

TMA4250 KOMLIG STATISTIKK

LØSNINGSFORSLAG

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PROBLEM 1 CONTINUOUS RANDOM FIELD

GRF $\{R(x); x \in \mathbb{R}^1\}$

where

$$E\{R(x)\} = \begin{cases} a & \text{for } x \leq 0 \\ b & \text{for } x \geq 0 \end{cases}$$

$$\text{COV}\{R(x'), R(x'')\} = c(\Delta x) = \exp\{-\Delta x\}$$

with

a, b unknown const

$$\Delta x = |x' - x''|$$

a) Requirements for pos. def. function $c(\Delta x)$:

$$\sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j c(|x_i - x_j|) \geq 0$$

all configurations $x = (x_1, \dots, x_n)$

all $\alpha = (\alpha_1, \dots, \alpha_n)$

all $n \geq 0$

Observe $R^0 = (R(x_1), R(x_2), R(x_3), R(x_4))$

with $X^0 = (x_1, x_2, x_3, x_4) = (-2, -1, 2, 4)$

b) BLUE for a and b

For a :

Consider linear estimator for a :

$$\hat{a} = \sum_{i=1}^4 \alpha_i R(x_i) \quad \text{with } \alpha = (\alpha_1, \dots, \alpha_4)$$

Unbiasedness:

$$E\{a - \hat{a}\} = 0$$

$$\Downarrow$$
$$\sum_{i=1}^4 \alpha_i E\{R(x_i)\} = a$$

$$\Downarrow$$
$$(\alpha_1 + \alpha_2)a + (\alpha_3 + \alpha_4)b = a$$

$$\Downarrow$$
$$(\alpha_1 + \alpha_2) = 1 \quad (\alpha_3 + \alpha_4) = 0$$

Variance:

$$\text{Var}\{a - \hat{a}\} = \text{Var}\{\hat{a}\} = \sum_{i=1}^4 \sum_{j=1}^4 \alpha_i \alpha_j \text{Cov}\{R(x_i), R(x_j)\}$$
$$= \sum_i \sum_j \alpha_i \alpha_j c(\Delta x_{ij})$$

with $\Delta x_{ij} = |x_i - x_j|$

BLUE-weights under quadratic loss are:

$$\alpha^* = \underset{\alpha}{\text{argmin}} \{ \text{Var}\{a - \hat{a}\} \} = \underset{\alpha}{\text{argmin}} \left\{ \sum_i \sum_j \alpha_i \alpha_j c(\Delta x_{ij}) \right\}$$

$$\alpha_1 + \alpha_2 = 1$$

$$\alpha_3 + \alpha_4 = 0$$

Can be solved by Lagrange minimization

BLUE for a with associated estimation variance:

$$\hat{a} = \sum_{i=1}^4 \alpha_i^* R(x_i)$$

$$\text{Var}\{\hat{a}\} = \sum_i \sum_j \alpha_i^* \alpha_j^* c(\Delta x_{ij})$$

For b :

Consider linear estimator for b :

$$\hat{b} = \sum_{i=1}^4 \beta_i R(x_i) \quad \text{with } \beta = (\beta_1, \beta_2, \beta_3, \beta_4)$$

BLUE-weights under quadratic loss are:

$$\beta^* = \underset{\beta}{\operatorname{argmin}} \{ \operatorname{Var} \{ \beta - \hat{\beta} \} \} = \underset{\beta}{\operatorname{argmin}} \left\{ \sum_i \sum_j \beta_i \beta_j C(\Delta x_{ij}) \right\}$$

$$\beta_1 + \beta_2 = 0$$

$$\beta_3 + \beta_4 = 1$$

Can be solved by Lagrange minimization.

BLUE for b with associated estimation variance:

$$\hat{b} = \sum_{i=1}^4 \beta_i^* R(x_i)$$

$$\operatorname{Var} \{ \hat{b} \} = \sum_i \sum_j \beta_i^* \beta_j^* C(\Delta x_{ij})$$

Stepheight at $x=0^-$ is $\Delta = a - b$.

c) Possible estimator $\hat{\Delta} = \hat{a} - \hat{b} = \sum_i \alpha_i^* R(x_i) - \sum_i \beta_i^* R(x_i)$

$$= \sum_i (\alpha_i^* - \beta_i^*) R(x_i)$$

$\hat{\Delta} \sim N(a-b, \sigma_{\hat{\Delta}}^2)$

$$\operatorname{E}\{\hat{\Delta}\} = \hat{a} - \hat{b} \quad \operatorname{Var}\{\hat{\Delta}\} = \sum_i \sum_j (\alpha_i^* - \beta_i^*) (\alpha_j^* - \beta_j^*) C(\Delta x_{ij})$$

