

Rough path variational principles for fluid equations.

Joint work with

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1. Variational principles
2. Euler - Arnold
3. Physically relevant noisy decomposition of Lagrangian trajectories
4. Rough path framework
5. Main results

Euler eq.

$$\begin{cases} \partial_t u + u \cdot \nabla u = -\nabla p \\ \operatorname{div} u = 0 \end{cases}$$

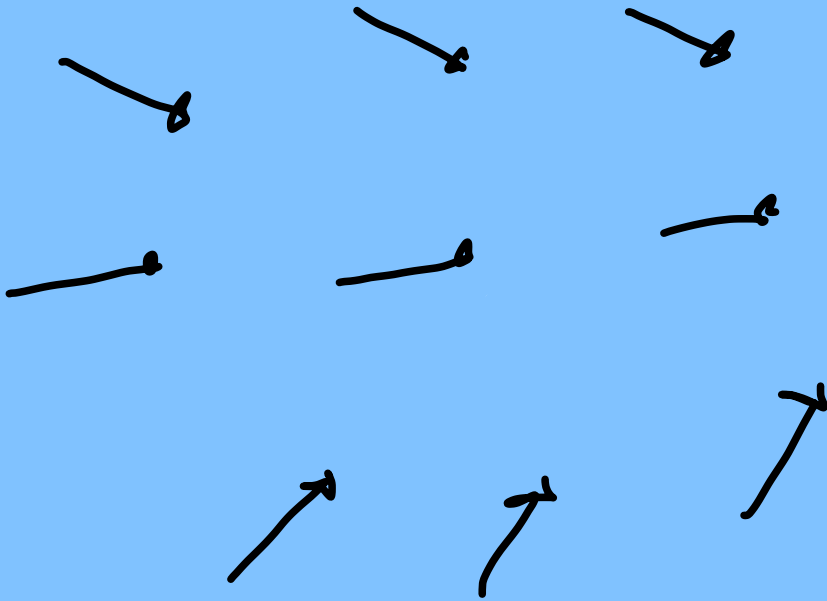
Solution is a pair

u = vector field

p = pressure

In coordinates

$$\partial_t u^i + u^j \frac{\partial u^i}{\partial x^j} = - \frac{\partial p}{\partial x^i} \quad \forall i$$



