

MOMENTS [H: 4.2]

TMA 4267 [L2]

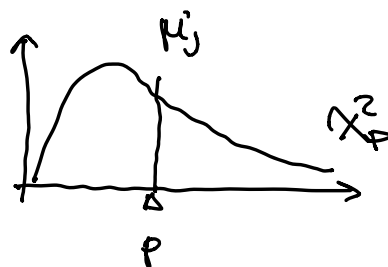
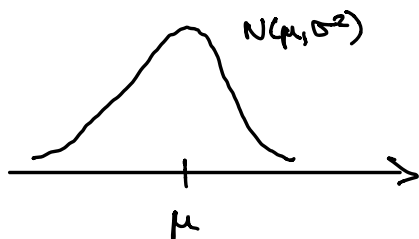
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$\mathbf{X}$ is a continuous random vector.
 $p \times 1$

Mean (first order moment)

expected value
 center of gravity
 location of distribution

$$E(\mathbf{X}_j) = \int_{-\infty}^{\infty} x_j f_j(x_j) dx_j$$



DEF: Let $\mathbf{X}$ be a random vector

$$\mu = E(\mathbf{X}) = \{E(\mathbf{X}_j)\} \leftarrow \text{vector with this as the } j\text{th element}$$

$$\begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_p \end{bmatrix}$$

$\Rightarrow E(\mathbf{X}_j)$ is calculated from the marginal distribution of $\mathbf{X}_j$ and contains no information about dependencies between $\mathbf{X}_j$ and $\mathbf{X}_k$
 $j \neq k$

We also define a random matrix = matrix of RVs and $E(\mathbf{X}) = \{E(\mathbf{X}_{ij})\}$ $\leftarrow E$ of each element

Remember: $\mathbb{R} \rightarrow E(aX+b) = \int_{-\infty}^{\infty} (ax+b) f(x) dx$
 scalar $= a \int_{-\infty}^{\infty} x f(x) dx + b \int_{-\infty}^{\infty} f(x) dx$
 $= a E(X) + b$

RULES FOR MEAN

$\mathbb{X}$ and $\mathbb{Y}$ are random matrices (n may be 1)
 $n \times p$ $n \times p$

and $\mathbb{A}$ and $\mathbb{B}$ are constant matrices
 $m \times n$ $p \times q$

1) $E(\mathbb{X} + \mathbb{Y}) = E(\mathbb{X}) + E(\mathbb{Y})$

Proof: Look at element $Z_{ij} = X_{ij} + Y_{ij}$ and
 see that $E(Z_{ij}) = E(X_{ij} + Y_{ij}) = E(X_{ij}) + E(Y_{ij})$

2) $E(\mathbb{A} \mathbb{X} \mathbb{B}) = \mathbb{A} E(\mathbb{X}) \mathbb{B}$

Proof: look at element (i,j) of $\mathbb{A} \mathbb{X} \mathbb{B}$

$$e_{ij} = \sum_{k=1}^n a_{ik} \sum_{l=1}^p x_{kl} b_{lj}$$

and see that $E(e_{ij})$ is the element (ij) of $\mathbb{A} E(\mathbb{X}) \mathbb{B}$.

Covariance matrix [H4.2]

- ① From TMA4240/42 & ST1101: X and Y are scalar RVs with $E(X) = \mu_x$ and $E(Y) = \mu_y$.

$$\begin{aligned} a) \text{ Cov}(X, Y) &= E((X - \mu_x)(Y - \mu_y)) \\ &\stackrel{c)}{=} E(X \cdot Y) - \mu_x \mu_y \end{aligned}$$

Remember: $\text{Cov}(X, Y) > 0$: high X and high Y
 < 0 : high X and low Y
 $= 0$: no linear pattern

$$b) \text{ Var}(X) = \text{Cov}(X, X) = E(X^2) - \mu_x^2$$

- d) $\text{Cov}(X, Y) = 0$ if X and Y are independent, but not necessarily the opposite

- ② Now: random vectors

a) DEF [H4.16]

