

TMA4220
Numerical solution of partial differential equations
by element methods

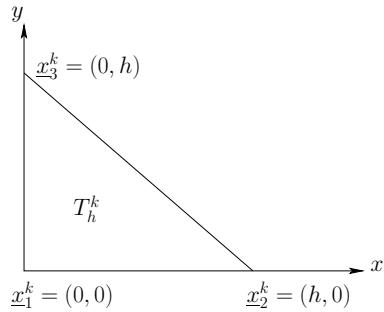
Suggested solutions to Problem Set 6¹

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Exercise 1

(January 5, 2004)

a)



$$\begin{aligned}
 H_1^k &= 1 - x/h - y/h \\
 H_2^k &= x/h \\
 H_3^k &= y/h \\
 H_\alpha^k &= c_\alpha + c_{x_\alpha} \cdot x + c_{y_\alpha} \cdot y, \quad \alpha = 1, 2, 3
 \end{aligned}$$

$$H_1^k = 1 - \frac{x}{h} - \frac{y}{h} \Rightarrow c_1 = \frac{1}{h}, \quad c_{x_1} = -\frac{1}{h}, \quad c_{y_1} = -\frac{1}{h}$$

$$H_2^k = \frac{x}{h} \Rightarrow c_2 = 0, \quad c_{x_2} = \frac{1}{h}, \quad c_{y_2} = 0$$

$$H_3^k = \frac{y}{h} \Rightarrow c_3 = 0, \quad c_{x_3} = 0, \quad c_{y_3} = \frac{1}{h}$$

$$\begin{aligned}
 A_{\alpha\beta}^k &= \int_{T_h^k} \left(\frac{\partial H_\alpha^k}{\partial x} \frac{\partial H_\beta^k}{\partial x} + \frac{\partial H_\alpha^k}{\partial y} \frac{\partial H_\beta^k}{\partial y} \right) dA \\
 &= \text{Area}^k (c_{x_\alpha} c_{x_\beta} + c_{y_\alpha} c_{y_\beta}) \quad 1 \leq \alpha, \beta \leq 3
 \end{aligned}$$

$$A_{11}^k = \frac{h^2}{2} \cdot ((-1) \cdot (-1) + (-1) \cdot (-1)) \frac{1}{h^2} = \frac{1}{2} \cdot 2$$

$$A_{12}^k = \frac{h^2}{2} \cdot ((-1) \cdot 1 + (-1) \cdot 0) \frac{1}{h^2} = \frac{1}{2} \cdot (-1)$$

$$A_{13}^k = \frac{h^2}{2} \cdot ((-1) \cdot 0 + (-1) \cdot 1) \frac{1}{h^2} = \frac{1}{2} \cdot (-1)$$

$$A_{21}^k = \frac{h^2}{2} \cdot (1 \cdot (-1) + 0 \cdot (-1)) \frac{1}{h^2} = \frac{1}{2} \cdot (-1)$$

$$A_{22}^k = \frac{h^2}{2} \cdot (1 \cdot 1 + 0 \cdot 0) \frac{1}{h^2} = \frac{1}{2} \cdot (1)$$

$$A_{23}^k = \frac{h^2}{2} \cdot (1 \cdot 0 + 0 \cdot 1) \frac{1}{h^2} = \frac{1}{2} \cdot (0)$$

$$A_{31}^k = \frac{h^2}{2} \cdot (0 \cdot (-1) + 1 \cdot (-1)) \frac{1}{h^2} = \frac{1}{2} \cdot (-1)$$

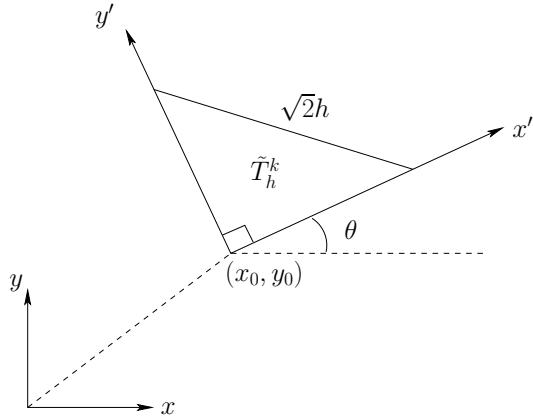
$$A_{32}^k = \frac{h^2}{2} \cdot (0 \cdot 1 + 1 \cdot 0) \frac{1}{h^2} = \frac{1}{2} \cdot (0)$$

$$A_{33}^k = \frac{h^2}{2} \cdot (0 \cdot 0 + 1 \cdot 1) \frac{1}{h^2} = \frac{1}{2} \cdot (1)$$

As expected $A_{\alpha\beta}^k = A_{\beta\alpha}^k$ (symmetry).

$$\underline{A}^k = \frac{1}{2} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$$

b)



Consider a right-triangular element with hypotenuse $\sqrt{2}h$ at any position and any orientation.

