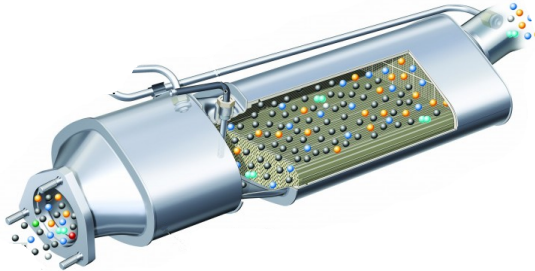


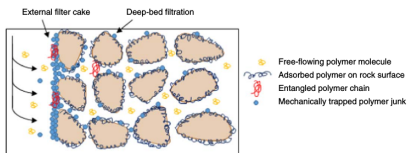
Mathematical Modeling  
Project fall 2016

Diesel Particulate Filter



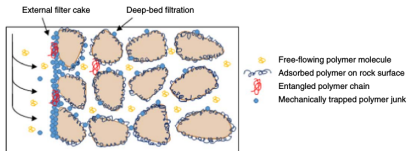
# Background

- ▶ Loss of injectivity in polymer enhanced oil recovery



# Background

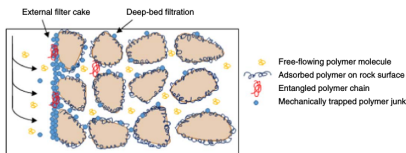
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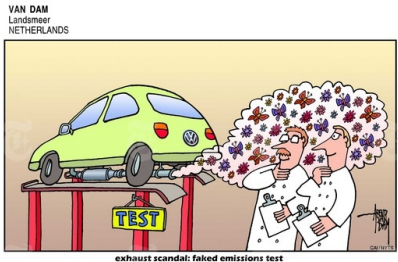
- ▶ [Master projects at SINTEF](#)

# Background

- ▶ Loss of injectivity in polymer enhanced oil recovery



- ▶ [Master projects at SINTEF](#)
- ▶ Volkswagen emissions scandal



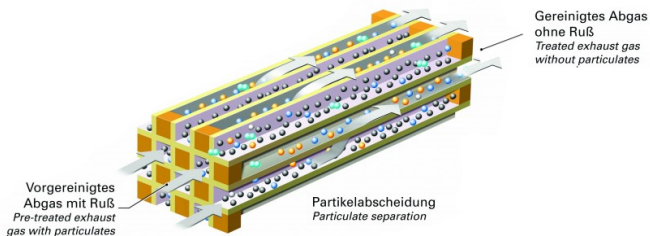
- ▶ Diesel motor emits soot particles

# Filter design

- ▶ Diesel motor emits soot particles
- ▶ Health hazard

# Filter design

- ▶ Diesel motor emits soot particles
- ▶ Health hazard
- ▶ Exhaust gas enters honeycomb structure and it forces to flow through a porous media



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- ▶ Amount of particles that are filtered versus energy that is used to operate the filter.



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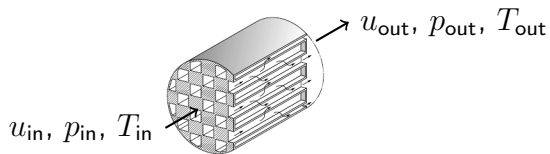
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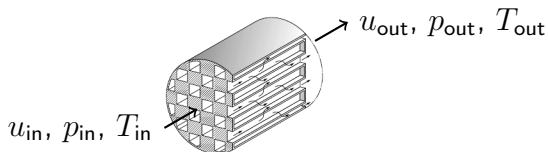
# Filter efficiency (2)

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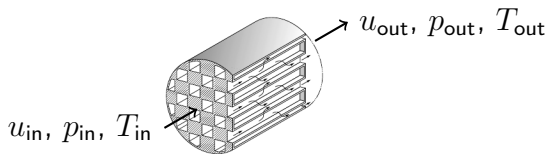
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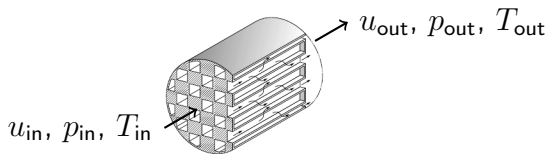
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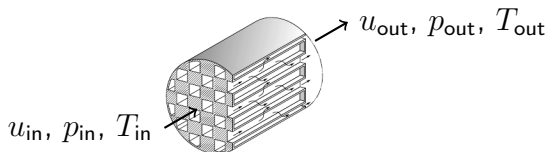