0.9 confidence interval:

$$\left[(\hat{a} - \hat{b}) - \sigma_{\hat{\Delta}} Z_{0.05}, (\hat{a} - \hat{b}) + \sigma_{\hat{\Delta}} Z_{0.05} \right]$$

\swarrow 0.05 quantile stand. Gauss

Characteristics of α^* :

$$L_\alpha = \sum_i \sum_j \alpha_i \alpha_j c_{ij} + \lambda_1^\alpha (\alpha_1 + \alpha_2 - 1) + \lambda_2^\alpha (\alpha_3 + \alpha_4)$$

$$\frac{dL_\alpha}{d\alpha} = 0 \Rightarrow \left. \begin{array}{l} \sum_j \alpha_j c_{1j} + \lambda_1^\alpha = 0 \\ \sum_j \alpha_j c_{2j} + \lambda_1^\alpha = 0 \\ \sum_j \alpha_j c_{3j} + \lambda_2^\alpha = 0 \\ \sum_j \alpha_j c_{4j} + \lambda_2^\alpha = 0 \\ \alpha_1 + \alpha_2 = 1 \\ \alpha_3 + \alpha_4 = 0 \end{array} \right\} \begin{array}{l} \sum_j \alpha_j (c_{1j} - c_{2j}) = 0 \\ \sum_j \alpha_j (c_{3j} - c_{4j}) = 0 \\ \alpha_2 = 1 - \alpha_1 \\ \alpha_4 = -\alpha_3 \end{array}$$

Characteristics of β^* :

$$L_\beta = \sum_i \sum_j \beta_i \beta_j c_{ij} + \lambda_1^\beta (\beta_1 + \beta_2) + \lambda_2^\beta (\beta_3 + \beta_4 - 1)$$

$$\frac{dL_\beta}{d\beta} = 0 \Rightarrow \left. \begin{array}{l} \sum_j \beta_j c_{1j} + \lambda_1^\beta = 0 \\ \sum_j \beta_j c_{2j} + \lambda_1^\beta = 0 \\ \sum_j \beta_j c_{3j} + \lambda_2^\beta = 0 \\ \sum_j \beta_j c_{4j} + \lambda_2^\beta = 0 \\ \beta_1 + \beta_2 = 0 \\ \beta_3 + \beta_4 = 1 \end{array} \right\} \begin{array}{l} \sum_j \beta_j (c_{1j} - c_{2j}) = 0 \\ \sum_j \beta_j (c_{3j} - c_{4j}) = 0 \\ \beta_2 = -\beta_1 \\ \beta_4 = 1 - \beta_3 \end{array}$$

Krav til BLUE for $\Delta^+ = \sum_i z_i R(x_i)$

$$z_i^* = \operatorname{argmax} \left\{ \begin{array}{l} \sum_i \sum_j z_i z_j c_{ij} \\ z_1 + z_2 = 1 \\ z_3 + z_4 = -1 \end{array} \right\} \quad \left. \begin{array}{l} \operatorname{Var}\{\Delta^+\} = \sum_i \sum_j z_i z_j c_{ij} \\ E\{\Delta - \Delta^+\} = 0 \Rightarrow a \\ a - b = (z_1 + z_2)a + (z_3 + z_4)b \end{array} \right\}$$

$$Lz = \sum_i \sum_j z_i z_j c_{ij} + \lambda_1^z (z_1 + z_2 - 1) + \lambda_2^z (z_3 + z_4 + 1)$$

$$\frac{dLz}{dz_i} = 0 \Rightarrow \left. \begin{array}{l} \sum_j z_j c_{1j} + \lambda_1^z = 0 \\ \sum_j z_j c_{2j} + \lambda_1^z = 0 \\ \sum_j z_j c_{3j} + \lambda_2^z = 0 \\ \sum_j z_j c_{4j} + \lambda_2^z = 0 \\ z_1 + z_2 = 1 \\ z_3 + z_4 = -1 \end{array} \right\} \begin{array}{l} \sum_j z_j (c_{1j} - c_{2j}) = 0 \\ \sum_j z_j (c_{3j} - c_{4j}) = 0 \\ z_2 = 1 - z_1 \\ z_4 = -1 - z_3 \end{array}$$

These expressions uniquely define BLUE for Δ !

