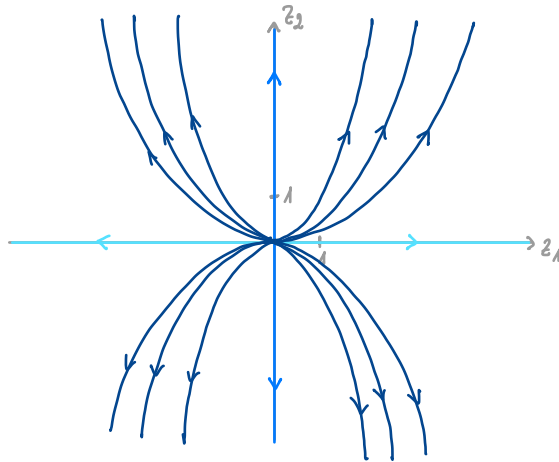
EIGENVALUES $\det(A - \lambda I) = 0$: $-\lambda(6 - \lambda) + 8 = 0$
 $\lambda^2 - 6\lambda + 8 = 0$
 $\lambda_{1,2} = 3 \pm \sqrt{9 - 8} = 3 \pm 1 \Rightarrow \lambda_1 = 2, \lambda_2 = 4$

EIGENVECTORS: $\lambda_1 = 2$ $(A - 2I)\vec{v}_1 = \begin{pmatrix} -2 & -2 \\ 4 & 4 \end{pmatrix} \vec{v}_1 = \vec{0} \Rightarrow \vec{v}_1 = c \begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad (c \in \mathbb{R})$

$\lambda_2 = 4$: $(A - 4I)\vec{v}_2 = \begin{pmatrix} -4 & -2 \\ 4 & 2 \end{pmatrix} \vec{v}_2 = \vec{0} \Rightarrow \vec{v}_2 = d \begin{pmatrix} 1 \\ -2 \end{pmatrix} \quad (d \in \mathbb{R})$

LET $P = [\vec{v}_1, \vec{v}_2] = \begin{pmatrix} 1 & 1 \\ -1 & -2 \end{pmatrix}$, $P^{-1} = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \Rightarrow A = P\Lambda P^{-1}$

PHASE DIAGRAM FOR $\dot{\vec{z}} = \Lambda \vec{z}$ WHERE $\vec{z} = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$



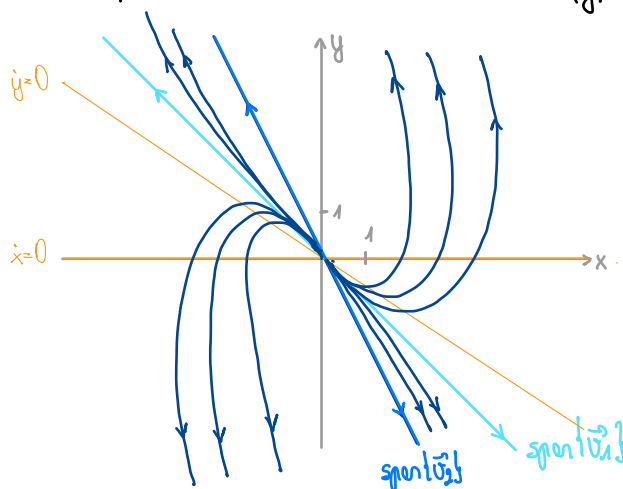
$$z_1(t) = e^{2t} z_1(0)$$

$$z_2(t) = e^{4t} z_2(0)$$

$$\Rightarrow z_2(t) = e^{4t} z_2(0) = (e^{2t} z_1(0))^2 \frac{z_2(0)}{z_1^2(0)} = z_1^2(t) \frac{z_2(0)}{z_1^2(0)}$$

OF THE FORM: $z_2 = \alpha z_1^2 \quad (\alpha \in \mathbb{R}, z_1 \neq 0)$

PHASE DIAGRAM FOR $\dot{\vec{x}} = A\vec{x}$ WHERE $\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$



ISOCINES:

$$\dot{x} = 0: -2y = 0 \Rightarrow y = 0$$

$$\dot{y} = 0: 4x + 6y = 0 \Rightarrow y = -\frac{2}{3}x$$

1b) GENERAL SOLUTION

$$\vec{x}(t) = c_1 e^{2t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 e^{4t} \begin{pmatrix} 1 \\ -2 \end{pmatrix} \quad (c_1, c_2 \in \mathbb{R})$$

