

TMA4215 Numerical Mathematics — Fall 2016

**PROBLEM SET 9** 

1 A sequence  $\{x^{(k)}\}$  from an iterative method is said to converge to x with rate/order p > 1 in a norm  $\|\cdot\|$  if

$$\frac{\|\boldsymbol{x}^{(k+1)} - \boldsymbol{x}\|}{\|\boldsymbol{x}^{(k)} - \boldsymbol{x}\|^p} \to \mu \ge 0 \quad \text{as} \quad k \to \infty.$$

We write  $x_k$  instead of  $x^{(k)}$  when x is a scalar. Also, when p = 1, we say that  $\{x^{(k)}\}$  converges to x

- ★ linearly if  $\mu \in (0, 1)$ ;
- \* superlinearly, that is, asymptotically faster than linear, if  $\mu = 0$ ;
- \* or sublinearly, that is, asymptotically slower than linear, if  $\mu = 1$  but still  $x^{(k)} \rightarrow x^{1}$ .

Suggestively, convergence is called quadratic when p = 2, cubic when p = 3, and so on. Note, however, that convergence rates can be nonintegral—for example, the classical secant method for root-finding is locally convergent with order equal to the golden ratio.

What is the best (largest) order of convergence for the following sequences?

a) 
$$x_k = 3^{-k}$$
.  
b)  $x_k = (-1)^k (k+1)^{-2}$ .  
c)  $x_k = \pi^{-5^k}$ .

Solution. a) Since

$$\frac{|x_{k+1}|}{|x_k|^p} = 3^{k(p-1)-1} \xrightarrow[k \to \infty]{} \begin{cases} \infty & \text{if } p > 1; \\ \frac{1}{3} & \text{if } p = 1, \end{cases}$$

it follows that  $\{x_k\}$  converges linearly to 0 with  $\mu = 1/3$ .

b) We have  $x_k \rightarrow 0$  and

$$\frac{|x_{k+1}|}{|x_k|^p} = \left(\frac{(k+1)^p}{k+2}\right)^2 \xrightarrow[k \to \infty]{} \begin{cases} \infty & \text{if } p > 1; \\ 1 & \text{if } p = 1, \end{cases}$$

so the rate of convergence is sublinear.

c) This time

$$\frac{|x_{k+1}|}{|x_k|^p} = \pi^{5^k(p-5)}$$

which yields that the order of convergence is quintic, with  $\mu = 1$ .

<sup>&</sup>lt;sup>1</sup>This follows implicitly for all the other cases by the ratio test for sequences.

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Recall that Newton's method

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

applied to a twice continuously differentiable function  $f : \mathbb{R} \to \mathbb{R}$  is locally quadratically convergent provided that the root  $\alpha$  is simple. If, however,  $\alpha$  has multiplicity m > 1, in other words, if

$$f(\alpha) = f'(\alpha) = \dots = f^{(m-1)}(\alpha) = 0$$
 and  $f^{(m)}(\alpha) \neq 0$ 

for a sufficiently smooth  $f \in C^m(\mathbb{R})$ , then the rate of convergence is just linear. In this exercise, you will establish that the modified Newton scheme

$$x_{k+1} = x_k - m \frac{f(x_k)}{f'(x_k)}$$
(\*)

retains the quadratic convergence speed in the presence of a root  $\alpha$  with multiplicity *m*.

a) Show that α is a fixed point of the function φ(x) = x - mf(x)/f'(x). *Hint:* l'Hôpital's rule. *Solution.* By l'Hôpital's rule and the multiplicity of α,

$$\frac{f(\alpha)}{f'(\alpha)} = \frac{f'(\alpha)}{f''(\alpha)} = \dots = \frac{f^{(m-1)}(\alpha)}{f^{(m)}(\alpha)} = 0,$$

because  $f^{(m-1)}(\alpha) = 0$  and  $f^{(m)}(\alpha) \neq 0$ . Thus  $\phi(\alpha) = \alpha$ .

b) Prove that  $\phi'(\alpha) = 0$ . *Hint:* Write *f* as  $f(x) = (x - \alpha)^m h(x)$  for some function *h* satisfying  $h(\alpha) \neq 0$  before you calculate f'(x) and f''(x).