E_x
Chemical process
 X = temp, pressure
 Y = yield, quality

X and Y are two random vectors.
 $p \times 1$ $q \times 1$

$$E(X) = \mu_x \quad \text{and} \quad E(Y) = \mu_y$$

$$\text{Cov}(\underline{X}, \underline{Y}) = E \left[\underbrace{(\underline{X} - \underline{\mu}_X)}_{p \times 1} \underbrace{(\underline{Y} - \underline{\mu}_Y)^T}_{1 \times q} \right]$$

$$= \sum \text{Cov}(\underline{X}, \underline{Y})$$

↑
sigma

and $\text{Cov}(\underline{X}, \underline{Y}) = 0$ if $\underline{X}$ and $\underline{Y}$ are independent.

If $p=2, q=3$

$$\text{Cov}(\underline{X}, \underline{Y}) = \begin{bmatrix} \text{Cov}(X_1, Y_1) & \text{Cov}(X_1, Y_2) & \text{Cov}(X_1, Y_3) \\ \text{Cov}(X_2, Y_1) & \text{Cov}(X_2, Y_2) & \text{Cov}(X_2, Y_3) \end{bmatrix}$$

Not a square matrix, but $\text{Cov}(\underline{X}, \underline{Y}) = \text{Cov}(\underline{Y}, \underline{X})^T$

$$b) \underbrace{\text{Cov}(\underline{X}, \underline{X})}_{p \times p} = E \left[(\underline{X} - \underline{\mu}_X)(\underline{X} - \underline{\mu}_X)^T \right]$$

$$= \begin{bmatrix} \underbrace{E[(X_1 - \mu_1)(X_1 - \mu_1)]}_{\text{Var}(X_1)} & \dots & \underbrace{E[(X_1 - \mu_1)(X_p - \mu_p)]}_{\text{Cov}(X_1, X_p)} \\ \vdots & \ddots & \vdots \\ \underbrace{E[(X_p - \mu_p)(X_1 - \mu_1)]}_{\text{Cov}(X_p, X_1)} & \dots & \underbrace{E[(X_p - \mu_p)(X_p - \mu_p)]}_{\text{Var}(X_p)} \end{bmatrix}$$

$$= \Sigma = \Sigma_{xx}$$

$$= \underline{\text{Cov}(\mathbf{X})} \text{ or } \text{Var}(\mathbf{X})$$

$$= \text{"variance-covariance matrix"}$$

Example: 4x4 matrix

$$\begin{aligned} \text{Observations: } \text{Cov}(\mathbf{X}_1, \mathbf{X}_2) &= \text{Cov}(\mathbf{X}_2, \mathbf{X}_1) \\ &= E[(\mathbf{X}_1 - \mu_1)(\mathbf{X}_2 - \mu_2)] \\ &= \iint_{-\infty}^{\infty} (x_1 - \mu_1)(x_2 - \mu_2) f(x_1, x_2) dx_1 dx_2 \end{aligned}$$

Σ is a symmetric matrix.

Cont.

$$c) \text{Cov}(\mathbf{X}, \mathbf{Y}) = \underset{\substack{\uparrow \\ \text{Rec Ex 1. P3}}}{E(\mathbf{X} \mathbf{Y}^T)} - \mu_x \cdot \mu_y^T$$

$$\underset{p \times p}{\text{Cov}(\mathbf{X})} = E(\underset{p \times 1}{\mathbf{X}} \underset{1 \times p}{\mathbf{X}^T}) - \underset{p \times 1}{\mu_x} \underset{1 \times p}{\mu_x^T}$$

d) As before if $\mathbf{X}_i$ and $\mathbf{Y}_j$ are independent

$$\Rightarrow \text{Cov}(\mathbf{X}_i, \mathbf{Y}_j) = 0.$$

And if all pairs of $\mathbf{X}$ s and $\mathbf{Y}$ s are ^{$p \times q$} independent

$$\Rightarrow \text{Cov}(\mathbf{X}, \mathbf{Y}) = \mathbf{0}$$

Correlation

$$X_1 \text{ and } X_2: \text{Corr}(X_1, X_2) = \frac{\text{Cov}(X_1, X_2)}{\sqrt{\text{Var}(X_1) \cdot \text{Var}(X_2)}}$$