SINCE $\lambda_1 = 2$ & $\lambda_2 = 4$ ARE POSITIVE: $\vec{x}(t) \rightarrow \vec{0} \Leftrightarrow \vec{x}_0 = \vec{0}$

$$2a) \text{ EP: } \begin{cases} \dot{x}=0 \Rightarrow y=-x-2 \\ \dot{y}=0 \Rightarrow y^2=-x \end{cases} \Rightarrow \begin{cases} y^2-y-2=0 \\ y^2=-x \end{cases} \Rightarrow \begin{cases} y_1, y_2 = \frac{1}{2} \pm \sqrt{\frac{1}{4}+2} = \frac{1}{2} \pm \frac{3}{2} \\ y^2=-x \end{cases}$$

$$\Rightarrow \text{TWO EP: } (-1, -1), (-4, 2)$$

$$\text{JACOBIAN: } Jf(\vec{x}) = \begin{pmatrix} 1 & 1 \\ 1 & 2y \end{pmatrix} \quad [f(\vec{x}) \dots \text{RHS OF THE SYSTEM, IE } \dot{\vec{x}} = f(\vec{x})]$$

$$\begin{aligned} \rightarrow Jf((-1, -1)) &= \begin{pmatrix} 1 & 1 \\ 1 & -2 \end{pmatrix}: \text{EIGENVALUES: } \det(Jf((-1, -1)) - \lambda I) = 0 \\ &(1-\lambda)(-2-\lambda)-1=0 \\ &-2+2\lambda-\lambda+\lambda^2-1=0 \\ &\lambda^2+\lambda-3=0 \\ &\lambda_{1,2} = -\frac{1}{2} \pm \sqrt{\frac{1}{4}+3} \Rightarrow \lambda_1 < 0 \text{ \& } \lambda_2 > 0 \end{aligned}$$

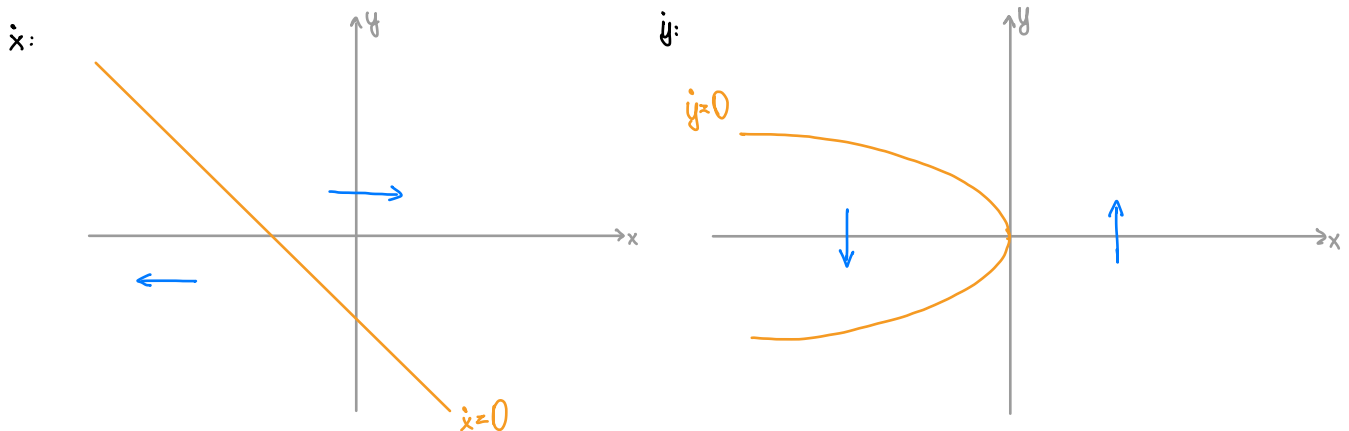
$\Rightarrow (-1, -1) \dots$ SADDLE POINT