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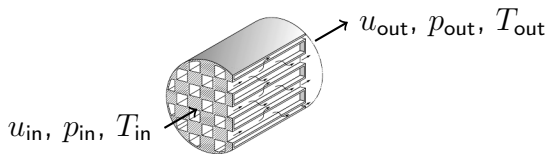
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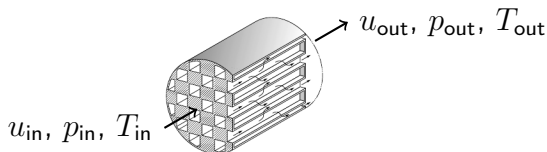
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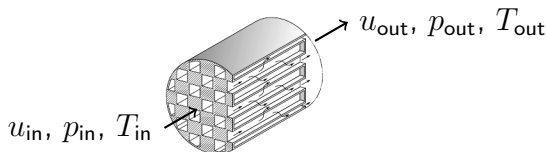
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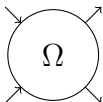
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  - ▶ Conservation of mass
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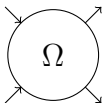


$$\rho_t + \nabla \cdot (\rho u) = 0$$

$$\left\{ \begin{array}{l} \text{rate of} \\ \text{change} \end{array} \right\} = \left\{ \begin{array}{l} \text{what} \\ \text{comes} \\ \text{in} \end{array} \right\} - \left\{ \begin{array}{l} \text{what} \\ \text{comes} \\ \text{out} \end{array} \right\}$$

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- ▶ Hence,

$$\frac{d}{dt} \int_{\Omega} \rho \, dx = - \int_{\partial\Omega} \rho u \cdot \mathbf{n} \, dx$$

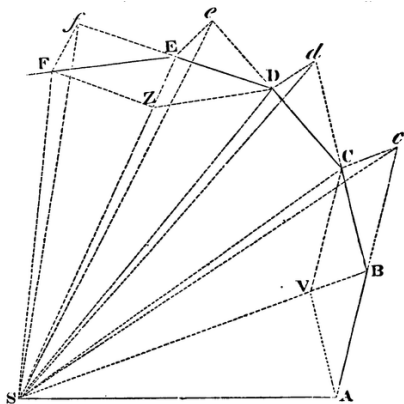
implies

$$\int_{\Omega} \frac{\partial \rho}{\partial t} \, dx = - \int_{\Omega} \nabla \cdot (\rho u) \, dx$$





# Conservation of momentum



$$\text{momentum} = m\mathbf{v}$$

$$\frac{d}{dt}(m\mathbf{v}) = \mathbf{f}$$

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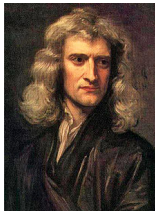
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- ▶ Divergence theorem for matrices

$$\int_{\Omega} \nabla \cdot A(x) dx = \int_{\partial\Omega} A(x) \mathbf{n} dx$$

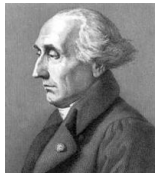
# Newton and Lagrange



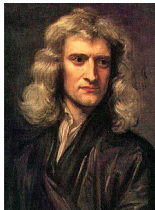
$$m\ddot{x} = f$$

- ▶ Introduce kinetic and potential energy

$$E_{\text{kin}} = \frac{1}{2}m\dot{x}^2 \quad \text{and} \quad E_{\text{pot}}(x)$$



# Newton and Lagrange



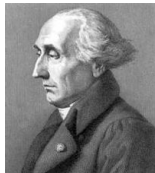
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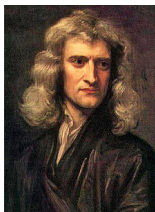
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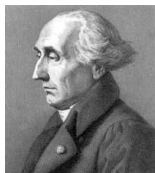
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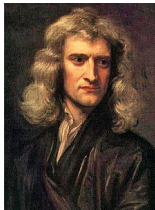
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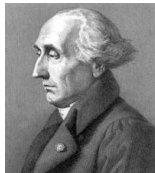
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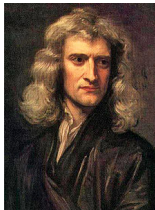
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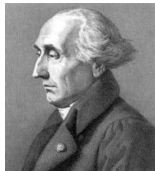
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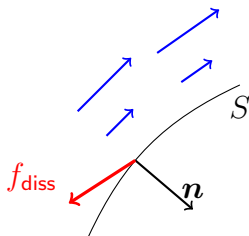
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*Test surface S*