Rec Ex1, P1i do this in R

See matrix formula on slides

Ex: Given Σ find g :

$$\begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 1 \\ 0 & 0 & 2 & 1 \\ 0 & 1 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & \frac{1}{2} & 0 & 0 \\ \frac{1}{2} & 1 & 0 & \frac{1}{2} \\ 0 & 0 & 1 & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} & 1 \end{bmatrix}$$

Q: can information in Σ be condensed?

$$\text{tr}(\Sigma) = \sum_{i=1}^p \text{Var}(X_i) = \text{"total variance"}$$

$\uparrow$
trace = sum of diagonal elements

$$\det(\Sigma) = \text{"generalized variance"}$$

E and Cov of linear combinations

$$\begin{array}{ll} \mathbf{X} & \text{RV} \\ p \times 1 & \end{array} \quad \begin{array}{l} E(\mathbf{X}) = \mu_X \\ \text{Cov}(\mathbf{X}) = \Sigma_X \end{array}$$

$$\begin{array}{ll} \mathbf{C} & \text{Constants} \\ k \times p & \end{array}$$

Consider: $\mathbf{Z} = \mathbf{C}\mathbf{X} = \begin{bmatrix} \sum_{j=1}^p c_{1j} X_j \\ \sum_{j=1}^p c_{2j} X_j \\ \vdots \\ \sum_{j=1}^p c_{kj} X_j \end{bmatrix}$

Vector
of k linear combinations

$$1) \mu_Z = E(\mathbf{Z}) = E(\mathbf{C}\mathbf{X}) = E(\mathbf{C}\mathbf{X}\mathbf{I})$$

$E(\mathbf{A}\mathbf{X}\mathbf{B})$
where $\mathbf{B} = \mathbf{I}$

$$= \mathbf{C} E(\mathbf{X}) \mathbf{I} = \mathbf{C} E(\mathbf{X}) = \underline{\underline{\mathbf{C}\mu_X}}$$

$$2) \Sigma_Z = \text{Cov}(\mathbf{Z}) = \text{Cov}(\mathbf{C}\mathbf{X}) \stackrel{?}{=} \mathbf{C} \text{Cov}(\mathbf{X}) \mathbf{C}^T$$
$$= \mathbf{C} \Sigma_X \mathbf{C}^T$$

$$\text{Proof: } \text{Cov}(\mathbf{Z}) = E[(\mathbf{Z} - \mu_Z)(\mathbf{Z} - \mu_Z)^T]$$

$$= E \left((C\bar{X} - C\mu_X)(C\bar{X} - C\mu_X)^T \right)$$

$$= E \left(C \underbrace{(\bar{X} - \mu_X)(\bar{X} - \mu_X)^T}_{\substack{Y \\ p \times p}} C^T \right)$$

use $E(AXB) = A E(X) B$

$\begin{matrix} & \nearrow & \uparrow & \nwarrow \\ & C & Y & C^T \end{matrix}$

$$= C \underbrace{E((\bar{X} - \mu_X)(\bar{X} - \mu_X)^T)}_{\text{Cov}(\bar{X})} C^T = \underline{\underline{C \text{Cov}(\bar{X}) C^T}}$$

Example: Cork data and C matrix

$$\bar{X} = \begin{bmatrix} \bar{X}_N \\ \bar{X}_E \\ \bar{X}_S \\ \bar{X}_W \end{bmatrix}, \text{ but want } \begin{matrix} N-S \\ E-W \\ (E+W)-(N+S) \end{matrix} \left| \begin{matrix} k=3 \end{matrix} \right.$$

$Y = C\bar{X}$, where

$\underbrace{\quad}_{p=4}$

$$C_{3 \times 4} = \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ -1 & 1 & -1 & 1 \end{bmatrix}$$

$E(Y_1) = 1^{\text{th}} \text{ element of } C\mu$

$\text{Cov}(Y_1, Y_3) = \text{element } (1,3) \text{ of } C\Sigma C^T$