

(1a)

$$(1+aB) \cdot (1+LB^7) = 1+aB+bB^7+abB^8$$

$$= \theta(B) \quad \text{grad } 8$$

$$\varphi(B) = 1 \quad \text{grad } 0$$

$$\varphi(B)X = \theta(B)Z \Rightarrow X \sim \text{ARMA}(0,8)$$

$$= \text{MA}(8)$$

fordi  $X$  også er svakt stationær ved

$$X_t = Z_t + aZ_{t-1} + bZ_{t-7} + abZ_{t-8} \quad (*)$$

$$E(X_t) = 0 \quad (\text{uavh. av } t)$$

$$E(X_{t+h} X_t) = \gamma(h) \quad (\text{uavh. av } t)$$

fra regning i ld.

(15) Fra (\*) er  $X = \sum_{j=0}^t \psi_j z_{t-j}$   
d.v.s. afhængig af forhistorien  
 $\dots, z_{-1}, z_0, \dots, z_t$ .

(c)  $Z = (1 + aB)^{-1} (1 + bD^2)^{-1} X$   
 unikt via geometriske rekke fordi  
 $|a|, |b| < 1$  og det er sikkert  
 at  $(Z \sim WN(0, \sigma^2))$   $Z$  er svakt  
 stasjonær.

Uten antagelse om svakt stasjonærhet  
 er  $Z$  ikke unikt gitt. Det  
 finnes 8 lineært uavhengige løsninger  
 til  $(1 + aB)(1 + bD^2)Z = 0$ .

Overstående gir  $Z_t = \sum_{j \geq 0} \pi_j X_{t-j}$  med  
 $\sum_{j \geq 0} |\pi_j| < \infty$ .

$$1 = (1 + aZ + bZ^2 + abZ^3) \cdot (1 + \pi_1 Z + \pi_2 Z^2 + \dots)$$

$$0 = \pi_1 + a \Rightarrow \pi_1 = -a$$

$$0 = \pi_2 + a\pi_1 + b \Rightarrow \pi_2 = -a\pi_1 - b$$

$$0 = \pi_3 + a\pi_2 \Rightarrow \pi_3 = -a\pi_2$$

$$0 = \pi_4 + a\pi_3 \Rightarrow \pi_4 = -a\pi_3 \quad \text{etc}$$

$$(1d) \quad X_t = Z_t + aZ_{t-1} + bZ_{t-7} + abZ_{t-8}$$

$$\gamma(-h) = \gamma(h) = \gamma_h = 0 \quad \text{bertjeft gra:}$$

$$\gamma_0 = E(X_t X_t) = [1 + a^2 + b^2 + a^2 b^2] \sigma^2$$

$$\begin{aligned} \gamma_1 &= E(X_{t+1} X_t) = E[(Z_{t+1} + aZ_t + bZ_{t-6} + abZ_{t-7}) \cdot X_t] \\ &= (a + ab^2) \sigma^2 \end{aligned}$$

$$\gamma_2 = E(X_t (Z_{t+2} + aZ_{t+1} + bZ_{t-5} + abZ_{t-6})) = 0$$

$$\gamma_3 = E(X_t (Z_{t+3} + aZ_{t+2} + bZ_{t-4} + abZ_{t-5})) = 0 = \gamma_4 = \gamma_5$$

$$\gamma_6 = ab\sigma^2, \quad \gamma_7 = (1+a^2)b\sigma^2, \quad \gamma_8 = ab\sigma^2$$

$h$	0	1	7	8	$\left. \begin{array}{l} \gamma(h) = \gamma \cdot \left\{ \begin{array}{l} \frac{1+a^2+b^2+ab^2}{1} \quad  h =0 \\ \frac{a \cdot (1+b^2)}{1} \quad  h =1 \\ ab \quad  h =6 \\ \frac{b \cdot (1+a^2)}{1} \quad  h =7 \\ ab \quad  h =8 \\ 0 \quad \text{ellers} \end{array} \right. \end{array} \right\}$
$\gamma$	0,65	-0,27	-0,26	0,11	
$\rho$	1	-0,41	-0,41	0,16	


Se også likelihood i Fig. 2  $\ddot{=}$   
Lag 1 & 7 dominerer.

(1e)  $\hat{X}_n$  is the projection of  $X_n$  onto the subspace spanned by  $1, X_1, \dots, X_{256}$ . It is unique.

$$\left[ \hat{X}_n = \sum_{j=0}^{256} c_j X_j \quad X_0 = 1 \right]$$

$c_j$ 's are not unique except if  $X_j$  are lin. independent

Note: Completeness of  $\mathcal{H} = L^2(\Omega)$  is not needed in the argument: A finite dimensional subspace is complete.