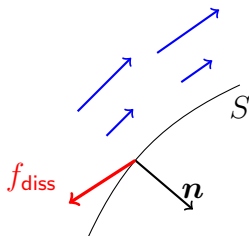


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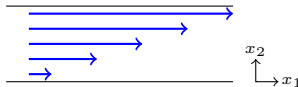
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Moving plates

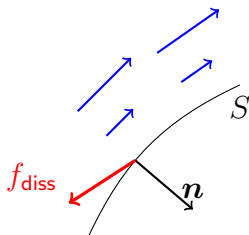


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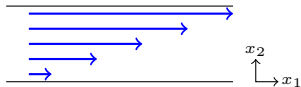
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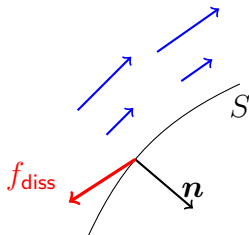
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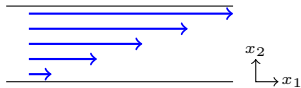
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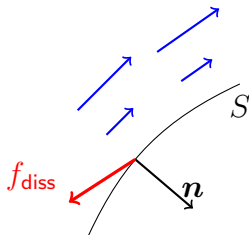
$$\nabla u = \begin{pmatrix} 0 & v \\ 0 & 0 \end{pmatrix}, \quad \nabla \cdot u = \text{tr}(\nabla u), \quad \mathbf{n} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

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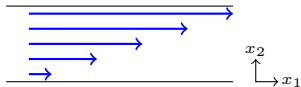
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- ▶ Viscous energy

$$E_{\text{diss}} = \int_{\Omega} \left( \frac{\lambda}{2} \operatorname{tr}(\boldsymbol{\varepsilon})^2 + \mu \|\boldsymbol{\varepsilon}\|^2 \right) dx$$

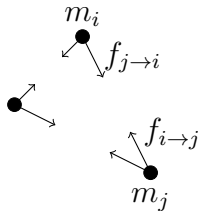
where  $\boldsymbol{\varepsilon}$  is symmetric tensor

$$\boldsymbol{\varepsilon} = \frac{1}{2}(\nabla u + \nabla(u)^T).$$

# Conservation of momentum and angular momentum

## ► Newton's third law

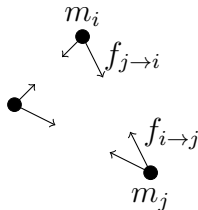
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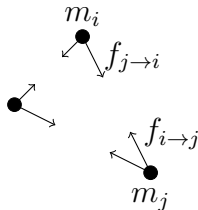
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# Conservation of momentum and angular momentum

- ▶ Newton's third law

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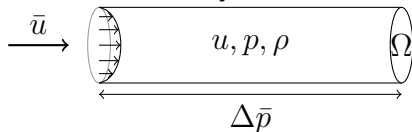
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- ▶ For a closed system, we have the conservation of momentum and of **angular momentum**

$$\frac{d}{dt} \sum_i (m_i v_i) = 0 \quad \text{and} \quad \frac{d}{dt} \sum_i m_i r_i \times v_i = 0$$

# Approximation of the viscous force

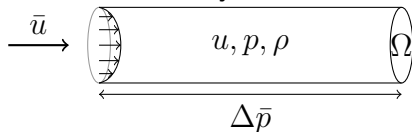
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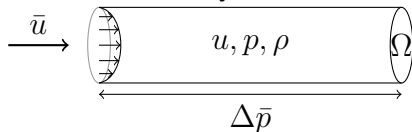
- ▶ Define average values over the cross-section,

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**Q:** Express  $f_{diss}$  as a function of  $\bar{u}$ . Show that  $f_{diss} = -a\bar{u}$ , for a constant  $a$  that depends only on the shape  $\Omega$ . You have to compute the velocity profile.

