Regularisation by noise and nonlinear Young integrals

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Rough paths and SPDEs - Trondheim

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Regularisation by noise in a nutshell

Regularisation by noise refers to a class of phenomena in which ill-posed equations become well-posed under the introduction of noise; frequently observed in ODEs and PDEs.

Why is it important?

The model is a mathematical idealisation, obtained by ignoring less relevant factors in the dynamics; real systems are always affected by a background noise

 \leadsto physically observed solutions should be the ones stable under small noisy perturbations

→ vanishing noise selection criteria for mathematical solutions.

The "regularisation by noise program" ideated by Flandoli amounts to:

- 1. Find a physically meaningful, arbitrarily small noise restoring well-posedness in the equation.
- 2. Identify the zero noise limit (hopefully unique in some reasonable sense) **NB: this step is still mostly open!**

Probabilistic literature on Step 1.

There is now an extensive literature on regularisation for SDEs of the form

$$x_t = x_0 + \int_0^t b(s, x_s) \mathrm{d}s + \varepsilon W_t$$

with W suitable stochastic process (BM, Lévy, fBm), $\varepsilon > 0$. First results go back to Zvonkin (1974) and Veretennikov (1981).

A (very incomplete!) list of references:

- Krylov–Röckner (PTRL 2005): singular $b \in L_t^q L_x^p$;
- Flandoli–Gubinelli–Priola (Invent. 2010): flow and link with transport equation; later improved in works by Flandoli and collaborators;
- Works by Priola and collaborators for W Lévy noise;
- Works by Da Prato and collaborators for infinite dimensional ODEs with cylindrical BM;
- Nualart–Ouknine (SPA 2002) first considered *W* fBm; improved by Lê (EJP 2020).
- Proske and collaborators: very rough noises and C^{∞} regularisation.

Path-by-path uniqueness

In all of the above: W is a stoch. proc. on filtered $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t\geq 0}, \mathbb{P})$, uniqueness among solutions adapted to \mathcal{F}_t . But in principle the equation **pathwise meaningful**, i.e. we can fix the realization $W(\omega)$ and regard

$$x_t = x_0 + \int_0^t b(s, x_s) \mathrm{d}s + W_t(\omega) \tag{1}$$

as an ODE with random coefficients. For $x_0 \in \mathbb{R}^d$, denote by $C(x_0, \omega)$ the random set of solutions to (1).

Theorem (Davie, 2007)

Let W sampled as BM, b measurable and bounded. Then for any $x_0 \in \mathbb{R}^d$ $\mathbb{P}(\omega \in \Omega : \#C(x_0, \omega) = 1) = 1$

namely path-by-path uniqueness holds.

After Davie, several path-by-path uniqueness results have been established by Catellier–Gubinelli (2016), Shaposhnikov (2016) and more recently Harang–Perkowski (2020). Still, we are (partially) in a probabilistic setting.

An abstract analytic formulation of the problem

For given
$$x_0 \in \mathbb{R}^d$$
 and $w \in C([0, T]; \mathbb{R}^d)$, we aim at studying the equation

$$x_t = x_0 + \int_0^t b(s, x_s) ds + w_t \quad \forall t \in [0, T]$$
(2)

with w a given continuous path (possibly very rough) and b possibly distributional (for which the Lebesgue integral in (2) is not clearly defined). Suppose we can find the following "ingredients":

- a) A Banach space $E \subset C([0, T]; \mathbb{R}^d)$ containing $\{x_0 + w : x_0 \in \mathbb{R}^d\}$.
- b) A good definition for $T: E \to C([0, T]; \mathbb{R}^d)$ formally given by

$$(Tx)_t = \int_0^t b(s, x_s) \mathrm{d}s \quad \forall t \in [0, T]$$

in such a way that I - T leaves E invariant (I identity map).

c) All of the above consistent with the classical setting: for continuous

b, *T* defined as usual and *E* includes all classical solutions to (2). Then under the change of variable $\gamma = x_0 + w \in E$, eq. (2) becomes

$$x_t - (Tx)_t = \gamma_t \Leftrightarrow (I - T)x = \gamma \Leftrightarrow x \in (I - T)^{-1}(\gamma).$$

so that wellposedness amounts to $\#(I - T)^{-1}(\gamma) = 1$.