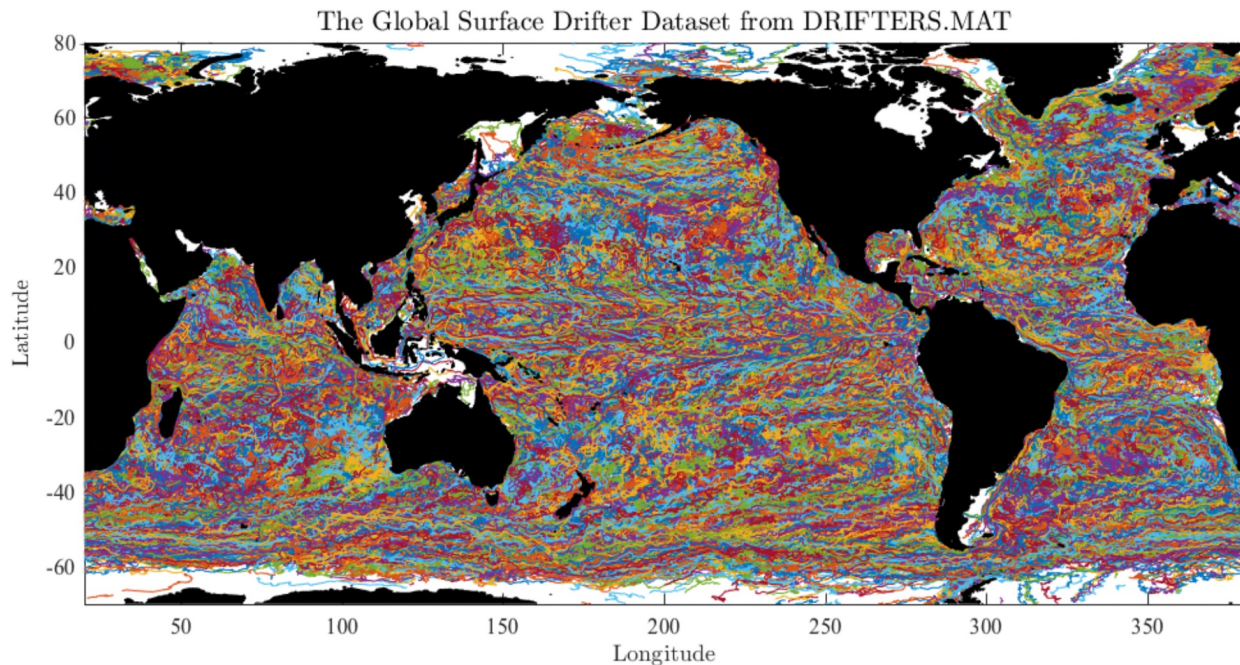
Lagrangian trajectories

$$\dot{\eta}_t = u_t(\eta_t)$$

Solution Properties of a 3D Stochastic Euler Fluid Equation

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$$\begin{aligned}\dot{\eta}_t &= \text{large scale} + \text{small scale} \\ &\approx u_t(\eta_t) + \text{random term} \\ &= u_t(\eta_t) + \sum_k(\eta_t) \dot{W}_t^k\end{aligned}$$

- parametrize uncertainty
- estimate β_k from data
- improve predictive power
- preserve geometric structure of Euler eq.

? What is the corresponding PDE ?

1. Variational principles and geodesics

Curve

$$[0, 1] \xrightarrow{q} M$$

want to minimize action functional

$$S(q, \dot{q}) = \int_0^1 L(q_t, \dot{q}_t) dt$$

for a given Lagrangian

$$L: TM \rightarrow \mathbb{R}$$

q critical point \Leftrightarrow

$$\frac{\partial L}{\partial q^i}(q_t, \dot{q}_t) - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}^i}(q_t, \dot{q}_t) = 0$$

Euler-Lagrange eq.

Proof

1. Variations

$$q^\varepsilon = q + \varepsilon \delta q$$

$$\delta q_0 = \delta q_1 = 0$$

2. Critical point

$$\left. \frac{\partial}{\partial \varepsilon} \right|_{\varepsilon=0} S(q^\varepsilon, \dot{q}^\varepsilon) = 0$$

3. integration by parts



Example: N point particles

$$(q^1, \dots, q^N) \in (\mathbb{R}^d)^N$$

w/ masses $(m_1, \dots, m_N) \in \mathbb{R}^N$

Potential $V: (\mathbb{R}^d)^N \rightarrow \mathbb{R}$

Define the Lagrangian

$$L(q, v) := \sum_n \frac{m_n}{2} |v^n|^2 - V(q)$$

Euler-Lagrange \Leftrightarrow Newton's law

$$m_n \ddot{q}_\epsilon^n = - \frac{\partial V}{\partial q^n}(q_\epsilon)$$

Example: M Riemannian w/metric $\langle \cdot, \cdot \rangle$.

Geodesic equations;

$$L(q, v) := \langle v, v \rangle_q$$

Euler-Lagrange



$$\ddot{q}_t^i + \Gamma_{jk}^i \dot{q}_t^j \dot{q}_t^k = 0$$

Geodesic
equation

where Γ_{jk}^i are the
Christoffel symbols

Example: Lie group, $M = G$

Right multiplication $R_q: p \mapsto pq$

If L is right invariant, i.e.

$$L \circ TR_q = L$$

Def $l(u) = L(e, u)$

$$u \in \mathfrak{g} = T_e G$$

reduced
Lagrangian

Euler-Poincaré reduction

TFAE

• q satisfies Euler-Lagrange

- $u = \dot{q} \circ \bar{q}^{-1} = R_{q_a}^{-1} \dot{q}$ and $\lambda = \frac{\partial l}{\partial u}$
critical points of

$$S(q, u, \lambda) = \int_0^1 l(u_t) + \langle \lambda_t, \dot{q}_t \circ \bar{q}_t^{-1} - u_t \rangle dt$$