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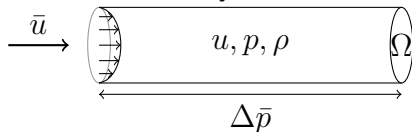
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- ▶ **Q:** Compute the coefficient  $a$  for  $\Omega$  given by a cylinder, a square or an hexagon.

# One dimensional approximation

Instead of considering

$$\begin{aligned}\rho_t + \nabla \cdot (\rho u) &= 0, \\ (\rho u)_t + \nabla \cdot (\rho u \otimes u) &= -\nabla p - au,\end{aligned}$$

we consider the one dimensional approximation

$$\begin{aligned}\rho_t + (\rho u)_x &= 0, \\ (\rho u)_t + (\rho u^2)_x &= -\frac{\partial p}{\partial x} - au.\end{aligned}$$

**Q:** *How are the one-dimensional equations obtained? What are the approximations that we are doing?*

# One dimensional approximation (2)

- ▶ We consider an ideal gas law, with constant temperature. Then  $p$  is proportional to  $\rho$ ,

$$p = b\rho$$

**Q:** *Setup the steady state equations. What are the boundary conditions?*

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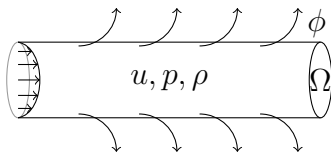
$$p = p_0 + \varepsilon \hat{p} \quad \text{and} \quad u = u_0 + \varepsilon \hat{u}.$$

- ▶ After that, we only consider steady-state.



# mass loss from the walls

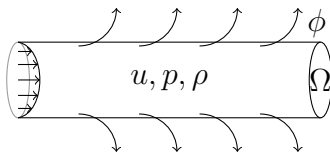
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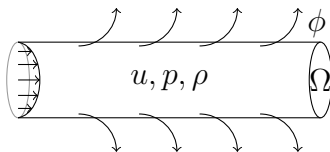


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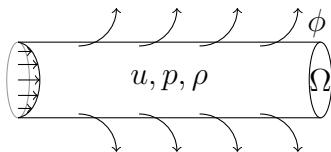


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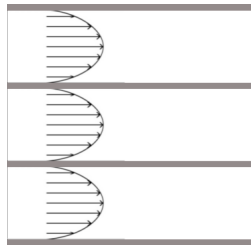
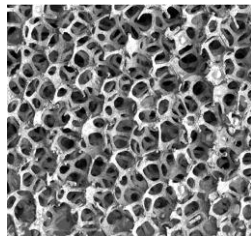
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- ▶ Q: *How are the full 3D equations changed?*
- ▶ Q: *How are the 1D equations changed?*
- ▶ Q: *Solve numerically the 1D equations in the stationary case.*

# Porous media

- ▶ Linear relation between velocity and pressure drop

$$u = -\frac{K}{\mu} \frac{\Delta p}{\Delta x}$$



# Porous media

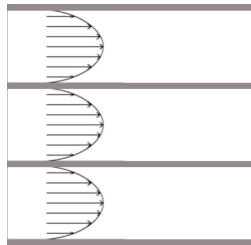
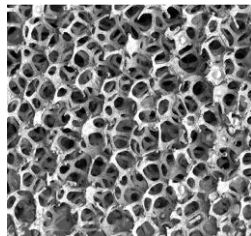
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$$u = -\frac{K}{\mu} \nabla p$$

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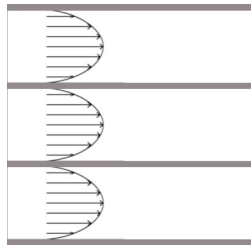
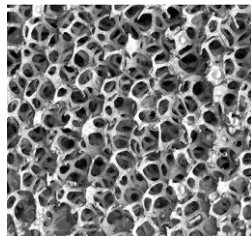
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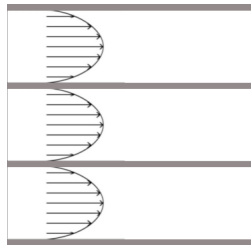
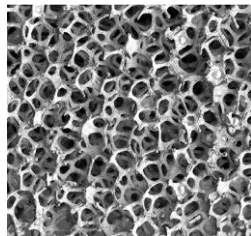
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- ▶ **Q:** *Derive the governing equation for a porous media.*





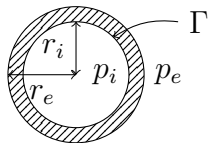
# Upscaling of the porous media layer

- ▶ We want to avoid solving the partial differential equations the porous media layer.