We have reduced ourselves to the study of the set $(I - T)^{-1}(\gamma)$ for a map $T : E \to E$ defined map on a Banach space.

- Leray–Schauder–Tychonoff, Schaefer's theorems: if T is a continuous compact map satisfying suitable conditions, then #(I − T)⁻¹(γ) ≥ 1 for all γ ∈ E.
- **Banach–Caccioppoli**: if T is Lipschitz with constant c < 1, then I T is a bijection with Lipschitz inverse satisfying

$$\|(I-T)^{-1}(\gamma_1)-(I-T)^{-1}(\gamma_2)\|\leq rac{1}{1-c}\|\gamma_1-\gamma_2\|.$$

- Inverse function theorem: if x ∈ (I − T)⁻¹(γ), T is differentiable in U neighb. U of x and D_x(I − T) is an isomorphism of E, then there exists V neighb. of γ s.t. I − T has a differentiable inverse in V.
- Sard's theorem: if E is finite dimensional and T is C¹, then (I − T) is locally invertible around Lebesgue-a.e. γ ∈ E.

Old and new results in this formalism

Consider now the case $b: [0, T] \times \mathbb{R}^d \to \mathbb{R}^d$, $Tx = \int_0^{\cdot} b(s, x_s) \mathrm{d}s$.

- **Cauchy–Lipschitz**: if *b* Lipschitz, then (I T) is invertible on $E = C([0, T]; \mathbb{R}^d)$ with Lipschitz inverse. Sharp: cannot be weakened to any Hölder condition.
- **Peano**: if *b* continuous, *T* is continuous compact on $E = C([0, T]; \mathbb{R}^d)$ and $\#(I T)^{-1}(\gamma) \ge 1$ for every $\gamma \in E$. Sharp: cannot be weakened to *b* measurable bounded.
- If $b \in W^{1,p}$ with p > d (so $W^{1,p} \hookrightarrow C^0$), then $\#(I T)^{-1}(x_0) = 1$ for a.e. $x_0 \in \mathbb{R}^d$ [Caravenna,Crippa 2018]. Sharp: cannot be weakened to $b \in W^{1,p}$ with p < d [Brué, Colombo, de Lellis 2020].
- **Catellier–Gubinelli**: even for distributional *b*, if *w* is a "sufficiently irregular" path, one can define *T* on a suitable space $E = E^w$ and show that (I T) has a Lipschitz inverse on *E*.
- Natural question in view of Sard's theorem: what happens for generic γ? Is (I − T) invertible around a.e. γ ∈ C⁰?

Catellier and Gubinelli's idea revisited

For "sufficiently irregular" w, a good choice of "ingredients" is:

a) $E^w = w + C_t^{\alpha} \simeq C_t^{\alpha}$ for some $\alpha > 1/2$. E^w is made of paths which "look like" w at first order and corresponds to CG's solution Ansatz.

b) For such E^w , T is defined by means of **nonlinear Young integrals.** The "irregularity" of w amounts to requiring that the **averaged field**

$$T^{w}b(t,z) := \int_{0}^{t} b(r,z+w_{r}) dr, \quad T^{w}_{s,t}b(z) := T^{w}b(t,z) - T^{w}b(s,z)$$

is well defined with good space-time regularity. Intuitive picture: wild oscillations of w allows to trade between space and time regularity for $T^w b$, even for distributional b. For b continuous, $x = \theta + w$, then

$$\int_0^t b(r,\theta_r+w_r) \mathrm{d}r \approx \sum_i \int_{t_i}^{t_{i+1}} b(r,\theta_{t_i}+w_r) \mathrm{d}r = \sum_i T_{t_i,t_{i+1}}^w b(\theta_{t_i}).$$

Dependending on $T^w b$ and θ , the Riemann–Stjeltes sums on the r.h.s. might converge even if b distributional \rightsquigarrow nonlinear Young integral.

Nonlinear Young integration

Notation: $A_{s,t}(x) = A(t,x) - A(s,x)$. We say that $A : [0, T] \times \mathbb{R}^d \to \mathbb{R}^d$ is $C_t^{\alpha} C_x^{\beta}$ if $|A_{s,t}(x) - A_{s,t}(y)| \lesssim |t-s|^{\alpha} |x-y|^{\beta}$, $|A_{s,t}(x)| \lesssim |t-s|^{\alpha}$, $|A(t,x) - A(t,y)| \lesssim |x-y|^{\beta}$;

optimal constants $\llbracket A \rrbracket_{\alpha,\beta}$, $\lVert A \rVert_{\alpha,\beta}$; same $A \in C_t^{\alpha} C_x^{n+\beta}$.