- u is a critical point of

$$S(u) = \int_0^1 l(u_t) dt$$

when variations are restricted to be on the form

$$\delta u_t = \dot{w}_t + [u_t, w_t]$$

- u satisfies Euler-Poincaré eq;

$$\frac{d}{dt} \frac{\partial l}{\partial u} + \text{ad}_u^* \frac{\partial l}{\partial u} = 0$$

$$\left(\text{ad}_u \zeta = -[\zeta, u] \right)$$

2. Euler - Arnold

G = volume preserving diffeomorphisms
on some manifold M

Tangent space of G :

$$c : (-\varepsilon, \varepsilon) \rightarrow G \quad c_0 = f \in G$$

$$c \cdot (p) : (-\varepsilon, \varepsilon) \rightarrow M \quad c_0(p) = f(p) \in M$$

$$\Rightarrow T_f G \subset \{X : M \rightarrow TM \mid X_p \in T_{f(p)} M\}$$

Special case:

$$f = \text{id} = e \text{ in } G$$

$$\mathfrak{g} = T_e G = \text{div-free vector fields}$$

G is a

Lie - group

w/ composition as group operation

Translations

$$R_q p = p \circ q$$

C^∞

$$L_q p = q \circ p$$

Same regularity
as q .

C^∞ only if

G is Frechet

(Weak) Riemmanian metric

$$\langle X, Y \rangle_g = \int \langle X(z), Y(z) \rangle_z \mu(z)$$

yields right invariant metric on TG .

Arnold Formally

$$\eta: [0, 1] \rightarrow G$$

is a geodesic iff

$$u = \dot{\eta} \circ \eta^{-1} \in \mathfrak{g} = T_e G$$

solves Euler equation.

Ebin-Marsden

Rigorously,

letting

$G = \text{vol-pres. } W^{k,2}$ -Sobolev diffeos

$$k > \frac{d}{2}$$

Arnold was right.

+++

Gives equivalent formulation \checkmark via
critical points of Euler's eq.

$$S(u, \eta, \lambda) = \int_0^1 \langle u_t, u_t \rangle_g + \langle \lambda_t, u_t - \dot{\eta}_t \circ \eta_t^{-1} \rangle dt$$

Taking variations in (u, η, λ)

gives that critical points

of S satisfies

$$\lambda_t = u_t^b = \langle u_t, \cdot \rangle \in \dot{\Lambda}(\mathcal{H})$$

$$u_t = \dot{\eta}_t^0 \dot{\eta}_t^1 \Rightarrow \ddot{\eta}_t = u_t(\eta_t)$$

and

$$\partial_t u_t^b + \mathcal{L}_{u_t} u_t^b = -dp_t$$

In local coordinates

$$\partial_t u_t^i + u_t^j \frac{\partial u_t^i}{\partial x^j} + u_t^j \frac{\partial u_t^j}{\partial x^i} = - \frac{\partial p_t}{\partial x^i}$$

$$\frac{1}{2} \frac{\partial}{\partial x^i} (u_t^j)^2$$

Convenient to understand
 u as a 1-form,

$$u^b = \langle u, \cdot \rangle$$

- conserved quantities
(Kelvin-Noether circulation thm)
- Lie derivatives

More general Lagrangians
and underlying Banach
manifolds yield a
general class of
fluid equations, e.g.

- Burgers
- KdV
- Camassa-Holm
- ...

General set up

$$S(u, \eta, \lambda) = \int_0^1 \ell(u_t, \eta_t^* a_0) + \langle \lambda_t, u_t - \eta_t \circ \eta_t^{-1} \rangle dt$$

$a_t = \eta_t^* a_0$ - advected quantities
(e.g. heat, density, ...)