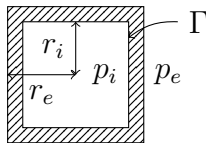
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$$U = \int_{\Gamma} u \cdot \mathbf{n} dx$$



Cylindrical channel

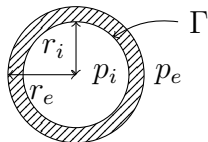


Square channel

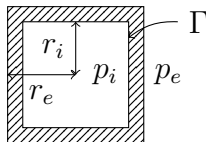
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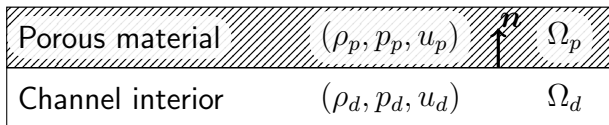
Square channel

- ▶ **Q:** Find the relation between  $U$  and  $p_e - p_i$  for the steady state. Compute  $\kappa$  for a cylinder and a square.

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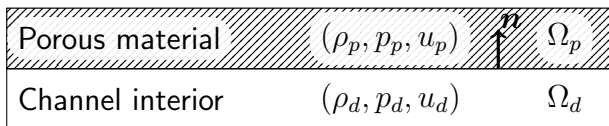
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- ▶ At the interface, we should have conservation of mass and force balance. **Q:** *What are the interface condition?*

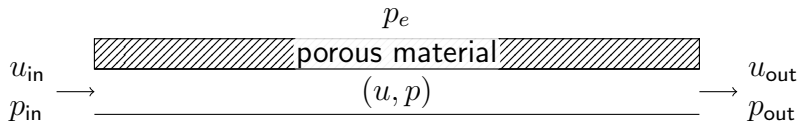


# Coupling of the channel with a porous layer

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- ▶ We consider pressure continuity at the interface (consistent with previous approximation). **Q:** *Set up the one dimensional equations.*



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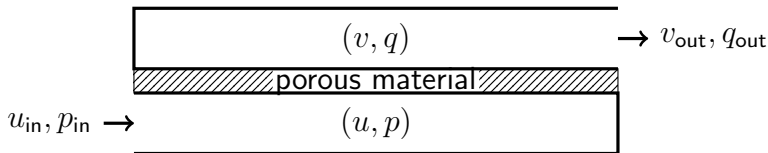
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- ▶ **Q:** *Solve the equations numerically.*

# Coupling the inlet and outlet channel

- ▶ We can now couple inlet and outlet channels

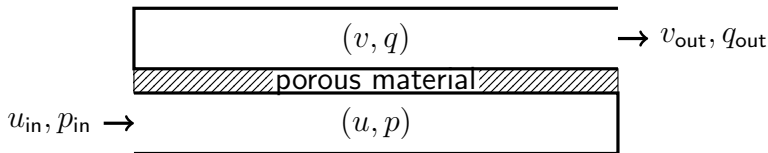
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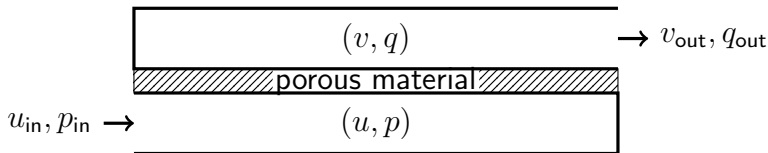


- ▶ **Q:** *Setup the equations for the one dimensional model in the stationary case.*

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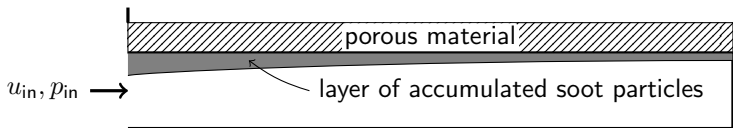
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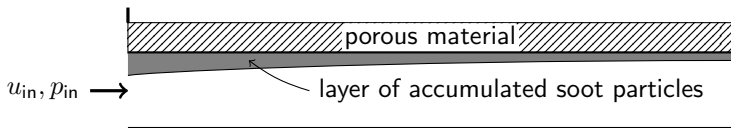
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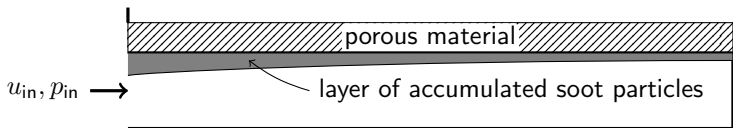
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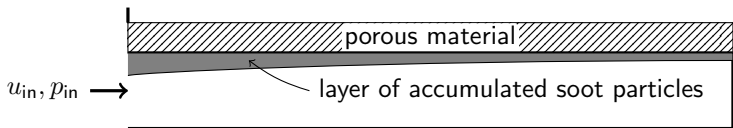