Theorem (Catellier, Gubinelli, 2012)

Let $A \in C_t^{\alpha} C_x^{\beta}$, $\theta \in C^{\gamma}([0, T]; \mathbb{R}^d)$ such that $\alpha + \beta \gamma > 1$. Then the following limit of Riemann-Stjeltes sums is well defined:

$$\int_{0}^{t} A(\mathrm{d}s,\theta_{s}) := \lim_{|\Pi| \to 0} \sum_{i=1}^{t} A_{t_{i},t_{i+1}}(\theta_{t_{i}})$$

Moreover $\int_0^{\cdot} A(ds, \theta_s) \in C_t^{\alpha}$ and the map $(A, \theta) \mapsto \int_0^{\cdot} A(ds, \theta_s)$ is continuous in respective topologies.

Idea of proof: Apply the sewing lemma to $\Gamma_{s,t} := A_{s,t}(\theta_s)$. Indeed:

$$\begin{split} |\delta \Gamma_{s,u,t}| &= |A_{s,t}(\theta_s) - A_{s,u}(\theta_s) - A_{u,t}(\theta_u)| = |A_{u,t}(\theta_s) - A_{u,t}(\theta_u)| \\ &\leq \llbracket A \rrbracket_{\alpha,\beta} |t - u|^{\alpha} |\theta_{s,u}|^{\beta} \leq \llbracket A \rrbracket_{\alpha,\beta} \llbracket \theta \rrbracket_{\gamma} |t - s|^{\alpha + \beta \gamma}. \quad \Box \end{split}$$

Perturbed ODE as nonlinear YDE

Therefore if $T^w b \in C^{\alpha}_t C^1_x$ for some $\alpha > 1/2$ and $x = \theta + w$ with $\theta \in C^{\alpha}_t$,

$$(Tx)_{\cdot} = \int_0^{\cdot} T^w b(\mathrm{d}s, \theta_s) =: \int_0^t b(s, x_s) \mathrm{d}s$$

is a well defined element of C_t^{α} and I - T maps E^w into itself. If $x, \gamma \in E^w$ are given by $x = \theta + w, \gamma = \tilde{\gamma} + w$, then $x \in (I - T)^{-1}(\gamma)$ is equivalent to

$$\theta_t = \int_0^t T^w b(\mathrm{d}s, \theta_s) + \tilde{\gamma}_t \tag{YDE}$$

which is a **nonlinear Young differential equation** for the choice $A = T^w b$; $\gamma = x_0 + w$ corresponds to $\tilde{\gamma}_t \equiv x_0 = \theta_0$ initial data.

- Nonlinear YDEs are a generalization of classical YDEs and can be applied in other classes of problems (see later).
- The solution theory we will develop allows to invert *I* − *T* on *E^w*, thus not on a neighb. of *w* in C⁰_t but rather along "special directions"
 → analogy with Malliavin calculus and Cameron–Martin space.

Solution theory for nonlinear YDEs

Theorem

Given $A \in C_t^{\alpha} C_x^1$ and $\gamma \in C_t^{\alpha}$, $\alpha > 1/2$, let $C(A, \gamma)$ denote the set of solutions to the NYDE associated to (A, γ) .

- The set C(A, γ) is non-empty, compact, simply connected in C^{1/2}; the map (A, γ) → C(A, γ) is measurable in suitable topologies
 → if A is random, then C(A, γ) is a random compact set
 → can construct measurable selections for (A, γ) → θ ∈ C(A, γ).
- 2) If $A \in C_t^{\alpha} C_x^2$, then $\#C(A, \gamma) = 1$ and the solution map $(A, \gamma) \mapsto \theta(A, \gamma)$ is Frechét differentiable.
- 3) Restricting to $\gamma = x_0 \in \mathbb{R}^d$, to any $A \in C_t^{\alpha} C_x^2$ we can associated a flow of diffeormorphisms $\Phi^A(s, t, x_0)$; $A \mapsto \Phi^A$ continuous.
- 4) Higher regularity: if $A \in C_t^{\alpha} C_x^{n+1}$, then $\Phi^A(s, t, \cdot)$ belongs to C_x^n .

