

TMA4220  
Numerical solution of partial differential equations  
by element methods

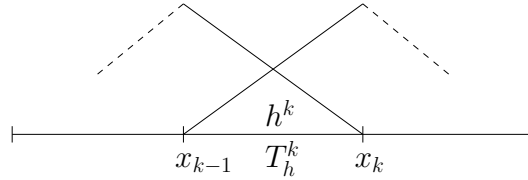
**Suggested solutions to Problem Set 5<sup>1</sup>**

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<sup>1</sup>Made by Einar Rønquist, Department of Mathematical Sciences, NTNU, N-7491 Trondheim, Norway.

## Exercise 5

(April 7 and 9, 2003)



Consider

$$\begin{aligned}
 & \int_{T_h^k} \frac{d\varphi_i}{dx}(x) \frac{d\varphi_j}{dx}(x) dx, \quad \begin{array}{l} i = (k-1) \text{ or } k \\ j = (k-1) \text{ or } k \end{array} \\
 &= \int_{T_h^k} \frac{dH_\alpha(\mathcal{F}_k^{-1}(x))}{dx} \frac{dH_\beta(\mathcal{F}_k^{-1}(x))}{dx} dx \quad \begin{array}{l} \alpha = 1 \text{ or } 2 \\ \beta = 1 \text{ or } 2 \end{array} \\
 &= \int_{\hat{T}} \left( \frac{dH_\alpha(\zeta)}{d\zeta} \cdot \frac{d\zeta}{dx} \right) \left( \frac{dH_\beta(\zeta)}{d\zeta} \cdot \frac{d\zeta}{dx} \right) \cdot \frac{dx}{d\zeta} d\zeta \\
 &= \frac{d\zeta}{dx} \int_{-1}^1 \frac{dH_\alpha(\zeta)}{d\zeta} \cdot \frac{dH_\beta(\zeta)}{d\zeta} d\zeta \\
 &= \frac{2}{h^k} \int_{-1}^1 \frac{dH_\alpha}{d\zeta} \frac{dH_\beta}{d\zeta} d\zeta \quad \begin{array}{l} \alpha = 1 \text{ or } 2 \\ \beta = 1 \text{ or } 2 \end{array}
 \end{aligned}$$

$$\begin{aligned}
 H_1(\zeta) &= \frac{1-\zeta}{2} \Rightarrow \frac{dH_1}{d\zeta} = -\frac{1}{2} \\
 H_2(\zeta) &= \frac{1+\zeta}{2} \Rightarrow \frac{dH_2}{d\zeta} = +\frac{1}{2}
 \end{aligned}$$

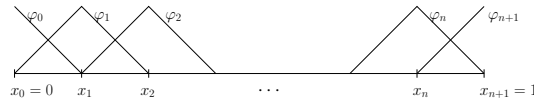
$$\begin{aligned}
 \Rightarrow \left[ \frac{2}{h^k} \int_{-1}^1 \frac{dH_\alpha}{d\zeta} \frac{dH_\beta}{d\zeta} d\zeta \right]_{\alpha, \beta=1}^2 &= \frac{2}{h^k} \begin{bmatrix} \int_{-1}^1 \frac{dH_1}{d\zeta} \frac{dH_1}{d\zeta} d\zeta & \int_{-1}^1 \frac{dH_1}{d\zeta} \frac{dH_2}{d\zeta} d\zeta \\ \int_{-1}^1 \frac{dH_2}{d\zeta} \frac{dH_1}{d\zeta} d\zeta & \int_{-1}^1 \frac{dH_2}{d\zeta} \frac{dH_2}{d\zeta} d\zeta \end{bmatrix} \\
 &= \frac{2}{h^k} \begin{bmatrix} \left(-\frac{1}{2}\right) \cdot \left(-\frac{1}{2}\right) \cdot 2 & \left(-\frac{1}{2}\right) \cdot \left(\frac{1}{2}\right) \cdot 2 \\ \left(\frac{1}{2}\right) \cdot \left(-\frac{1}{2}\right) \cdot 2 & \left(\frac{1}{2}\right) \cdot \left(\frac{1}{2}\right) \cdot 2 \end{bmatrix} \\
 &= \frac{2}{h^k} \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \\
 &= \frac{1}{h^k} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \\
 &\equiv \underline{A}^k
 \end{aligned}$$

## Exercise 6

(April 7 and 9, 2003)

a)

$$\begin{aligned} \underline{\tilde{M}}_h &\in \mathbb{R}^{(n+1) \times (n+1)} \\ (\tilde{M}_h)_{ij} &= \int_0^1 \varphi_i \varphi_j \, dx \quad 0 \leq i, j \leq n+1 \end{aligned}$$



$$\begin{aligned} \tilde{X}_h &= \{v \in H^1(\Omega) \quad , \quad v|_{T_h^k} \in \mathbb{P}_1(T_h^k), k = 1, \dots, K\} \\ &= \text{span}\{\varphi_0, \varphi_1, \varphi_2, \dots, \varphi_n, \varphi_{n+1}\} \end{aligned}$$

$$v(x) = \sum_{i=0}^{n+1} v_i \varphi_i(x) \quad \forall v(x) \in \tilde{X}_h$$

$\uparrow$   
 nodal basis:  $v_i = v(x_i)$

In particular:

$$v(x) = 1 \in \tilde{X}_h \quad \Rightarrow \quad \sum_{i=0}^{n+1} \varphi_i(x) = 1$$

