

Oppgave 8

a) Gitt initialverdi problemet

$$y' = \sqrt{y}, \quad y(0) = 1.$$

Skriv ned en *fullstending* algoritme for å finne en tilnærming til $y(2)$ ved bruk av implisitt (baklengs) Eulers metode, med steglengde $h = 2/N$.

Utfør et steg med algoritmen med $h = 0.1$, dvs. finn en tilnærming til $y(0.1)$.

NB! Algoritmen må gjerne skrives i form av kode i f.eks. MATLAB eller Python. Den skal være tilstrekkelig detaljert til at den kan implementeres.

a) Baklengs Euler: $u_{n+1} = u_n + h f(t_{n+1}, u_{n+1})$

Approximer $y(2)$ med steglengde $h = \frac{2}{N}$

$$y' = \sqrt{y} = f(t, y)$$

• Kode:

```
import math
```

```
N = 100 ← f.eks., kan endres
```

```
h = 2 / N
```

```
u = 1
```

← oppgaven spør kun om $y(2)$, så vi trenger ikke å lagre u_n for hver n

for i in range(N):

$$u = u + (h**2 + \text{math.sqrt}(4*u*h**2 + h**4))/2$$

print(u) ← tilnærning til $y(2)$

• Utleddning av formel for u_{n+1}

$$u_{n+1} = u_n + h\sqrt{u_{n+1}}$$

$$(h\sqrt{u_{n+1}})^2 = (u_{n+1} - u_n)^2$$

∴

$$u_{n+1}^2 - (2u_n + h^2)u_{n+1} + u_n^2 = 0$$

$$u_{n+1} = \frac{2u_n + h^2 \pm \sqrt{(2u_n + h^2)^2 - 4u_n^2}}{2}$$

$$= u_n + \frac{1}{2}h^2 \pm \frac{1}{2}\sqrt{4u_n h^2 + h^4}$$

$\geq \sqrt{h^4} = h^2$

$u_{n+1} - u_n < 0$ for $-$, og ≥ 0 for $+$.

Vi vil ha $y' = \sqrt{y} \geq 0$, så vi velger $+$.

Alternativ: bruk en rot-finnes på

def $g(x, s)$:

return $x - s - h * \text{math.sqrt}(x)$

for i in range(N):

$u =$ "lös $g(x, u) = 0$ m.h.p. x "

f.eks.

$u = \text{scipy.optimize.fsolve}(g, u, \text{args}=(s,))$
gjetning

• Ett steg med $h=0,1$

$$u_0 = 1$$

$$u_1 = u_0 + \frac{1}{2} (h^2 + \sqrt{4u_0 h^2 + h^4})$$

$$\approx 1,1051$$

Problem 3. (Ralston's method, 14 points)

For the ordinary differential equation

$$y'(t) = -6y(t), \quad \text{with } y(0) = 1,$$

consider *Ralston's method* given by the following Butcher tableau:

0	0	0
2/3	2/3	0
	1/4	3/4

Using the tableau and expanding the stage derivatives k_i , we can write the solution y_{n+1} in terms of the previous one, y_n , and of the time-step size $h > 0$. More precisely:

$$y_{n+1} = R(h)y_n, \quad \text{so that } y_n = [R(h)]^n y(0),$$

in which $R(h)$ is a second-degree polynomial.

- a) How many stages does this Runge–Kutta method have?
- b) Determine the polynomial $R(h)$.

RK med s steg

$$\left\{ \begin{aligned} u_{n+1} &= u_n + h \sum_{i=1}^s b_i K_i \end{aligned} \right.$$

$$\left\{ \begin{aligned} K_i &= f(t_n + c_i h, u_n + h \sum_{j=1}^s a_{ij} K_j) \end{aligned} \right.$$

$$\begin{array}{c|c} \vec{c} & A \\ \hline & \vec{b}^T \end{array}$$

a) 2 steg (fordi tabellen har 2 rader / kolonner)

$$\begin{array}{l|ll} b) & 0 & 0 \\ 0 & 0 & 0 \\ 2/3 & 2/3 & 0 \\ \hline & 1/4 & 3/4 \end{array} \quad \begin{aligned} K_1 &= f(t_n + 0, u_n + 0) \\ &= f(t_n, u_n) = -6u_n \\ K_2 &= f(t_n + \frac{2}{3}h, u_n + h\frac{2}{3}K_1) \end{aligned}$$

$$\begin{aligned} f(t, y) &= -6y \\ &= -6(u_n + h\frac{2}{3}K_1) \\ &= -6(u_n - \frac{2}{3}h6u_n) \\ &= -6u_n(1 - 4h) \end{aligned}$$

$$u_{n+1} = u_n + h\frac{1}{4}K_1 + h\frac{3}{4}K_2$$

$$= \dots = \underbrace{(1 - 6h + 18h^2)}_{R(h)} u_n$$

Problem 3 Numerical methods for ODEs [10 pts] Consider python code that solves an initial value problem with a Runge-Kutta method and prints the resulting x and y value after N steps:

```

1 def f(x, y):
2     return x * y**2
3
4 def step(x, y, h):
5     k1 = f(x, y)
6     k2 = f(x + h, y + h * k1)
7     y_new = y + (h / 2) * (k1 + k2)
8     x_new = x + h
9     return x_new, y_new
10
11 x = 0
12 y = 0.5
13 h = 0.1
14 N = 20
15
16 for n in range(N):
17     x, y = step(x, y, h)
18
19 print(x, y)

```

$x = t$ her

- a) What is the initial value problem that the code solves?
- b) Write the Butcher tableau for the method used. Is the method explicit or implicit? motivate your answer.

$$a) \quad y' = f(t, y) = t y^2 \quad \text{med} \quad y(0) = 0,5$$

$$b) \quad \left(\begin{array}{l} \text{RK med } s \text{ steg} \\ \left\{ \begin{array}{l} u_{n+1} = u_n + h \sum_{i=1}^s b_i K_i \\ K_i = f\left(t_n + c_i h, u_n + h \sum_{j=1}^s a_{ij} K_j\right) \end{array} \right. \end{array} \right) \quad \begin{array}{c|c} \vec{c} & A \\ \hline & \vec{b}^T \end{array}$$

$$2 \text{ steg} \begin{cases} K_1 = f(t_n, u_n) \\ K_2 = f(t_n + h, u_n + h \cdot K_1) \end{cases}$$

$$u_{n+1} = u_n + \frac{h}{2} (K_1 + K_2)$$

Butcher tabli:

0	0	0
1	1	0
	$\frac{1}{2}$	$\frac{1}{2}$

↖ eksplisitt

$a_{ij} = 0$ for $j \geq i$, så metoden er eksplisitt.