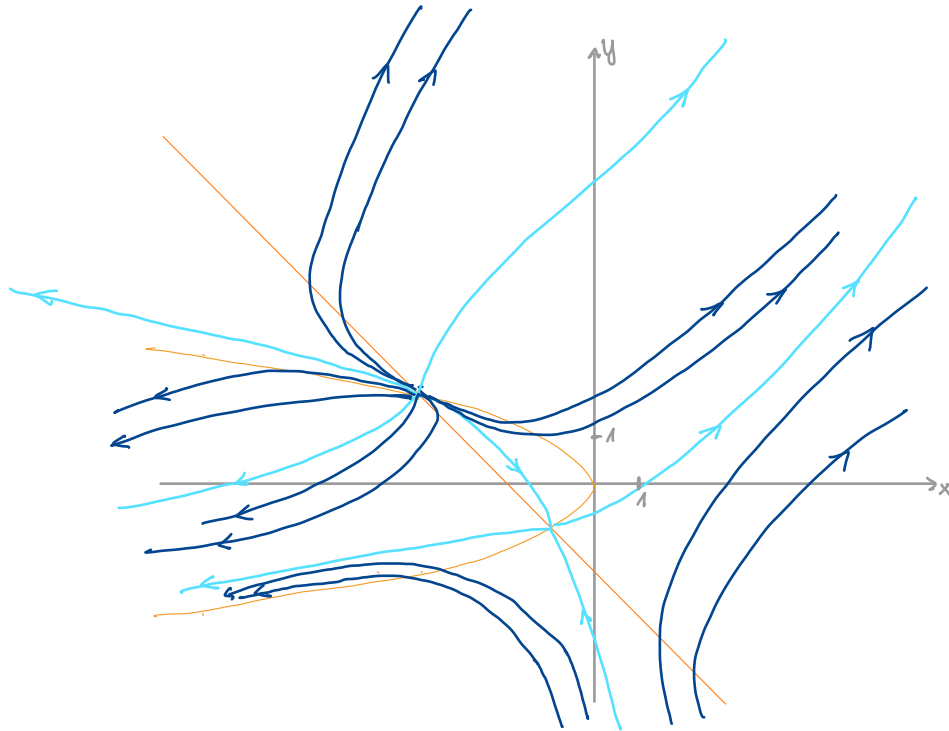
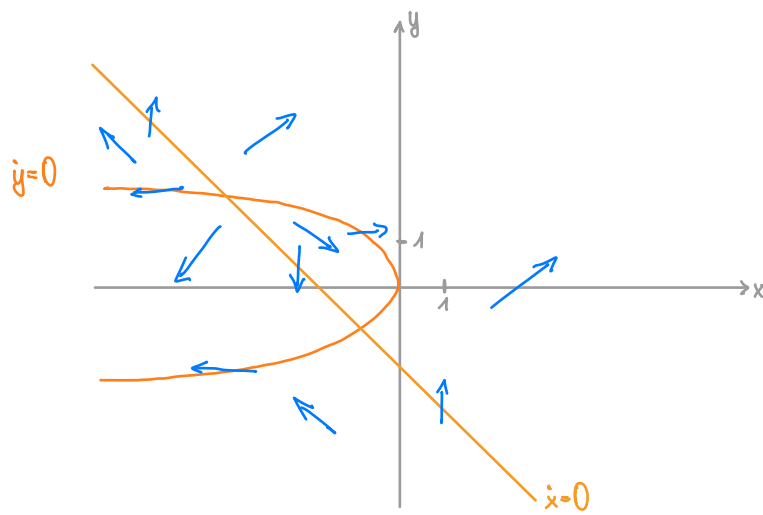
$$\begin{aligned} \rightarrow Jf((-4, 2)) &= \begin{pmatrix} 1 & 1 \\ 1 & 4 \end{pmatrix}: \text{EIGENVALUES: } \det(Jf((-4, 2)) - \lambda I) = 0 \\ &(1-\lambda)(4-\lambda)-1=0 \\ &4-4\lambda-\lambda+\lambda^2-1=0 \\ &\lambda^2-5\lambda+3=0 \\ &\lambda_{1,2} = \frac{5}{2} \pm \sqrt{\frac{25}{4}-\frac{12}{4}} \Rightarrow \lambda_1, \lambda_2 > 0 \end{aligned}$$