Proofs sparse in the literature: Catellier–Gubinelli, G.–Gubinelli., Hu–Lê, G.–Harang; everything can be found in the review arXiv:2009.12884.

Solution theory for nonlinear YDEs - II

Global existence of solutions holds under more general growth conditions. We say that $A \in C_t^{\alpha} C_x^{\beta,\lambda}$ if

$$|A_{\mathsf{s},t}(x) - A_{\mathsf{s},t}(y)| \lesssim |t-\mathsf{s}|^lpha |x-y|^eta (1+|x|^\lambda+|y|^\lambda);$$

similar concepts for $C_t^{\alpha} C_x^{n+\beta,\lambda}$, $C_t^{\alpha} C_{loc}^{n+\beta}$. Then:

- Point 1) holds for $A \in C_t^{\alpha} C_x^{\beta,\lambda}$ with $\alpha(1+\beta) > 1$, $\beta + \lambda \leq 1$;
- Point 2) holds for $A \in C_t^{\alpha} C_x^{\beta,\lambda} \cap A \in C_t^{\alpha} C_{loc}^{1+\beta}$, α, β, λ as above.

Explicit expression for the differential of $\gamma \mapsto \theta(A, \gamma)$ in point 2): Consider wlog the differential around $\gamma \equiv 0$, set $\overline{\theta} := \theta(A, 0)$ and let $M \in C_t^{\alpha}([0, T]; \mathbb{R}^{d \times d})$ be the unique solution to

$$M_t = I_d + \int_0^t DA(\mathrm{d}s, \bar{\theta}_s) M_s;$$

let N_t denote its matrix inverse. Then

$$\frac{\mathrm{d}}{\mathrm{d}\varepsilon}\theta(\boldsymbol{A},\varepsilon\gamma)|_{\varepsilon=0}=M_t\gamma_0+\int_0^tM_tN_s\mathrm{d}\gamma_s$$

~> link with Malliavin derivative.

Back to ODEs and solvability for a.e. w

With these results at hand we can now solve the perturbed ODE

$$x_t = x_0 + \int_0^t b(s, x_s) ds + w_t$$
 (3)

for distributional *b* and generic *w*. Analogy with rough paths: enhance the data of the problem from (b, w) to $(b, w, T^w b)$ with $T^w b \in C_t^{\alpha} C_x^2$, so

$$(b,w)\mapsto (b,w,T^wb)\mapsto (\Phi^{T^wb},w)\mapsto x_t=\Phi^{T^wb}(0,t,x_0)+w_t$$

where the first step can be done in a measurable way and all the remaining one are analytically defined continuous mappings.

Theorem (G., Gubinelli, 2020)

Let $b \in L_t^q C_x^{-n}$ for some q > 2 and $n \in \mathbb{N}$; then for almost every $w \in C([0, T]; \mathbb{R}^d)$ it holds $T^w b \in C_t^\alpha C_x^2$, where "almost every" must be understood in the sense of **prevalence**; as a consequence, existence and uniqueness holds for (3) and I - T is invertible "around" w in the sense of the set of special directions given by E^w .

Other applications of nonlinear YDE theory

A) Modulated equations treated by Chouk, Gubinelli (2014-2015):

$$\partial_t \varphi_t = A \varphi_t \dot{w}_t + \mathcal{N}(\varphi_t)$$

where A is the generator of a group $\{e^{tA}\}_{t\in\mathbb{R}}$ acting isometrically on all H^{α} and \mathcal{N} is a nonlinearity. Setting $U_t^w = e^{w_t A}$ and $\psi_t = (U_t^w)^{-1}\varphi_t$, formally ψ satisfies the mild formulation

$$\psi_t = \psi_0 + \int_0^t (U_s^w)^{-1} \mathcal{N}(U_s^w \psi_s) \mathrm{d}s =: \psi_0 + \int_0^t \mathcal{A}(\mathrm{d}s, \psi_s)$$

which can be recast as a nonlinear YDE driven by

$$A_{s,t}(\chi) := \int_s^t (U_r^w)^{-1} \mathcal{N}(U_r^w \chi) \mathrm{d}r.$$

B) **McKean–Vlasov** nonlinear YDEs treated by Harang, Mayorcas (2020):

$$X_t = \xi + \int_0^1 K * \mathcal{L}(X_s)(X_s + Z_s) \mathrm{d}s + B_t$$

for Z deterministic irregular path; setting $A = T^Z K$ it is of the form $X_t = \xi + \int_0^t A_{ds} * \mathcal{L}(X_s)(X_s) + B_t.$

Can we regularise SDEs driven by multiplicative fBm?

