

TMA4220  
Numerical solution of partial differential equations  
by element methods

**Suggested solutions to Problem Set 8<sup>1</sup>**

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## Exercise 1

We first express the element matrix associated with element  $T_h^k$  as a sum of two contributions: one from the diffusion term and one from the convection term,

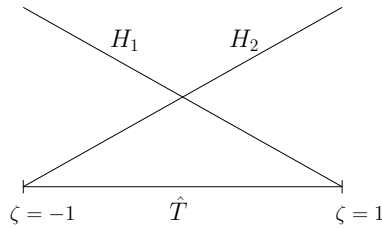
$$\underline{A}_h^k = \underbrace{A_{\text{Laplace}}^k}_{\text{diffusion}} + \underbrace{C^k}_{\text{convection}}$$

We have already seen how to derive

$$A_{\text{Laplace}}^k = \frac{\kappa}{h^k} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

On page 5 in the notes dated March 9, 2004, we derived the result

$$C_{\alpha\beta}^k = \int_{\hat{T}} U \frac{dH_\beta}{d\zeta} H_\alpha d\zeta \quad \begin{array}{l} \alpha = 1, 2 \\ \beta = 1, 2 \end{array}$$



$$\begin{aligned} H_1(\zeta) &= \frac{1-\zeta}{2}, & \frac{dH_1}{d\zeta} &= -\frac{1}{2} \\ H_2(\zeta) &= \frac{1+\zeta}{2}, & \frac{dH_2}{d\zeta} &= +\frac{1}{2} \end{aligned}$$

Explicit computation of  $C_{\alpha\beta}^k$ ,  $\alpha, \beta = 1, 2$  then gives:

$$C_{11}^k = \int_{-1}^1 U \frac{dH_1}{d\zeta} H_1 d\zeta \quad (U = \text{constant in } \mathbb{R}^1; \text{ a given incompressible velocity field )}$$

$$= U \int_{-1}^1 \left(-\frac{1}{2}\right) \left(\frac{1-\zeta}{2}\right) d\zeta = \frac{U}{4} \int_{-1}^1 (\zeta - 1) d\zeta = \frac{U}{4} \cdot (-2)$$

$$\underline{C_{11}^k} = -\frac{U}{2}$$

$$C_{12}^k = U \int_{-1}^1 \frac{dH_2}{d\zeta} H_1 d\zeta = U \int_{-1}^1 \left(\frac{1}{2}\right) \left(\frac{1-\zeta}{2}\right) d\zeta = \frac{U}{4} \cdot (+2)$$

$$\underline{C_{12}^k} = +\frac{U}{2}$$

$$\underline{C_{21}^k} = U \int_{-1}^1 \frac{dH_1}{d\zeta} H_2 d\zeta = U \int_{-1}^1 \left(-\frac{1}{2}\right) \left(\frac{1+\zeta}{2}\right) d\zeta = -\frac{U}{2}$$

$$\underline{C_{22}^k} = U \int_{-1}^1 \frac{dH_2}{d\zeta} H_2 d\zeta = U \int_{-1}^1 \left(+\frac{1}{2}\right) \left(\frac{1+\zeta}{2}\right) d\zeta = +\frac{U}{2}$$

Hence,

$$\underline{C}^k = \frac{U}{2} \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix}$$

and

$$\underline{A}_h^k = \frac{\kappa}{h^k} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{U}{2} \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix}$$

## Exercise 2

$$\begin{aligned} -\kappa u_{xx} - U u_x &= 0 & \text{in } \Omega = (0, \infty) \\ u(0) &= 0 \\ u(\infty) &= 0 \end{aligned}$$

Second-order central differences gives (see the notes dated March 9, 2004):

$$-\varepsilon \frac{(\hat{u}_{j+1} - 2\hat{u}_j + \hat{u}_{j-1}))}{\Delta x^2} - \frac{(\hat{u}_{j+1} - \hat{u}_{j-1}))}{2\Delta x} = 0 .$$

As derived in class, the exact difference solution can be expressed as:

$$\hat{u}_j = \left( \frac{1 - P_g/2}{1 + P_g/2} \right)^j, \quad j = 0, 1, \dots$$

Here, the grid Peclet number  $P_g = \frac{\Delta x}{\varepsilon} = \frac{U\Delta x}{\kappa} > 0$ .

Oscillations (defined as  $\hat{u}_j$  being both negative and positive) will occur when

$$1 - P_g/2 < 0 \Rightarrow \underline{P_g > 2}$$

This corresponds to  $\underline{\Delta x > 2\varepsilon}$ , i.e., we do not resolve the true boundary layer of thickness  $\varepsilon$ .

## Exercise 3

Modified problem:

$$-(\varepsilon + \frac{\Delta x}{2})u_{xx} - u_x = 0$$

Second-order finite differences applied to the modified problem gives:

$$\begin{aligned} -(\varepsilon + \frac{\Delta x}{2}) \frac{(\hat{u}_{j+1} - 2\hat{u}_j + \hat{u}_{j-1}))}{\Delta x^2} - \frac{(\hat{u}_{j+1} - \hat{u}_{j-1}))}{2\Delta x} &= 0 \\ -\varepsilon \frac{(\hat{u}_{j+1} - 2\hat{u}_j + \hat{u}_{j-1}))}{\Delta x^2} - \underbrace{\frac{(\hat{u}_{j+1} - 2\hat{u}_j + \hat{u}_{j-1}))}{2\Delta x} - \frac{(\hat{u}_{j+1} - \hat{u}_{j-1}))}{2\Delta x}}_{= \frac{\hat{u}_{j+1} - \hat{u}_j}{\Delta x}} &= 0 \end{aligned}$$

i.e., first order upwinding applied to the original problem.

The grid Peclet number for the modified problem ( $\Leftrightarrow$  first order upwinding) is:

$$\tilde{P}_g = \frac{\Delta x}{\tilde{\varepsilon}} = \frac{\Delta x}{\varepsilon + \frac{\Delta x}{2}}$$

$\max_{\varepsilon} \tilde{P}_g = 2 \Rightarrow$  first order upwinding is always stable (no oscillations), but we will experience a loss of accuracy. As  $\varepsilon$  goes to zero ( $\varepsilon \ll \Delta x$ ), the numerical solution will have a boundary layer of thickness approximately equal to  $\Delta x/2$ , i.e., the error in the boundary layer region will be  $\mathcal{O}(1)$ . However, the outer solution will be good.