Set $z_i = \alpha_i - \beta_i$ and insert:

$$\sum_j (\alpha_j - \beta_j) (c_{1j} - c_{2j}) = \overbrace{\sum_j \alpha_j (c_{1j} - c_{2j})} = 0 - \overbrace{\sum_j \beta_j (c_{1j} - c_{2j})} = 0 = 0$$

$$\sum_j (\alpha_j - \beta_j) (c_{3j} - c_{4j}) = \overbrace{\sum_j \alpha_j (c_{3j} - c_{4j})} = 0 - \overbrace{\sum_j \beta_j (c_{3j} - c_{4j})} = 0 = 0$$

$$\alpha_2 - \beta_2 = 1 - \alpha_1 + \beta_1 = \alpha_2 - \beta_2$$

$$\alpha_4 - \beta_4 = -1 - \alpha_3 + \beta_3 = \alpha_4 - \beta_4$$

Hence $z_i^* = \alpha_i^* - \beta_i^*$ is the BLUE-weights.

$$\Delta^+ = \hat{\Delta} = \sum_i (\alpha_i^* - \beta_i^*) R(x_i) !$$

Conclusion:

The estimator $\hat{\Delta} = \hat{a} - \hat{b}$ is the BLUE for Δ !!

PROBLEM 2 EVENT RANDOM FIELD

Homogeneous PRF intensity λ on $D \subset \mathbb{R}^2$

Area of D is ~~area~~ - known constant

No of points in D is N - RV

No of obs. points in D with obs. prob p is O - RV

a) Definition of PRF $\{X_1, \dots, X_N; D \subset \mathbb{R}^2\}$

Alt 1:

$$N \rightsquigarrow \text{Poisson}(\lambda a) = \frac{(\lambda a)^n}{n!} e^{-\lambda a}; \quad n=0, 1, 2, \dots$$

$$[X_1, \dots, X_N | N=n] \rightsquigarrow \prod_{i=1}^n \text{Uni}[D] = \prod_{i=1}^n \frac{1}{a}$$

Alt 2:

For all B in D : $N \rightsquigarrow \text{Poisson}(\lambda a)$

For all B_1, \dots, B_k , for all k , disjoint in D :

$(N_{B_1}, \dots, N_{B_k})$ independent

where N_B is no. of points in B .

b)

No of points in D - N - prior pdf

$$p(n) = \frac{(\lambda a)^n}{n!} e^{-\lambda a} \quad - \text{Poisson}$$

No of obs. in D given $N=n$ - $[O|N=n]$ - likelihood

$$p(\sigma | n) = \begin{cases} \binom{n}{\sigma} p^\sigma (1-p)^{n-\sigma} &; \sigma \leq n \\ 0 &; \sigma > n \end{cases} \quad \text{Binomial}$$

Focus on

No of points in D given $O=\sigma$ - $[N|O=\sigma]$ - post.

$$p(n | \sigma) = \frac{p(\sigma | n) p(n)}{p(\sigma)}$$

Note that

$$\begin{aligned}
 p(\sigma) &= \sum_{n=0}^{\infty} p(\sigma|n) p(n) \\
 &= \sum_{n=\sigma}^{\infty} p(\sigma|n) p(n) \\
 &= \frac{1}{\sigma!} p^{\sigma} e^{-\lambda a} \sum_{n=\sigma}^{\infty} \frac{n!}{\sigma!(n-\sigma)!} (1-p)^{n-\sigma} \frac{(\lambda a)^n}{n!} \\
 &= \frac{1}{\sigma!} p^{\sigma} e^{-\lambda a} (\lambda a)^{\sigma} \underbrace{\sum_{n=\sigma}^{\infty} \frac{[(1-p)\lambda a]^{n-\sigma}}{(n-\sigma)!}}_{e^{(1-p)\lambda a}} \\
 &= \frac{(p\lambda a)^{\sigma}}{\sigma!} e^{-p\lambda a}
 \end{aligned}$$

Hence:

$$\begin{aligned}
 p(n|\sigma) &= \begin{cases} \frac{n!}{\sigma!(n-\sigma)!} p^{\sigma} (1-p)^{n-\sigma} \frac{(\lambda a)^n}{n!} e^{-\lambda a} \frac{\sigma!}{(p\lambda a)^{\sigma}} e^{p\lambda a} & ; n \geq \sigma \\ 0 & ; n < \sigma \end{cases} \\
 &= \begin{cases} \frac{[(1-p)\lambda a]^{n-\sigma}}{(n-\sigma)!} e^{-(1-p)\lambda a} & ; n \geq \sigma \\ 0 & ; n < \sigma \end{cases}
 \end{aligned}$$