Hence

$$\begin{aligned} \sum_{i=0}^{n+1} \sum_{j=0}^{n+1} \tilde{M}_{h_{ij}} &= \sum_{i=0}^{n+1} \sum_{j=0}^{n+1} \int_0^1 \varphi_i \varphi_j \, dx \\ &= \int_0^1 \left( \sum_{i=0}^{n+1} \varphi_i \right) \left( \sum_{j=0}^{n+1} \varphi_j \right) \, dx \\ &= \int_0^1 1 \cdot 1 \, dx \\ &= \underline{1} \quad \text{Q.E.D.} \end{aligned}$$

b)

$$\begin{aligned}
\int_{T_h^k} \varphi_i \varphi_j \, dx & \quad \begin{array}{l} i = (k-1) \text{ or } k \\ j = (k-1) \text{ or } k \end{array} \\
& = \int_{T_h^k} H_\alpha(\mathcal{F}_k^{-1}(x)) H_\beta(\mathcal{F}_k^{-1}(x)) \, dx & \begin{array}{l} \alpha = 1 \text{ or } 2 \\ \beta = 1 \text{ or } 2 \end{array} \\
& = \int_{\hat{T}} H_\alpha(\zeta) H_\beta(\zeta) \frac{dx}{d\zeta} \, d\zeta \\
& = \frac{h^k}{2} \int_{-1}^1 H_\alpha H_\beta \, d\zeta \\
\underline{M}^k & = \frac{h^k}{2} \begin{bmatrix} \int_{-1}^1 H_1 H_1 \, d\zeta & \int_{-1}^1 H_1 H_2 \, d\zeta \\ \int_{-1}^1 H_2 H_1 \, d\zeta & \int_{-1}^1 H_2 H_2 \, d\zeta \end{bmatrix}
\end{aligned}$$

For example:  $\int_{-1}^1 H_1 H_1 \, d\zeta = \int_{-1}^1 \left(\frac{1-\zeta}{2}\right)^2 \, d\zeta = \frac{1}{4} \int_{-1}^1 (1 - 2\zeta + \zeta^2) \, d\zeta = \frac{2}{3}$

$$\Rightarrow \underline{M}^k = \frac{h^k}{2} \begin{bmatrix} \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} \end{bmatrix}$$

## Exercise 7

(April 7 and 9, 2003)

$$\begin{aligned}
-u_{xx} & = f \text{ in } \Omega = (0, 1) \\
u(0) & = u^D, \quad u_x(1) = 0
\end{aligned}$$

Point of departure:

$$\frac{1}{h} \begin{bmatrix} 1 & -1 & & & & & \\ -1 & 2 & -1 & & & & \\ & -1 & 2 & -1 & & & \\ & & & \ddots & & & \\ & & & & \ddots & & \\ & & & & & -1 & 2 & -1 \\ & & & & & & -1 & 1 \end{bmatrix} \begin{bmatrix} \tilde{u}_{h_0} \\ \tilde{u}_{h_1} \\ \vdots \\ \vdots \\ \tilde{u}_{h_n} \\ \tilde{u}_{h_{n+1}} \end{bmatrix} = \begin{bmatrix} \tilde{F}_{h_0} \\ \tilde{F}_{h_1} \\ \vdots \\ \vdots \\ \tilde{F}_{h_n} \\ \tilde{F}_{h_{n+1}} \end{bmatrix}$$

Weak form: Find  $u_h \in X_h^D$  such that

$$a(u_h, v) = l(v) \quad \forall v \in X_h$$

$X_h$  requires  $v(0) = 0$   
 $X_h^D$  requires  $v(0) = u^D$

$X_h \Rightarrow \varphi_0$  not admissible  $\rightarrow$  remove RO  
 $X_h^D \Rightarrow \tilde{u}_{h_0} = u^D \rightarrow$  move  $-u^D \times \text{CO}$  to the right hands side

Explicit elimination:

$$\frac{1}{h} \begin{bmatrix} 2 & -1 & & & & \\ -1 & 2 & -1 & & & \\ & & \ddots & & & \\ & & & \ddots & & \\ & & & & -1 & 2 & -1 \\ & & & & & -1 & 1 \end{bmatrix} \begin{bmatrix} u_{h_1} \\ \vdots \\ \vdots \\ u_{h_{n+1}} \end{bmatrix} = \begin{bmatrix} \tilde{F}_{h_1} - u^D \times (-\frac{1}{h}) \\ \tilde{F}_{h_2} \\ \vdots \\ \vdots \\ \tilde{F}_{h_{n+1}} \end{bmatrix}$$

Big-Number approach

Place  $\frac{1}{\epsilon} (\epsilon \ll 1)$  on entries  $(\tilde{A}_h)_{00}$

Place  $(\frac{1}{\epsilon}) \cdot u^D$  on entry  $\tilde{F}_{h_0}$ .