3. Use Lagrange multiplier to force decomposition

Wanted

$$\dot{\eta}_t = u_t(\eta_t) + \sum_k \lambda_k(\eta_t) \dot{W}_t^k$$

Use Lagrange multiplier

$$S(u, \eta, \lambda) = \int_0^1 \langle u_t, u_t \rangle_{\mathcal{Q}} + \langle \lambda_t, \dot{\eta}_t \circ \eta_t^{-1} - u_t - \sum_k \dot{W}_t^k \rangle$$

Formally

$$\partial_t u_t^b + \mathcal{L}_{u_t}^b u_t + \mathcal{L}_{\sum_k} u_t^b \dot{W}_t^k = - dp_t$$

4. Rough Paths

W irregular, e.g. sample path
of Brownian motion.

How to understand

$$\dot{\eta}_t = \mu_t(\eta_t) + \Sigma_t(\eta_t) \dot{W}_t \quad ?$$

H_0^1 - calculus ;

- discount. as a function of sample paths
- restricts to Markov noise
- already studied by Holm

Rough paths

Consider $u \equiv 0$ for simplicity

$$\eta_t - \eta_s = \int_s^t \beta_u(\eta_r) dW_r^k$$

$$\begin{aligned}
&= \beta_u(\eta_s) (W_t^k - W_s^k) \\
&+ \nabla \beta_u(\eta_s) \beta_\ell(\eta_s) \int_s^t (W_r^\ell - W_s^\ell) dW_r^k \\
&+ o(|t-s|^{1+\varepsilon})
\end{aligned}$$

The pair

$$(W, \mathbb{W}) = (W, \int W dW)$$

is called a rough path.

Typically need probability
to give meaning to

$\int W dW$ (e.g. ~~the~~ ~~or~~ Stratonovich)

- Nice continuity properties

$$(W, \mathbb{W}) \mapsto \eta(W, \mathbb{W})$$

- Can make sense of $\int W dW$ for more general sources of noise

5. Main results

Hamilton Pontryagin

Critical points of

$$S(\eta, u, \lambda) = \int_0^1 \mathcal{L}(u_t, \eta_t^* a_0) dt$$

$$+ \int_0^1 \langle \lambda_t, d\eta_t \circ \eta_t' - u_t dt - \sum_k \lambda_t^k dW_t^k \rangle$$

are exactly solutions of

$$d\eta_t = u_t \circ \eta_t dt + \sum_k \lambda_t^k \circ \eta_t \circ dW_t^k$$

$$d\lambda_t + \mathcal{L}_{u_t} \lambda_t dt + \mathcal{L}_{\sum_k \lambda_t^k} dW_t^k = \lambda_t \circ a_t dt$$

$$\lambda = \frac{\partial \mathcal{L}}{\partial u}$$

Clebsch

$$S(u, a, \lambda) = \int_0^1 \mathcal{L}(u_t, a_t) dt + \langle \lambda_t, da_t + \mathcal{L}_{u_t} a_t dt + \mathcal{L}_{z_k} a_t^p dW_t^k \rangle$$

Euler - Poincaré

$$S(u, a) = \int_0^1 \mathcal{L}(u_t, a_t) dt$$

variations on the form

$$\delta u dt = \partial_t \delta w dt - \text{ad}_{u_t} \delta w dt - \text{ad}_{z_k} \delta w dW_t^k$$

$$\delta a = -\mathcal{L}_{\delta w} a$$

Elements of the proof

- setting up the appropriate rough path spaces

- Rough Lie chain rule

$$d\hat{z}_t = \beta_t dt + \sigma_\kappa \circ dW_t^\kappa$$

tensor eq. ,

$$d\eta_t = u_t \circ \eta_t dt + \mathbb{z}_\kappa \circ \eta_t dW_t^\kappa$$






Then

$$d\eta_t^* \hat{z}_t = \eta_t^* (\beta_t + \mathbb{L}_{u_t} \hat{z}_t) dt$$

$$+ \eta_t^* (\sigma_\kappa + \mathbb{L}_{\mathbb{z}_\kappa} \hat{z}_t) \circ dW_t^\kappa$$

Next

- Local well-posedness of rough Euler;
 - BKM blow-up criterion
 - well-posedness for $d=2$ w/ smooth initial data
- general theory for rough PDE's
- regularization by noise?

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THANK YOU!