Consider now an SDE driven by B^H fBm of parameter H > 1/2 of the form $dx_t = b_1(t, x_t)dt + b_2(t, x_t)dB_t^H$;

take for simplicity of exposition $b_1 \equiv 0$, $b_2(t,x) = b(x)$ autonomous.

Since H > 1/2, for regular *b* the equation is pathwise well-posed in the Young sense; if $b \in C_x^{\alpha}$ with $\alpha < 1$, explicit counterexamples to uniqueness are known; if $\alpha \leq 1/H - 1$, the Young interpretation breaks down.

Question: can noise cure these pathologies? Leads to consider

$$x_{t} = x_{0} + \int_{0}^{t} b(x_{s}) \mathrm{d}B_{s}^{H} + w_{t}$$
(4)

New difficulties:

- If w is very rough, we expect a strong regularising effect, but at the same time (4) is not pathwise meaningful anymore even for smooth b!
- In analogy with above, we expect a central role to be played by

$$\Gamma^w b(t,z) = \int_0^t b(z+w_r) \mathrm{d}B_r^H$$

Wiener integral for fBm

Given $h \in C([0, T]; \mathbb{R}^d)$ and $\kappa \in (0, 1)$, define $\|h\|_{-\kappa} := \|\int_0^{\cdot} h_s ds\|_{1-\kappa}$.

Theorem (Hairer, Li, AP 2020)

Let B^H fBm with H > 1/2, $\kappa \in (0, H - 1/2)$, h deterministic, then

$$\Big|\int_{s}^{t}h_{r}\,\mathrm{d}B_{r}^{H}\Big\|_{L^{p}_{\Omega}}\lesssim_{p,H,T}\|h\|_{-\kappa}|t-s|^{H-\kappa}\quad\forall\,[s,t]\subset[0,T].$$

By a density argument, the Wiener integral $\int_{s}^{t} h_{r} dB_{r}^{H}$ is then well defined for all $h \in C^{-\kappa}$; moreover by Garsia-Rodemich-Rumsay

$$\mathbb{E}\left\|\int_{0}^{\cdot}h_{r}\,\mathrm{d}B_{r}^{H}\right\|_{H-\kappa-\varepsilon}^{p}\lesssim_{p,H,T,\varepsilon}\|h\|_{-\kappa}^{p}$$

where by assumption we can take $H - \kappa - \varepsilon > 1/2$.

Actually already known: [Jolis, JMAA 2007] for $h \in W^{1/2-H,2}$. **Intuitive idea**: dB^{H} "=" $I^{H-1/2}dB$ where *B* standard Bm and I^{α} fractional integral, so $\langle h, dB^{H} \rangle$ "=" $\langle I^{H-1/2}h, dB \rangle$, it suffices $I^{H-1/2}h \in L^2$. $h \in C^{-\kappa} \Rightarrow I^{H-1/2}h \in C^{H-1/2-\kappa-}$, so it's enough to require $\kappa < H - 1/2$.

Construction of multiplicative averaged field

We can now construct
$$\Gamma^w b$$
 by relying on the regularity of $T^w b!$
If $T^w b \in C^{\alpha}_t C^1_x$ with $\alpha + H > 3/2$, taking $\kappa = 1 - \alpha$, $H - \kappa > 1/2$, then
 $\|\Gamma^w_{s,t}b(x) - \Gamma^w_{s,t}b(y)\|_{L^p_{\Omega}} = \left\|\int_s^t [b(x+w_r) - b(y+w_r)] dB^H_r\right\|_{L^p_{\Omega}}$
 $\lesssim_P ||t-s|^{H-\kappa} \left\|\int_0^{\cdot} b(x+w_r) dr - \int_0^{\cdot} b(y+w_r) dr\right\|_{C^{\alpha}_{\Omega}}$
 $\lesssim_P \|T^w b\|_{C^{\alpha}_t C^1_x} ||t-s|^{1/2+}||x-y|$

and now applying a (suitably modified) version of GRR lemma we obtain

Proposition

Suppose $T^w b \in C_t^{\alpha} C_x^{n+\beta}$ for $\alpha > 3/2 - H$ and $\beta \in (0, 1)$. Then for any $\alpha' \in (1/2, \alpha + H - 1)$, $\beta' < \beta$ and $\lambda > 0$ it holds $\Gamma^w b \in C_t^{\alpha'} C_x^{n+\beta',\lambda} \quad \mathbb{P}-a.s.$

The results from [CG16], [GG20], [HP20] give plenty examples of deterministic w for which $T^w b$ has the desired regularity.