(If)  $(1-B)(1-B^2)$  has (8) roots  
on the unit circle so 1  
cannot be w.stationary. 

(19) No  $X$  is, but 8  
linear independent solutions  
of  $(1-D)(1-D^7)T_H = 0$  gives  
non-uniqueness. The general solution is  
 $T = T_p + T_H$  where  $T_p$  is a particular  
solution.

(1h)  $\hat{t}_{200} = t_{200}$  with  $0 = \omega_{200}$ .

$$(1-B) \cdot (1-B^7) = 1 - B - B^7 + B^8 \quad (2)$$

$$\Rightarrow \hat{T}_n = \hat{T}_{n-1} + \hat{T}_{n-7} - \hat{T}_{n-8} + \hat{X}_n \quad (R)$$

where  $\hat{\cdot}$  denotes projection on linear span of  $1, T_{-7}, T_{-6}, \dots, T_{256}$ . This is the same as the linear span of  $1, T_{-7}, \dots, T_0, X_1, \dots, X_{256}$  due to (2).

Basic assumption:  $T_{-7}, \dots, T_0$  uncorrelated with  $X_i$ . This means that  $\hat{X}_n$  can be found as in 1e.

$$\hat{t}_{257} = t_{256} + t_{250} - t_{247} + \hat{X}_{257}$$

$$\text{and } \omega_{257}^2 = E \left( T_{257} - \hat{T}_{257} \right)^2 = E \left( X_{257} - \hat{X}_{257} \right)^2$$

These two can be calculated from the covariance function  $\gamma$  and the innovations algorithm.  
(Or Durbin-Levinson)

$\hat{t}_{200}$  can be calculated using (R)



repeatedly.

The iterative algorithm gives  
 $\approx 2$   
300.

(1i) The key is uncorrelated  
initial condition:  $X \perp T_{-1} \dots T_0$   
This ensures that  $\hat{t}_n$  is  
given recursively by previous  $\hat{t}_k$ 's and  
the  $\hat{X}_n$  prediction.

(2a) The cat count is uncertain and takes integer values for each day. //

(2b)  $0, 1, 2, \dots$  (but  $< S_{\text{mill}}$ ) //

(2c) Yes, possibly, since simplest model with  $0, 1, 2, \dots$  values.

Every second a certain probability of a new detected car.

Conditionally the above is reasonable, but unconditionally probably not.

A reasonable tentative model is

hence  $Y_{300} | Y_s, s < 300 \sim \text{Poisson}(\lambda_{300})$

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$$\begin{aligned}
 (2d) \quad & P(Y_{t_1} = y_{t_1}, \dots, Y_{t_k} = y_{t_k}) \\
 &= P\left(\underbrace{(Y_{t_1} = y_{t_1}) \cap \dots \cap (Y_{t_k} = y_{t_k})}_{\text{event}}\right)
 \end{aligned}$$

$$(Y_{t_i} = y_{t_i}) = \{\omega \mid Y_{t_i}(\omega) = y_{t_i}\}$$

defines both.

Note:  $(Y_t = y_t)$  is an event since  $Y_t$  is a random variable:

$$(Y_t = y_t) = \bigcap_{n=1}^{\infty} \left[ \left( Y_t \leq y_t - \frac{1}{n} \right)^c \cap (Y_t \leq y_t) \right]$$

Hence all probabilities above are defined.

(2e) Let  $B = (Y_{200} = y)$  and  
 $A = (Y_{-7} = y_{-7}, \dots, Y_{256} = y_{256})$ ,

so

$$g(y) = P(B|A) = \frac{P(B \cap A)}{P(A)}$$

(2f) Median and mean

$$\tilde{\mu} = \sum_y | \tilde{\mu} - y | g(y)$$

$$\sigma = \sqrt{\sum_y (\mu - y)^2 g(y)}$$

respectively and can be used  
to quantify the uncertainty a

$\mu = \sum y \cdot g(y)$ , but  $\tilde{\mu}$   
by optimization

Uncertainty:

2.5% &

and 97.5% percentiles

are also

a natural choice -

ISO GUM

2g) Must prove that  
 $U = \log(\max(V, 0.1))$   
 is a random variable if  $V$  is.

