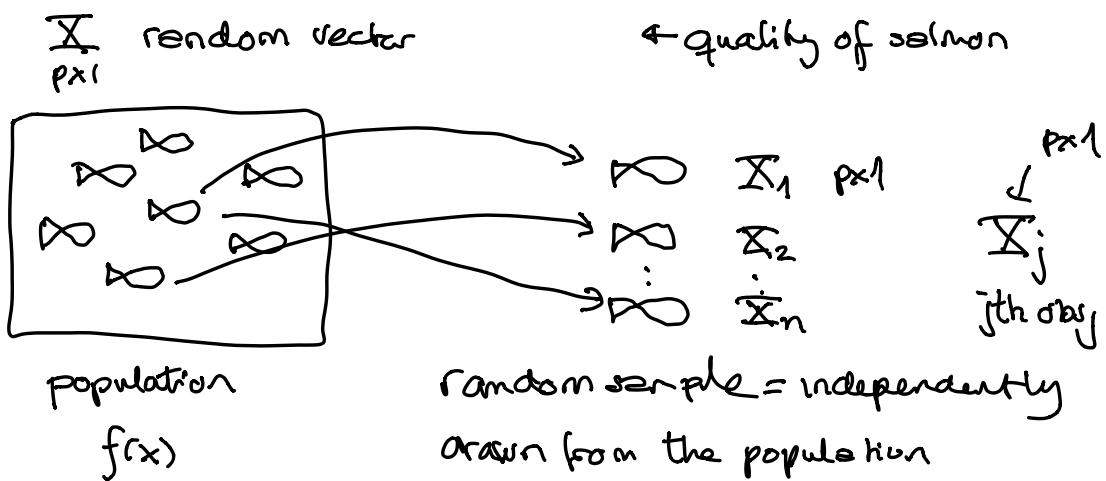


Parameter estimation: μ and Σ

TMA4267 L6

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[H3.3, H4.5]



3 variations on notation:

a) $X_j, j=1, \dots, n$

b) $\underset{n \times p}{\mathbf{X}} = \begin{bmatrix} \mathbf{x}_1^T \\ \mathbf{x}_2^T \\ \vdots \\ \mathbf{x}_n^T \end{bmatrix}$ data matrix x rows = Obj
 cols = RV's

c) $\underset{np \times 1}{\mathbf{x}^*} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_n \end{bmatrix}$ vector of RV's

How can we use $X_j, j=1, \dots, n$ to estimate $\mu = E(\mathbf{X})$
and $\Sigma = \text{Cov}(\mathbf{X})$?

① Estimating $\mu = E(\bar{X})$

$$\hat{\bar{X}} = \underset{p \times 1}{\frac{1}{n} \sum_{j=1}^n \bar{X}_j}$$

$$E(\hat{\bar{X}}) = E\left(\underset{p \times 1}{\frac{1}{n} \sum_{j=1}^n \bar{X}_j}\right) = \underset{unbiased}{\frac{1}{n} \sum_{j=1}^n \overbrace{E(\bar{X}_j)}^{\mu}} = \frac{1}{n} \cdot n \cdot \mu = \underline{\mu}$$

$$\text{Cov}(\hat{\bar{X}}) = \underset{p \times p}{\text{Cov}\left(\frac{1}{n} \sum_{j=1}^n \bar{X}_j\right)}$$

$$= \left(\frac{1}{n}\right)^2 \sum_{j=1}^n \text{Cov}(\bar{X}_j)$$

$\bar{X}_1, \dots, \bar{X}_n$ independent

$$\text{Cov}(\bar{X}) = E((\bar{X} - \mu)(\bar{X} - \mu)^\top)$$

$$= \frac{1}{n^2} \sum_{j=1}^n \underset{\text{Cov}(\bar{X}_j)}{\sum} = \frac{1}{n^2} \cdot n \cdot \Sigma = \frac{1}{n} \underline{\underline{\Sigma}}$$

If $\bar{X}_1, \bar{X}_2, \dots, \bar{X}_n$ i.i.d $\overset{\text{identically}}{\downarrow}$ $N_p(\mu, \Sigma)$

$\overset{\text{independent}}{\uparrow}$ $\overset{\text{distributed}}{\uparrow}$

$$\hat{\bar{X}} \sim N_p(\mu, \frac{1}{n} \Sigma)$$

(2) Estimating Σ

Motivation: $\Sigma = E((\bar{X} - \mu)(\bar{X} - \mu)^T)$

$$S = \frac{1}{n-1} \sum_{j=1}^n (\underbrace{\bar{X}_j - \bar{\bar{X}}}_{p \times p})(\underbrace{\bar{X}_j - \bar{\bar{X}}}_{p \times p})^T$$

$$E(S) = \dots = \Sigma \quad \text{unbiased}$$

↑
see proof, separate file

Quadratic forms [F: B33, Theorem B.2]

\mathbf{X} random vector, A constant matrix

$$\underbrace{\mathbf{X}^T A \mathbf{X}}_{\begin{matrix} 1 \times p \\ P \times p \\ 1 \times 1 \end{matrix}} = \sum_{i=1}^p \sum_{j=1}^p a_{ij} x_i \cdot x_j \text{ is quadratic form.}$$