Solution theory for perturbed SDEs

Let's go back to the study of $x_t = x_0 + \int_0^t b(x_s) dB_s^H + w_t$ (5)

Definition

We say that $x : \Omega \to C([0, T]; \mathbb{R}^d)$ is a *pathwise solution* of (5) if there exist α, β, λ with $\alpha > 1/2$, $\alpha(1 + \beta) > 1$, $\beta + \lambda \leq 1$ such that

a) $\Gamma^{w}b(\omega)$ is a well defined element of $C_{t}^{\alpha}C_{x}^{\beta,\lambda}$ for \mathbb{P} -a.e. ω ;

b)
$$x(\omega) \in E^w$$
 for \mathbb{P} -a.e. ω ;

c)
$$\theta(\omega) := x(\omega) - w \in C(\Gamma^w b(\omega), x_0)$$
 for \mathbb{P} -a.e. ω .

Definition

We say that *path-by-path wellposedness* holds for (5) if a) holds and $\mathbb{P}(\omega \in \Omega : \#C(\Gamma^w b(\omega), x_0) = 1 \text{ for all } x_0 \in \mathbb{R}^d) = 1.$

Theorem (G., Harang)

Suppose there exist α, β, λ with $\alpha > 1/2$, $\alpha(1 + \beta) > 1$, $\beta + \lambda \leq 1$ such that $\Gamma^w b(\omega) \in C_t^{\alpha} C_x^{1+\beta,\lambda}$. Then path-by-path wellposedness holds.

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Solution theory for perturbed SDEs - II

Theorem

Let
$$b \in C_x^s$$
, $s \in \mathbb{R}$, $w \in C_t^0$ be such that $T^w b \in C_t^{1/2} C_x^{s+\nu}$ for $s + \nu(2H-1) > 2;$

then path-by-path wellposedness holds and eq. (5) admits a random flow of diffeomorphisms. If $s + \nu(2H - 1) > n + 1$, the flow is spatially C^n .

Theorem (G., Harang)

Let $b \in C_x^s$ be compactly supported, w sampled as an fBm of parameter $\delta \in (0, 1)$, w independent of B^H . If

$$s > 2 - \frac{1}{\delta} \left(H - \frac{1}{2} \right)$$

then uniqueness holds for (5), which admits a random flow of diffeom. Similarly higher regularity for $s > n + 1 - (H - 1/2)/\delta$.

In particular: since H > 1/2, for any $s \in \mathbb{R}$ we can find $\delta > 0$ small enough such that the conditions are satisfied!

Things I couldn't cover

- A more detailed explanation of the notion of prevalence: introduced by Hunt, Sauer, York (1992), notion of "Lebesgue full sets" for infinite dim. spaces based on characterization via Fubini theorem.
- ② The nonlinear Young theory allows to provide a solution theory for

 $\partial_t u + b \cdot \nabla u + cu + \dot{w} \cdot \nabla u = 0$

whenever $T^w b$, $T^w c \in C_t^{\alpha} C_x^2$ with $\alpha > 1/2$; this includes transport and continuity equations perturbed by w. See [GG20], [G20].

The results by Gubinelli, Lejay, Tindel (PA 2020) can be generalised to nonlinear Young parabolic equations of the form

$$\mathrm{d}x_t = -Ax_t\mathrm{d}t + B(\mathrm{d}t, x_t)$$

with $B \in C_t^{\alpha} C_{V,W}^2$ for suitable V, W, see [G20].

Work in progress with Harang, Mayorcas: study DDSDEs of the form

$$X_t = \xi + \int_0^t B(s, X_s, \mathcal{L}(X_s)) \mathrm{d}s + W_t^H$$

with distributional B, generalising the results from [CG16].

Essential bibliography

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