First, notice that

$$\underline{A}_{\alpha\beta}^k = \int_{T_h^k} \nabla H_\alpha^k \cdot \nabla H_\beta^k dA$$

The integrand $(\nabla H_\alpha^k \cdot \nabla H_\beta^k)$ represents a dot product. We know that this is a geometric invariant in the sense that the dot product is unaffected by the choice of Cartesian coordinate system. Hence, we can introduce another Cartesian coordinate system (x', y') which represents a translation and a rotation compared to (x, y) .

In the (x', y') coordinate system, the local basis functions read:

$$\begin{aligned} H_1^k &= 1 - \frac{x'}{h} - \frac{y'}{h} \\ H_2^k &= \frac{x'}{h} \\ H_3^k &= \frac{y'}{h} \end{aligned}$$

and

$$\underline{A}^k = \frac{1}{2} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \quad \text{as in a)}$$

c)

$$\begin{aligned} M_{\alpha\beta}^k &= \int_{T_h^k} \varphi_i|_{T_h^k} \varphi_j|_{T_h^k} dA && \text{for some } i, j. \\ &= \int_{T_h^k} H_\alpha^k \cdot H_\beta^k dA, && 1 \leq \alpha, \beta \leq 3 \end{aligned}$$

Consider the element depicted in a).

$$\begin{aligned} H_1^k &= 1 - \frac{x}{h} - \frac{y}{h} \\ H_2^k &= \frac{x}{h} \\ H_3^k &= \frac{y}{h} \end{aligned}$$

$$\begin{aligned} M_{11}^k &= \int_{T_h^k} \left(1 - \frac{x}{h} - \frac{y}{h}\right)^2 dA = h^2 \int_{\xi=0}^1 \int_{\eta=0}^{1-\xi} (1 - \xi - \eta)^2 d\eta d\xi \\ &= h^2 \int_{\xi=0}^1 \left[-\frac{1}{3}(1 - \xi - \eta)^3\right]_0^{1-\xi} d\xi \\ &= h^2 \int_{\xi=0}^1 \left[-\frac{1}{3}(1 - \xi - (1 - \xi))^3 + \frac{1}{3}(1 - \xi)^3\right] d\xi \\ &= h^2 \int_{\xi=0}^1 \frac{1}{3}(1 - \xi)^3 d\xi = h^2 \frac{1}{3} \left[-\frac{1}{4}(1 - \xi)^4\right]_0^1 \\ &= h^2 \cdot \frac{1}{3} \cdot \frac{1}{4} \\ &= \underline{\frac{1}{12}h^2} \end{aligned}$$

$$\begin{aligned} M_{12}^k &= \int_{T_h^k} \left(1 - \frac{x}{h} - \frac{y}{h}\right) \frac{x}{h} dA = h^2 \int_{\xi=0}^1 \int_{\eta=0}^{1-\xi} (1 - \xi - \eta)\xi d\eta d\xi \\ &= h^2 \int_{\xi=0}^1 \xi \left[-\frac{1}{2}(1 - \xi - \eta)^2\right]_0^{1-\xi} d\xi \\ &= h^2 \int_{\xi=0}^1 \xi \frac{1}{2}(1 - \xi)^2 d\xi = \frac{h^2}{2} \int_0^1 (\xi - 2\xi^2 + \xi^3) d\xi \\ &= \frac{h^2}{2} \left[\frac{1}{2}\xi^2 - \frac{2}{3}\xi^3 + \frac{1}{4}\xi^4\right]_0^1 = \frac{h^2}{2} \left(\frac{1}{2} - \frac{2}{3} + \frac{1}{4}\right) = \frac{h^2}{2} \cdot \frac{1}{12} \\ &= \underline{\frac{h^2}{24}} \end{aligned}$$