$\Rightarrow (-4, 2) \dots$ UNSTABLE NODE

2b) FROM a) EP: $(-1, -1) \dots$ SADDLE
 $(-4, 2) \dots$ UNSTABLE NODE

$$\begin{aligned} \rightarrow \text{ISOCINES: } \dot{x}=0 &\Rightarrow y=-x-2 \\ \dot{y}=0 &\Rightarrow x=-y^2 \end{aligned}$$





3) → LINEARISATION AT (0,0)

$$\dot{\vec{x}} = \begin{pmatrix} 0 & 0 \\ 0 & -4 \end{pmatrix} \vec{x} = A\vec{x} \quad \text{EIGENVALUES OF } A: 0, -4$$

↪ CAN'T USE LINEARISATION

→ LYAPUNOV FCT

LET $V(x,y) = 2x^2 + y^4$... CONTINUOUS, STRICT MIN AT (0,0), $V(0,0) = 0$

$$\begin{aligned} \dot{V}(x,y) &= 4x\dot{x} + 4y^3\dot{y} = 4x(x^3g(x,y) + y^4x) + 4y^3(yg(x,y) - x^2y) \\ &= 4(x^4 + y^4)g(x,y) < 0 \end{aligned}$$

$\forall \vec{x} = (x,y)$ ST $0 < |\vec{x}| \leq 1$

$$[\text{LET } \vec{x} = (x,y) \text{ ST } |\vec{x}| \leq 1 \Rightarrow g(x,y) = x^2 + y^2 - 4 \leq -3 < 0]$$

$$\dot{V}(0,0)=0$$

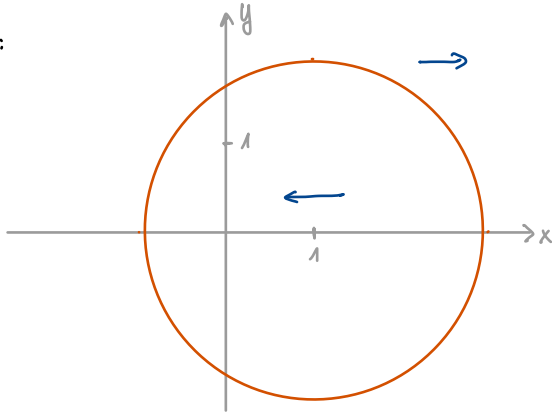
$\Rightarrow (0,0)$ STABLE AND ASYMPTOTICALLY STABLE.

$$4) \text{ EP: } \begin{aligned} \dot{x}=0 &\Rightarrow y^2-4=-(x-1)^2 \\ \dot{y}=0 &\Rightarrow y^2-4=-(x+1)^2 \end{aligned} \Rightarrow \begin{aligned} y^2-4 &= -(x-1)^2 \\ y^2-4 &= -(x+1)^2 \end{aligned} \Rightarrow \begin{aligned} y^2-4 &= -(x-1)^2 \\ y^2-4 &= -1 \end{aligned} \Rightarrow \begin{aligned} y^2-4 &= -(x-1)^2 \\ x=0 \end{aligned} \Rightarrow \begin{aligned} y^2-4 &= -1 \\ x=0 \end{aligned}$$