NOTE that the difference between n and σ , $(n-\sigma)$, follows a Poisson $(1-p)\lambda a$ which corresponds to the points not observed. In particular $p=1$, exact observations give:

$$p(n|\sigma) = \begin{cases} 0 & n > \sigma \\ 1 & n = \sigma \\ 0 & n < \sigma \end{cases}$$

PROBLEM 3 MOSAIC RANDOM FIELD

$$L: \{L_x; x \in \mathcal{L}_\Phi\} \text{ - MRF} \quad \mathcal{L}_\Phi: (100 \times 100)$$

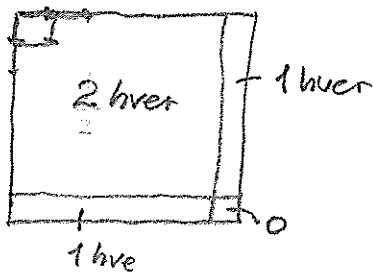
$$L_x \in \{-1, 1\}$$

$$\text{Prob}\{L=l\} = \text{const} \cdot \exp\left\{\beta \sum_{\langle u,v \rangle} l_u l_v\right\}$$

a) Most and least probable outcomes of L .

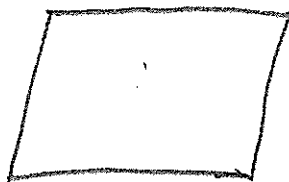
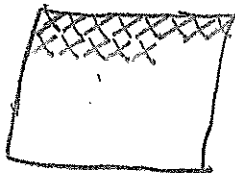
Note that $\# \langle u,v \rangle =$

$(99 \times 99) \times \frac{4}{2} =$	19800
$(2 \times 99) \times \frac{2}{2} =$	198
$(1 \times 1) \times 0 =$	0
	19800



Notation $\boxtimes = -1$ $\square = 1$

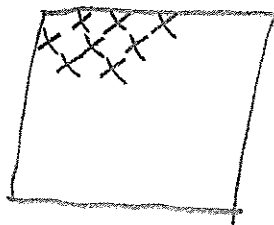
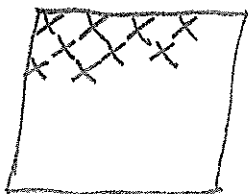
Most probable:



all $l_u l_v = 1$
 $\sum_{\langle u,v \rangle} l_u l_v = 19800$

$$\text{Prob}\{L=l\} = \text{const} \times \exp\{19800\beta\} = \text{const} \underbrace{\exp\{\beta\}}_{> 1}^{19800}$$

Least probable:



all $l_u l_v = -1$
 $\sum_{\langle u,v \rangle} l_u l_v = -19800$

$$\text{Prob}\{L=l\} = \text{const} \times \exp\{-19800\beta\} = \text{const} \frac{1}{\underbrace{\exp\{\beta\}}_{> 1}^{19800}}$$

Markov model:

$$\text{Prob}\{l_s = l_s \mid l_{-s} = l_{-s}\} = \frac{\text{Prob}\{L = (l_s, l_{-s})\}}{\sum_{l'_s \in \{-1, 1\}} \text{Prob}\{L = (l'_s, l_{-s})\}}$$

$$= \frac{\text{const.} \cdot \exp\left\{\beta \sum_{\substack{\langle u, v \rangle \\ u, v \neq s}} l_u l_v\right\} \exp\left\{\beta \sum_{\langle s, t \rangle} l_s l_t\right\}}{\sum_{l'_s \in \{-1, 1\}} \text{const.} \cdot \exp\left\{\beta \sum_{\substack{\langle u, v \rangle \\ u, v \neq s}} l_u l_v\right\} \exp\left\{\beta \sum_{\langle s, t \rangle} l'_s l_t\right\}}$$

$$= \frac{\exp\left\{\beta \sum_{\langle s, t \rangle} l_s l_t\right\}}{\exp\left\{-\beta \sum_{\langle s, t \rangle} l_t\right\} + \exp\left\{\beta \sum_{\langle s, t \rangle} l_t\right\}} \quad ; \text{ all } s \in \mathcal{S}_D$$

The major differences between the Gibbs & Markov models are:

- the former is joint pdf
 - the latter uni-conditional pdf's all $s \in \mathcal{S}_D$
- the former has non-computable const
 - the latter has computable const