In our case  $V$  takes values  
 $0, 1, 2, \dots$ . This means that  
 $U$  takes values  $\log(0.1), \log(1), \log(2)$   
 $\dots$  on  $(V=0), (V=1), \dots$   
 so with probabilities  
 $(P(V=0), P(V=1), \dots)$

$$U = \sum_{i=0}^{\infty} u_i \cdot (V=i)$$

$$(U \leq u) = \bigcup_{\substack{i \\ u_i \leq u}} (V=i)$$

which is an event.

Note: There is 1-1 correspondence  
 between  $U$  and  $T$ . Both are discrete.

$$\textcircled{3a} \quad t_i = \log(\max(y_i, 0.1))$$

$$(1-D)(1-\beta^T) = 1 - \beta - \beta^T + \beta^8$$

$$X_i = t_i - t_{i-1} - t_{i-7} + t_{i-8}$$

gib  $X_1, \dots, X_{256}$   $n = 256$

To variabler for  $\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}$

abhangig von  $E(X_i) = 0$   
an das Wert  $i$  der. Diese an das Wert  
(hier  $i$  der  $X_i \rightarrow X_i - \bar{X}$ ).

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{i=1}^n X_{i+h} \cdot X_i \quad \begin{array}{l} X_i = 0 \\ i > 256 \end{array}$$

(35) A close look at fig. 1 gives a reason to expect a 7 day season, viz approx. 4 periods in each month. See e.g. between Sep & Oct. The source of the data also makes a 7 day season reasonable. This motivates the  $D_7$  term. The correlation is essentially 0 for  $h > 8$ , and motivates  $MA(8)$ , and the simplest combination is then as given.

See also  $ld$  which gives dominating negative peaks at lag 1 & 7.



3c) Using, or re-deriving,  
the formulae for  $\gamma(0)$ ,  $\gamma(1)$   
and  $\gamma(7)$  gives three equations  
for three unknowns.

Algebraic manipulation gives second  
order equations, and assuming  
(a), (b)  $\neq 1$ , give:

$$\gamma: \delta = -0.3379$$

$$a = -0.6512$$

$$a^2 = 0.3940$$

(3d) The covariance function is given as function of  $a, b, c$ .

The EM alg. can be used to calculate

$$L = \prod_{i=1}^{256} f(x_i | x_{i-1}, \dots, x_1)$$

since the conditions are Gaussian if  $z$  is assumed Gaussian. Minimization gives  $\hat{a}, \hat{b}, \hat{c}$

(3e) A forecast for  $T_{300}$  can be computed as in 1b.

A reasonable forecast is then

$$Y_{300} = \text{floor}(\exp(T_{300}))$$

(3d)

$$X_t = Z_t + aZ_{t-1} + bZ_{t-7} + abZ_{t-8}$$

La  $Z_{-7}, Z_{-6}, \dots, Z_0$  velges

'på passende vis'. Da er

$$Z_1 = X_1 - aZ_0 - bZ_{-6} - abZ_{-7}$$

$\vdots$

$$Z_{256} = X_{256} - aZ_{256-1} - bZ_{256-7} - abZ_{256-8}$$

'Passende vis' kan være i.i.d. fra  $N(0, \sigma^2)$ .

Et mere standard alternativ er

$$\begin{aligned} \hat{Z}_i &= (X_i - \hat{X}_i) / \hat{\sigma}_i \quad (\text{residual}) \\ &= \hat{W}_i \end{aligned} \quad \text{S. 3.1 RD.}$$

Et tredje:  $Z_t = \sum_{j=0}^{\infty} \pi_j X_{t-j}$

og  $\hat{Z}_t$  ved  $\hat{a}$  kan brude de observerte.

2g) No, because of Fig. 2

2h)  $Z^2$  modelled as an ARMA,  
so yes.

$Z^2$  is correlated in GARCH

2i) Initial estimates for  $Z$   
is from 3rd. A GARCH(1,1)  
in the form:

$$Z_t = \sqrt{h_t} \epsilon_t, \quad \epsilon_t \sim \text{ID}(0,1)$$

$$(1 - \rho, \beta) h_t = \alpha_0 + \alpha_1 Z_{t-1}^2 \quad (*)$$

$\alpha_0, \alpha_1, \rho, \beta$  can be found using  
the conditional  $Z$  of  $Z_t$ .  
This is determined from

The conditional variance  $h_t$ :

$$\tilde{z} = \prod_{t=2}^n \frac{1}{\sqrt{h_t}} \varphi\left(\frac{z_t}{\sqrt{h_t}}\right)$$

and (\*) determines  $h_t$  by  
recursion.