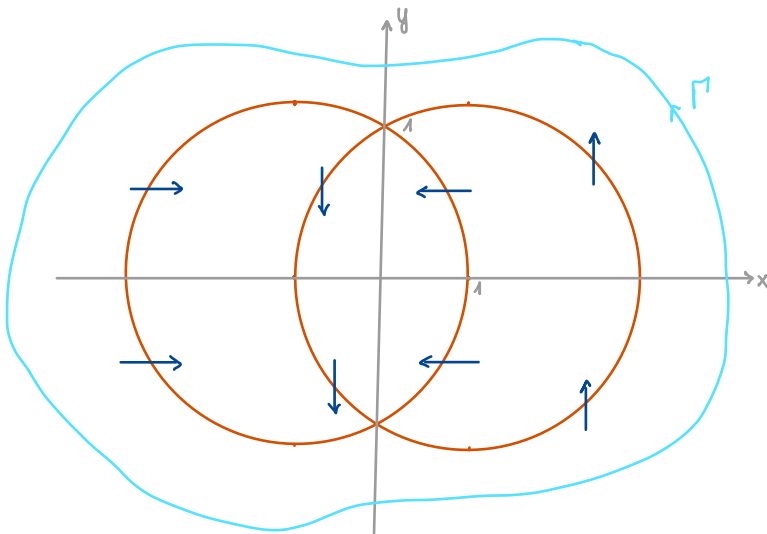
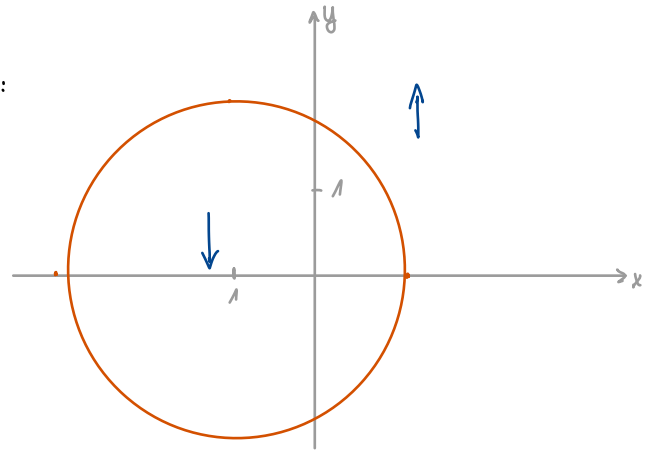
$\Rightarrow$ TWO EPs: $(0, \pm\sqrt{3})$

ISOCINES / NULLCLINES:

$\dot{x}$:



$\dot{y}$:



$$\text{LET } f(\vec{x}) = \begin{pmatrix} (x-1)^2 + y^2 - 4 \\ (x+1)^2 + y^2 - 4 \end{pmatrix}$$

INDEX:

$$I_f(\Gamma) = 0$$

$\Rightarrow$ THE INDEX OF EVERY CURVE SURROUNDING ALL EP EQUALS ZERO.

INDEX OF A PERIODIC ORBIT SURROUNDING ALL EP: 1

$\Rightarrow$ THERE EXISTS NO PERIODIC ORBIT SURROUNDING ALL EPs.

$$5) \dot{x} = ax + \sin(t)$$

$$\text{LET } y(t) = e^{-at} x(t) \Rightarrow \dot{y}(t) = (\dot{x}(t) - ax(t)) e^{-at} = e^{-at} \sin(t)$$

$$\Rightarrow y(t) = y(0) + \int_0^t e^{-as} \sin(s) ds =$$

$$\Rightarrow x(t) = e^{at} y(t) = e^{at} y(0) + \int_0^t e^{a(t-s)} \sin(s) ds = e^{at} x(0) + \int_0^t e^{a(t-s)} \sin(s) ds.$$

$$\cdot) |e^{at} x(0)| \leq |x(0)| \text{ SINCE } a < 0 \text{ \& } t \geq 0$$

$$\cdot) \left| \int_0^t e^{a(t-s)} \sin(s) ds \right| \leq \int_0^t e^{a(t-s)} ds = -\frac{1}{a} e^{a(t-s)} \Big|_0^t = \frac{1}{|a|} (e^{at} - 1)$$

$$\Rightarrow \left| \int_0^t e^{a(t-s)} ds \right| \leq \frac{1}{|a|} (1 - e^{at}) \leq \frac{1}{|a|} \text{ SINCE } a < 0 \text{ \& } t \geq 0$$

$$\Rightarrow |x(t)| \leq |e^{at} x(0)| + \left| \int_0^t e^{a(t-s)} \sin(s) ds \right| \leq |x(0)| + \frac{1}{|a|}$$

$\Rightarrow x(t)$ REMAINS BOUNDED FOR ALL $t \geq 0$.