$$\begin{aligned}
M_{13}^k &= \int_{T_h^k} \left(1 - \frac{x}{h} - \frac{y}{h}\right) \frac{y}{h} dx dy = h^2 \int_{\xi=0}^1 \int_{\eta=0}^{1-\xi} (1 - \xi - \eta) \eta d\eta d\xi \\
&= h^2 \int_{\xi=0}^1 \left[\frac{1}{2}(1 - \xi) \eta^2 - \frac{1}{3} \eta^3 \right]_0^{1-\xi} d\xi \\
&= h^2 \int_{\xi=0}^1 \left(\frac{1}{2}(1 - \xi)^3 - \frac{1}{3}(1 - \xi)^3 \right) d\xi = h^2 \int_0^1 \frac{1}{6}(1 - \xi)^3 d\xi \\
&= \frac{h^2}{6} \left[-\frac{1}{4}(1 - \xi)^4 \right]_0^1 = \frac{h^2}{6} \cdot \frac{1}{4} \\
&= \underline{\frac{h^2}{24}}
\end{aligned}$$

$$\begin{aligned}
M_{22} &= \int_{T_h^k} \left(\frac{x}{h}\right)^2 dx dy = h^2 \int_{\xi=0}^1 \int_{\eta=0}^{1-\xi} \xi^2 d\eta d\xi \\
&= h^2 \int_0^1 \xi^2 (1 - \xi) d\xi = h^2 \left[\frac{1}{3} \xi^3 - \frac{1}{4} \xi^4 \right]_0^1 \\
&= \underline{\frac{h^2}{12}}
\end{aligned}$$

$$\begin{aligned}
M_{23}^k &= \int_{T_h^k} \left(\frac{x}{h}\right) \left(\frac{y}{h}\right) dx dy = h^2 \int_{\xi=0}^1 \int_{\eta=0}^{1-\xi} \xi \cdot \eta d\eta d\xi \\
&= h^2 \int_{\xi=0}^1 \xi \left[\frac{1}{2} \eta^2 \right]_0^{1-\xi} d\xi = h^2 \int_0^1 \xi \frac{1}{2} (1 - \xi)^2 d\xi \\
&= \frac{h^2}{2} \int_0^1 (\xi - 2\xi^2 + \xi^3) d\xi = \frac{h^2}{2} \left[\frac{1}{2} \xi^2 - \frac{2}{3} \xi^3 + \frac{1}{4} \xi^4 \right]_0^1 \\
&= \underline{\frac{h^2}{24}}
\end{aligned}$$

$$M_{33}^k = \underline{\frac{h^2}{12}}$$

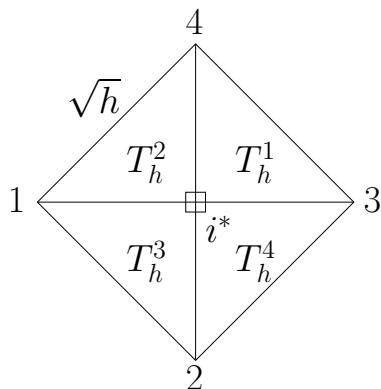
$$\underline{M^k} = \frac{h^2}{24} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \quad (\text{Invariant with respect to translation and rotation.})$$

Check:

$$\begin{aligned}\underline{1}^T \underline{M}^k \underline{1} &= \sum_{\alpha} \sum_{\beta} M_{\alpha\beta}^k \\ &= \frac{h^2}{2} \\ &= \underline{\text{Area}}^k\end{aligned}$$

Exercise 2

(January 5, 2004)



- T_h^1 : global nodes $(i^*, 3, 4)$
- T_h^2 : global nodes $(i^*, 4, 1)$
- T_h^3 : global nodes $(i^*, 1, 2)$
- T_h^4 : global nodes $(i^*, 2, 3)$

Initial row i^* in \tilde{A}_h :

Column:	1	2	3	4	i^*
row i^* →	0	0	0	0	0

Row i^* after assembling contributions from T_h^1 :

row i^* →			$-\frac{1}{2}$	$-\frac{1}{2}$	1
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Row i^* after assembling contributions from T_h^2 :

row i^* →	$-\frac{1}{2}$		$-\frac{1}{2}$	-1	2
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Row i^* after assembling contributions from T_h^3 :

row i^* →	-1	$-\frac{1}{2}$	$-\frac{1}{2}$	-1	3
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Row i^* after assembling contributions from T_h^4 (final result):

row i^* →	-1	-1	-1	-1	4
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