Solution. Routine calculations give

$$\phi'(x) = 1 - m + m \frac{f(x)f''(x)}{f'(x)^2},$$

with

$$f'(x) = (x - \alpha)^{m-1} \left[ mh(x) + (x - \alpha)h'(x) \right]$$

and

$$f''(x) = (x - \alpha)^{m-2} \left[ m(m-1)h(x) + 2m(x - \alpha)h'(x) + (x - \alpha)^2 h''(x) \right].$$

Since  $h(\alpha) \neq 0$ , we find that

$$\frac{f(x)f''(x)}{f'(x)^2} = \frac{h(x)\left[m(m-1)h(x) + 2m(x-\alpha)h'(x) + (x-\alpha)^2h''(x)\right]}{\left[mh(x) + (x-\alpha)h'(x)\right]^2}$$
$$\xrightarrow[x \to \alpha]{} \frac{m(m-1)}{m^2} = 1 - \frac{1}{m},$$

and so  $\phi'(\alpha) = 0$ , as desired.

c) Let  $e_k = x_k - \alpha$  be the error at step *k* and show that

$$e_{k+1} = \frac{1}{2}\phi''(\xi)e_k^2$$

for some  $\xi$  between  $x_k$  and  $\alpha$ . Now deduce that (\*) achieves quadratic convergence speed.

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*Solution.* Notice first that  $e_{k+1} = x_{k+1} - \alpha = \phi(x_k) - \phi(\alpha)$  from (\*), the definition of  $\phi$  and a). Hence, by Taylor expansion and b),

$$e_{k+1} = \phi'(\alpha)(x_k - \alpha) + \frac{1}{2}\phi''(\xi)(x_k - \alpha)^2 = \frac{1}{2}\phi''(\xi)e_k^2$$

for some  $\xi$  between  $x_k$  and  $\alpha$ . Consequently, quadratic convergence rate follows from

$$\lim_{k\to\infty}\frac{e_{k+1}}{e_k^2}=\frac{1}{2}\phi''(\alpha),$$

where we have used that  $\xi \to \alpha$  as  $x_k \to \alpha$  and the continuity of  $\phi''$ .

3 Let  $G: \mathbb{R}^3 \to \mathbb{R}^3$  be given as

$$G(\mathbf{x}) = (g_1(\mathbf{x}), g_2(\mathbf{x}), g_3(\mathbf{x})) = \begin{bmatrix} \frac{1}{6} (1 + 2\cos(x_1 x_2)) \\ \frac{1}{9} \sqrt{x_1^2 + \sin x_3 + 1.06} - 0.1 \\ \frac{1}{20} (1 - e^{-x_1 x_2}) - \frac{\pi}{6} \end{bmatrix},$$

where  $\mathbf{x} = (x_1, x_2, x_3)$ . Show that the fixed-point iteration  $\mathbf{x}^{(k+1)} = \mathbf{G}(\mathbf{x}^{(k)})$  converges towards a unique fixed point for all starting vectors  $\mathbf{x}^{(0)}$  in the closed cube

$$D = \{ \mathbf{x} \in \mathbb{R}^3 : -1 \le x_1, x_2, x_3 \le 1 \}.$$

Also, verify the result numerically.

*Solution.* If we can show that *G* is a contraction—that is, a Lipschitz function with Lipschitz constant less then 1—satisfying  $G(D) \subseteq D$ , then Banach's fixed-point theorem guarantees the existence of a unique fixed point in *D*.

It can be seen that

$$g_1(1,1,x_3) \approx 0.34 < g_1(x_1,x_2,x_3) \le 0.5 = g_1(0,x_2,x_3);$$
  

$$g_2(0,x_2,-1) \approx -0.048 < g_2(x_1,x_2,x_3) < 0.09 \approx g_2(1,x_2,1);$$
  

$$g_3(-1,1,x_3) \approx -0.61 < g_3(x_1,x_2,x_3) < -0.49 \approx g_2(1,1,x_3),$$

so that, indeed,  $G(D) \subseteq D$ . Furthermore, from the mean value theorem we know that contractivity of *G* is assured provided

$$\max_{i=1,2,3} \sum_{j=1}^{3} \left| \frac{\partial g_i}{\partial x_j}(\mathbf{x}) \right| < 1 \quad \text{for all} \quad \mathbf{x} \in D.$$

Some calculations yield that

$$\begin{vmatrix} \frac{\partial g_1}{\partial x_1} \end{vmatrix} < 0.281, \qquad \begin{vmatrix} \frac{\partial g_1}{\partial x_2} \end{vmatrix} < 0.281, \qquad \begin{vmatrix} \frac{\partial g_1}{\partial x_3} \end{vmatrix} = 0, \\ \begin{vmatrix} \frac{\partial g_2}{\partial x_1} \end{vmatrix} < 0.067, \qquad \begin{vmatrix} \frac{\partial g_2}{\partial x_2} \end{vmatrix} = 0, \qquad \begin{vmatrix} \frac{\partial g_2}{\partial x_3} \end{vmatrix} < 0.119, \\ \begin{vmatrix} \frac{\partial g_3}{\partial x_1} \end{vmatrix} < 0.136, \qquad \begin{vmatrix} \frac{\partial g_3}{\partial x_2} \end{vmatrix} < 0.136, \qquad \begin{vmatrix} \frac{\partial g_3}{\partial x_3} \end{vmatrix} = 0,$$

for all  $x \in D$ , which means that

$$\max_{i=1,2,3} \sum_{j=1}^{3} \left| \frac{\partial g_i}{\partial x_j}(\mathbf{x}) \right| < \max\{0.562, 0.186, 0.272\} = 0.562 < 1.$$

Hence, G has a unique fixed point in D.