$$6) \dot{x} = (1+t^2)x^2$$

$$x_0 = 0 \Rightarrow x(t) = 0 \quad \forall t$$

$$x_0 \neq 0: \quad \frac{\dot{x}}{x^2} = 1+t^2 \Rightarrow -\frac{1}{x(t)} + \frac{1}{x(t_0)} = \int_{t_0}^t 1+s^2 ds = t + \frac{t^3}{3} - t_0 - \frac{t_0^3}{3}$$

$$\Rightarrow x(t) - x(t_0) = x(t_0)x(t) \left(t + \frac{t^3}{3} - t_0 - \frac{t_0^3}{3} \right)$$

$$\Rightarrow x(t) = \frac{x(t_0)}{1 - x(t_0) \left(t + \frac{t^3}{3} - t_0 - \frac{t_0^3}{3} \right)} = \frac{x_0}{1 - x_0 \left(t + \frac{t^3}{3} - t_0 - \frac{t_0^3}{3} \right)}$$

$$f(t) = t + \frac{t^3}{3} \Rightarrow f'(t) = 1+t^2 \dots f(t) \text{ STRICTLY INCREASING}$$

$$f(t) \rightarrow \pm \infty \quad (t \rightarrow \pm \infty)$$

$$\Rightarrow \text{IF } x_0 \neq 0, \text{ THEN } \exists t^* \in \mathbb{R} \text{ ST } 1 - x_0 \left(t + \frac{t^3}{3} - t_0 - \frac{t_0^3}{3} \right) = 0$$

$$\Rightarrow |x(t)| \rightarrow \infty \text{ AS } t \rightarrow t^*$$

$\Rightarrow$ NO GLOBAL SOLUTION

$\Rightarrow$ ONLY FOR $(x_0, t_0) = (0, t_0)$ WITH $t_0 \in \mathbb{R}$ THERE EXISTS A GLOBAL SOLUTION.

$$4) \Sigma = \{(0, y) \in \mathbb{R}^2 \mid y > 0\}, \quad \vec{x} \in \Sigma \Rightarrow \vec{x} = (r \cos(\theta), r \sin(\theta)) = (0, r) \text{ WHERE } r = |\vec{x}| \text{ AND } \theta = 2n\pi + \frac{\pi}{2} \quad (n \in \mathbb{Z})$$

$\Rightarrow$ IF $\vec{x}(0) = \vec{x}_0 \in \Sigma$, THEN $\vec{x}(t, \vec{x}_0)$ WILL LEAVE Σ BUT RETURN TO Σ IF θ HAS CHANGED BY 2π , SINCE $\dot{\theta} = 2 > 0$.

$\Rightarrow$ THE TIME $\tau(\vec{x}_0)$ AT WHICH $\vec{x}(t, \vec{x}_0)$ RETURNS TO Σ FOR THE FIRST TIME IS GIVEN BY $\theta(\tau(\vec{x}_0)) - \theta(0) = 2\tau(\vec{x}_0) = 2\pi$

$$\Rightarrow \tau(\vec{x}_0) = \pi$$

$$\Rightarrow \Pi(\vec{x}_0) = \vec{x}(\tau(\vec{x}_0); \vec{x}_0) = \vec{x}(\pi, \vec{x}_0) \dots \text{POINCARÉ MAP}$$

$$\Rightarrow (\vec{x}_0 = (0, r_0)): \Pi((0, r_0)) = \Pi(\vec{x}_0) = \vec{x}(\pi, \vec{x}_0) = (0, r(\pi)) \text{ WHERE } r(t) \text{ IS THE SOL TO (2a)}$$

$$\Rightarrow \Pi((0, r_0)) = (0, r(\pi)) = \left(0, \frac{r_0}{e^{\pi} + r_0(1 - e^{\pi})}\right) = \left(0, \frac{r_0}{r_0 + e^{\pi}(1 - r_0)}\right)$$

$$\text{NOTE } r(\pi) < r_0 \text{ IF } 0 < r_0 < 1 \text{ AND } r(\pi) > r_0 \text{ IF } 1 < r_0 < -\frac{e^{\pi}}{1 - e^{\pi}}$$

$$r_0 + e^{\pi}(1 - r_0) = 0 \Rightarrow r_0(1 - e^{\pi}) + e^{\pi} = 0 \Rightarrow r_0 = -\frac{e^{\pi}}{1 - e^{\pi}}$$

$$\Rightarrow |r(\pi) - 1| > |r_0 - 1| \text{ IF } r_0 \neq 1$$

$$\Rightarrow (0, 1) \notin W(\Gamma_{\vec{x}_0}) \quad \forall \vec{x}_0 \in \Sigma \quad (\Gamma_{\vec{x}_0} \dots \text{ORBIT THROUGH } \vec{x}_0)$$

$$\Rightarrow \Gamma_{(0, 1)} \text{ IS UNSTABLE.}$$