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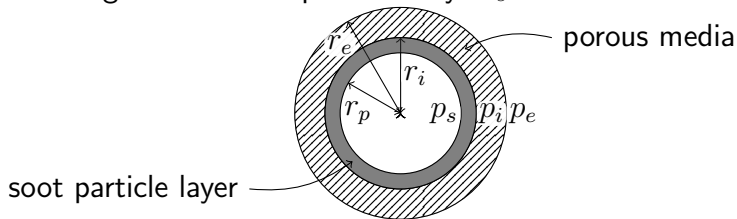
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- ▶ **Q:** *Compute this value numerically (one-dimensional case).*

# Filter clogging

- ▶ The soot accumulates on the porous wall, reducing the efficiency of the filter.

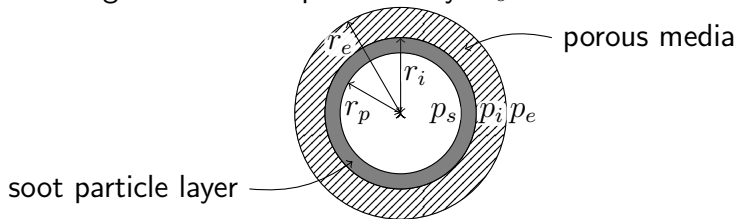
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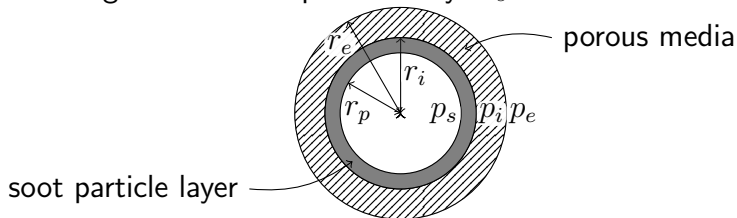


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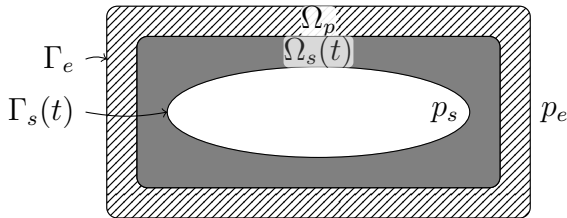
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- ▶ The coefficient  $\kappa$  depends on the amount of accumulated soot and the amount of accumulated soot depends on  $\kappa$ .
- ▶ **Q:** *Set up the coupled equations.*

# Filter clogging - general cross-section

- ▶ For a general geometry of the cross-section, the particles do not accumulate uniformly at the interface

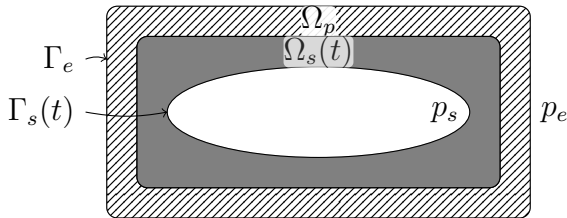


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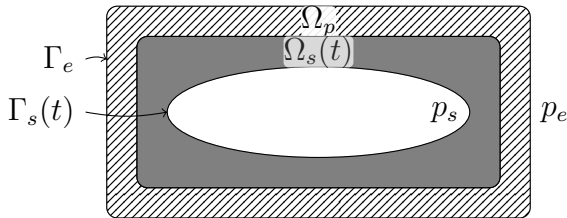
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- ▶ **Q:** *Derive the equation for  $x(\tau, t)$ .* Find an equation that guarantees the conservation of the mass of soot.
- ▶ **Q:** *Design and implement a scheme to solve the governing equations for this problem.*