The fixed point equals  $x = \frac{1}{6}(3, 0, -\pi)$  and the following script in MATLAB demonstrates that the fixed-point iteration converges for any  $x_0 \in D$ .

```
G = @(x) [(1 + 2 * cos(x(1) .* x(2))) / 6; ...
sqrt(x(1).^2 + sin(x(3)) + 1.06) / 9 - .1; ...
(1 - exp(-x(1) .* x(2))) / 20 - (pi / 6)];
fixedpt = [.5; 0; -pi / 6];
% Run fixed-point iteration with random starting points
% and compute maximum absolute error of all tests.
tests = 100;
testpoints = -1 + 2 * rand(3, tests);
for n = 1:tests
for k = 1:13
testpoints(:, n) = G(testpoints(:, n));
end
end
max_abs_error = max(max(abs(testpoints - repmat(fixedpt, 1, tests))))
```

Noticeably, convergence is obtained after just 13 iterations for all the tests.

4 Consider the system of equations

$$x_1^2 + x_2^2 = 1;$$
  
$$x_1^3 - x_2 = 0,$$

which has two solutions—one in the region  $-1 \le x_1, x_2 \le 0$  and the other one in  $0 \le x_1, x_2 \le 1$ . Try a fixed-point scheme based on the formulation

$$x_1 = \sqrt[3]{x_2};$$
  
 $x_2 = \sqrt{1 - x_1^2};$ 

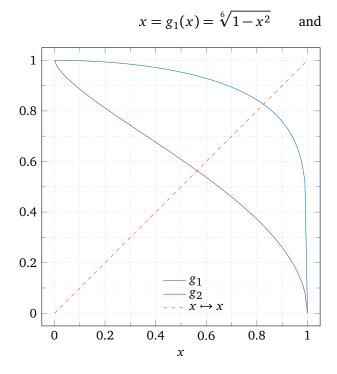
and show—with explanation—that it converges for suitable starting values. How would you select the starting values?

*Hint*: It is simpler to do the analysis if you consider two subsequent iterations as one. That is, consider instead the scheme  $\mathbf{x}^{(k+2)} = G(G(\mathbf{x}^{(k)}))$  with the appropriate G. This decouples the iterations into two scalar cases.

Solution. The fixed-point iteration for two steps is given by

$$x_1^{(k+1)} = \sqrt[3]{x_2^{(k)}}, \qquad x_1^{(k+2)} = \sqrt[6]{1 - (x_1^{(k)})^2},$$
$$x_2^{(k+1)} = \sqrt{1 - (x_1^{(k)})^2}, \qquad x_2^{(k+2)} = \sqrt{1 - (x_2^{(k)})^{2/3}}.$$

Since  $x_1^{(k+2)}$  and  $x_2^{(k+2)}$  only depend on  $x_1^{(k)}$  and  $x_2^{(k)}$ , respectively, the original iteration can be viewed as fixed-point iterations on the two separate scalar equations



**Figure 1:** Graphs of  $g_1$  and  $g_2$  and their fixed-points.

$$x = g_2(x) = \sqrt{1 - x^{2/3}}.$$

We now intend to use Banach's fixed point theorem on the  $g_i$ 's, and for each of these we need to find an interval [a, b] such that  $g_i([a, b]) \subseteq [a, b]$  and  $|g'_i(x)| < 1$  for all  $x \in [a, b]$ .

Practically, we start by locating the fixed points graphically. Figure 1 shows that  $g_1$  has a fixed point near 0.8, and  $g_2$  one near 0.5. Considering  $g_1$  first, we calculate

$$g_1'(x) = -\frac{x}{3(1-x^2)^{5/6}},$$

which implies that  $|g'_1(x)| < 1$  at least when  $0 \le x \le 0.87$ . This interval, however, does not satisfy  $g_1([0, 0.87]) \subseteq [0, 0.87]$ . But since  $g_1$  is monotonically decreasing, some trial and error reveals that

$$g_1([0.76, 0.87]) \subseteq [0.76, 0.87].$$

Similarly, we can show that the two conditions are satisfied for  $g_2$  on the interval [0.22, 0.80].

In conclusion, the system of equations has a unique fixed point in the region

$$D = \left\{ x \in \mathbb{R}^2 : 0.76 \le x_1 \le 0.87, 0.22 \le x_2 \le 0.80 \right\}$$

and the iterations converge for all starting values in *D*.