$\mu = E(\mathbf{X})$, $\Sigma = \text{Cov}(\mathbf{X})$

The "trace formula": $\text{Cov}(\mathbf{X})$

$$E(\mathbf{X}^T A \mathbf{X}) = \text{tr}(A \Sigma) + \mu^T A \mu$$

Ex: V2014 P1a

$$p=3, \mu = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \Sigma = I, A = \begin{pmatrix} \frac{2}{3} & -\frac{1}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & -\frac{1}{3} & \frac{2}{3} \end{pmatrix}$$

$$E(\mathbf{X}^T A \mathbf{X}) = \text{tr}(\underbrace{A I}_A) + (1 \ 1 \ 1) A \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 0 \cdot \frac{2}{3} + (1 \ 1 \ 1) \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = 0$$

Symmetric and idempotent matrices

A is symmetric ; $A = A^T$

A is idempotent ; $AA = A$

* The eigenvalues of A are 0 and 1

$$\begin{aligned} Ae &= \lambda e \\ \underbrace{Ae}_\lambda &= \underbrace{A\lambda e}_\lambda \\ A^2e &= \lambda \underbrace{Ae}_\lambda = \lambda^2 e \\ \underbrace{\lambda e}_\lambda &\quad \text{only 0 and 1 possible} \end{aligned}$$

* The rank of a matrix is the number of linearly independent rows, and also given as the number of nonzero eigenvalues.

* General rule: $\text{tr}(A) = \sum_{i=1}^n \lambda_i$, since $\lambda_i = 0$ or 1
 $\text{tr}(A)$ must be the number of nonzero eigenvalues.

$\Rightarrow \text{tr}(A) = \text{rank}(A)$ for symmetric and idempotent A .

Now: example = the centering matrix.
(RecEx1.P4, CompEx1.2a)

$$\underset{n \times n}{\underbrace{\mathbf{I} - \frac{1}{n} \mathbf{1}\mathbf{1}^T}} = \begin{pmatrix} 1-\frac{1}{n} & -\frac{1}{n} & \dots & -\frac{1}{n} \\ -\frac{1}{n} & 1-\frac{1}{n} & \ddots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ -\frac{1}{n} & \dots & \dots & 1-\frac{1}{n} \end{pmatrix}$$

Distribution of quadratic form

$$\underset{p \times 1}{\mathbf{Z}} \sim N_p(\mathbf{0}, \mathbf{I})$$

$\nwarrow \mathbf{Z}_1, \dots, \mathbf{Z}_p \text{ are independent}$

R is symmetric and idempotent with $\text{rank}(R) = r$.

Result: $\mathbf{Z}^T R \mathbf{Z} \sim \chi_r^2$

Proof via $R = P \Lambda P^T$

$$\mathbf{Z}^T R \mathbf{Z} = \text{sum of } r \text{ } N(0, 1)^2 \sim \chi_r^2$$

In CompEx 1.12c: $\mathbf{Z} \sim N_n(\mu \mathbf{1}, \sigma^2 \mathbf{I})$

\Downarrow

$$N_n(\mathbf{0}, \mathbf{I})$$

Finally: Ratio of quadratic forms
(more in Part 2-3)

- * $\bar{X} \sim N_p(0, I)$
- * R and S symmetric and idempotent with
 $\text{rank}(R) = r$, $\text{rank}(S) = s$
- * $RS = 0$

Result: a) $\bar{X}^T R \bar{X} \sim \chi^2_r$,
 $\bar{X}^T S \bar{X} \sim \chi^2_s$
 and independent.

Because: $R\bar{X}$ and $S\bar{X}$ are indep if $R \text{Cov}(\bar{X}) S^T = 0$

We have $\text{Cov}(\bar{X}) = I$ and $S = S^T$ so

$R^T S^T = RS < 0 \Rightarrow$ yes!

Then a function of $R\bar{X}$ $f(R\bar{X})$ and function
of $S\bar{X}$ $g(S\bar{X})$ are also independent \Rightarrow (*) see
next page
for a comment

$\bar{X}^T R \bar{X}$ will be indep of $\bar{X}^T S \bar{X}$

b)

$$\frac{\frac{\bar{X}^T R \bar{X}}{r}}{\frac{\bar{X}^T S \bar{X}}{s}} \sim F_{r,s}$$

$$\frac{\frac{\chi^2_r}{r}}{\frac{\chi^2_s}{s}} \sim F_{r,s}$$

This result will be used a lot in Part 2+3.

⊗ Here $f(R\mathbf{x}) = \frac{1}{r} (\mathbf{R}\mathbf{x})^T R\mathbf{x} = \frac{1}{r} \mathbf{x}^T \underbrace{R^T R}_{\begin{array}{l} " \text{symmetric} \\ R R \end{array}} \mathbf{x}$

$$= \frac{1}{r} \mathbf{x}^T R\mathbf{x}$$

R
 $" \text{identity}$
 R

and the same for $g(\delta\mathbf{x})$.

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